Abstract

Session types are a type-based approach to the verification of message-passing programs. They have been much studied as type systems for the $\pi$-calculus and for languages such as Java. A session type specifies what and when should be exchanged through a channel. Central to session-typed languages are constructs in types and processes that specify sequencing in protocols.

Here we study minimal session types, session types without sequencing. This is arguably the simplest form of session types. By relying on a core process calculus with sessions and higher-order concurrency (abstraction-passing), we prove that every process typable with usual (non minimal) session types can be compiled down into a process typed with minimal session types. This means that having sequencing constructs in both processes and session types is redundant; only sequentiality in processes is indispensable, as it can precisely codify sequentiality in types.

Our developments draw inspiration from work by Parrow on behavior-preserving decompositions of untyped processes. By casting Parrow’s results in the realm of typed processes, our results reveal a conceptually simple formulation of session types and a principled avenue to the integration of session types into languages without sequencing in types.

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Keywords and phrases Session types, process calculi, $\pi$-calculus.

1 Introduction

Session types are a type-based approach to the verification of message-passing programs. A session type specifies what and when should be exchanged through a channel; this makes them a useful tool to enforce safety and liveness properties related to communication correctness. Session types have had a significant impact on the foundations of programming languages [15], but also on their practice [1]. In particular, the interplay of session types and object-oriented
languages has received much attention (cf. [8, 7, 14, 11, 2, 18, 25]). In this work, our goal is to understand to what extent session types can admit simpler, more fundamental formulations. This foundational question has concrete practical ramifications, as we discuss next.

In session-typed languages, sequencing constructs in types and processes specify the intended structure of message-passing protocols. In the session type $S = ?(\text{Int}); ?(\text{Int}); !(\text{Bool}); \text{end}$, sequencing (denoted ‘;’) allows us to specify a protocol for a channel that first receives (?) two integers, then sends (!) a Boolean, and finally ends. As such, $S$ could type a service that checks for integer equality. Sequencing in types goes hand-in-hand with sequencing in processes, which is specified using prefix constructs (denoted ‘.’). The $\pi$-calculus process $P = s!(x_1).s?(x_2).s!(b).0$ is an implementation of the equality service: it first expects two values on name $s$, then outputs a Boolean on $s$, and finally stops. Thus, name $s$ in $P$ conforms to type $S$. Session types can also specify sequencing within labeled choices and recursion; these typed constructs are also in close match with their respective process expressions.

Originally developed on top of the $\pi$-calculus for the analysis of message-passing protocols between exactly two parties [12], session types have been extended in many directions. We find, for instance, multiparty session types [13] and extensions with dependent types, assertions, exceptions, and time (cf. [6, 15] for surveys). All these extensions seek to address natural research questions on the expressivity and applicability of session types theories.

Here we address a different, if opposite, question: is there a minimal formulation of session types? This is an appealing question from a theoretical perspective, but seems particularly relevant to the practice of session types: identifying the “core” of session types could enable their integration in languages whose type systems do not have advanced constructs present in session types (such as sequencing). For instance, the Go programming language offers primitive support for message-passing concurrency; it comes with a static verification mechanism which can only enforce that messages exchanged along channels correspond with their declared payload types—it cannot ensure essential correctness properties associated to the structure of protocols. This observation has motivated the development of advanced static verification tools based on session types for Go programs [22, 21].

This paper identifies an elementary formulation of session types and studies its properties. We call them minimal session types: these are session types without sequencing. That is, in session types such as ‘!($U$); $S$’ and ‘?($U$); $S$’, we decree that $S$ can only correspond to $\text{end}$, the type of the terminated protocol.

Adopting this elementary formulation entails dispensing with sequencing, which is one of the most distinctive features of session types. While this may appear as a far too drastic restriction, it turns out that it is not: our main result is that for every process $P$ that is well-typed under standard (non minimal) session types, there is a process decomposition $D(P)$ that is well-typed using minimal session types. Intuitively, $D(P)$ codifies the sequencing information given by the session types (protocols) of $P$ using additional synchronizations. This shows that having sequencing in both types and processes is redundant; only sequencing at the level of processes is truly fundamental. To define $D(P)$ we draw inspiration from a known result by Parrow [24], who proved that untyped $\pi$-calculus processes can be decomposed as a collection of trios processes, i.e., processes with at most three nested prefixes [24].

The question of how to relate session types with other type systems has attracted interest in the past. Session types have been encoded into generic types [10] and linear types [5, 3, 4]. As such, these prior studies concern the relative expressiveness of session types: where the expressivity of session types stands with respect to that of some other type system. In sharp contrast, we study the absolute expressiveness of session types: how session types can be explained in terms of themselves. To our knowledge, this is the first study of its kind.
The process language that we consider for decomposition into minimal session types is HO, the core process calculus for session-based concurrency studied by Kouzapas et al. [19, 20]. HO is a very small language: it supports abstraction-passing only and lacks name-passing and recursion; still, it is also very expressive, because both features can be expressed in it in a fully abstract way. As such, HO is an excellent candidate for a decomposition. Being a higher-order language, HO is very different from the (untyped, first-order) π-calculus considered by Parrow in [24]. Also, the session types of HO severely constrain the range and kind of conceivable decompositions. Therefore, our results are not an expected consequence of Parrow’s: essential aspects of our decomposition into processes typable with minimal session types are only possible in a higher-order setting, not considered in [24].

Summing up, in this paper we make the following contributions:
1. We identify the class of minimal session types as a simple fragment of standard session types that retains its absolute expressiveness.
2. We show how to decompose processes typable with standard session types into processes typable with minimal session types. We prove that this decomposition satisfies a typability result for a rich typed language that includes labeled choices and recursive types.
3. We develop optimizations of our decomposition that bear witness to its robustness.

The rest of the paper is organized as follows. §2 summarizes the syntax, semantics, and session type system for HO, the core process calculus for session-based concurrency. §3 presents the decomposition of well-typed HO processes into minimal session types. The decomposition is presented incrementally, starting with a core fragment that is later extended with further features. §4 presents optimizations of the decomposition. §5 elaborates further on related works and §6 concludes. The appendix contains omitted definitions and proofs.

2 The Source Language

We recall the syntax, semantics, and type system for HO, the higher-order process calculus for session-based concurrency studied by Kouzapas et al. [19, 20]. HO is arguably the simplest language for session types: it supports passing of abstractions (functions from names to processes) but does not support name-passing nor process recursion. Still, HO is very expressive: it can encode name-passing, recursion, and polyadic communication via type-preserving encodings that are fully-abstract with respect to contextual equivalence [19].

2.1 Syntax and Semantics

The syntax of names, variables, values, and HO processes is defined as follows:

\[
\begin{align*}
n, m & ::= a, b | s, \bar{s} \\
u, w & ::= n | x, y, z \\
V, W & ::= x, y, z | \lambda x. P \\
P,Q & ::= u!\langle V \rangle.P | u?\langle x \rangle.P | u \ll t.P | u \ll \{ l_i : P_i \}_{i \in I} | V u | P \parallel Q | (\nu n) P | 0
\end{align*}
\]

We use \(a, b, c, \ldots\) to range over shared names, and \(s, \bar{s}, \ldots\) to range over session names. Shared names are used for unrestricted, non-deterministic interactions; session names are used for linear, deterministic interactions. We write \(n, m\) to denote session or shared names, and assume that the sets of session and shared names are disjoint. The dual of \(n\) is denoted \(\bar{n}\); we define \(\bar{\bar{s}} = s\) and \(\bar{a} = a\), i.e., duality is only relevant for session names. Variables are
denoted with \( x, y, z, \ldots \). An abstraction \( \lambda x. P \) is a process \( P \) with parameter \( x \). Values \( V, W, \ldots \) include variables and abstractions, but not names. A tuple of variables \( (x_1, \ldots, x_k) \) is denoted \( \vec{x} \) (and similarly for names and values). We use \( \epsilon \) to denote the empty tuple.

Processes \( P, Q, \ldots \) include usual \( \pi \)-calculus output and input prefixes, denoted \( u!(V).P \) and \( u?((x).P) \), respectively. Processes \( u \ll P \) and \( u \triangleright \{l_i : P_i\}_{i \in I} \) are selecting and branching constructs, respectively, commonly used in session calculi to express deterministic choices [12]. Process \( V u \) is the application which substitutes name \( u \) on abstraction \( V \). Constructs for inaction \( 0 \), parallel composition \( P_1 \parallel P_2 \), and name restriction \( (\nu n)P \) are standard. HO lacks name-passing and recursion, but they are expressible in the language (see Exam. 2.1 below).

We sometimes omit trailing \( 0 \)'s, so we may write, e.g., \( u!(V) \) instead of \( u!(V).0 \). Also, we write \( u!(.)P \) and \( u?().P \) whenever the exchanged value is not relevant (cf. Rem. 3.7).

Session name restriction \( (\nu s)P \) simultaneously binds session names \( s \) and \( \vec{s} \) in \( P \). Functions \( \text{fv}(P) \), \( \text{fn}(P) \), and \( \text{fs}(P) \) denote, respectively, the sets of free variables, names, and session names in \( P \), and are defined as expected. If \( \text{fv}(P) = \emptyset \), we call \( P \) closed. We write \( P[u/y] \) (resp., \( P[V/y] \)) for the capture-avoiding substitution of name \( u \) (resp., value \( V \)) for \( y \) in process \( P \). We identify processes up to consistent renaming of bound names, writing \( \equiv_{s} \) for this congruence. We shall rely on Barendregt’s variable convention, which ensures that free and bound names are different in every mathematical context.

The operational semantics of HO is defined in terms of a reduction relation, denoted \( \rightarrow \). Reduction is closed under structural congruence, denoted \( \equiv \), which is defined as the smallest congruence on processes such that:

\[
P \mid 0 \equiv P \quad P_1 \parallel P_2 \equiv P_2 \parallel P_1 \quad P_1 \parallel (P_2 \mid P_3) \equiv (P_1 \mid P_2) \parallel P_3 \quad (\nu n)0 \equiv 0
\]

\[
P \parallel (\nu n)Q \equiv (\nu n)(P \mid Q) \quad (n \notin \text{fn}(P))
\]

We assume the expected extension of \( \equiv \) to values \( V \). The reduction relation expresses the behavior of processes; it is defined as follows:

\[
(\lambda x. P) u \rightarrow P[u/x] \quad \text{[App]}
\]

\[
n!(V).P \mid \pi?((x).Q) \rightarrow P \mid Q[V/x] \quad \text{[Pass]}
\]

\[
n \ll l_j.Q \mid \pi \triangleright \{l_i : P_i\}_{i \in I} \rightarrow Q \mid P_j \quad (j \in I) \quad \text{[Sel]}
\]

\[
P \rightarrow P' \Rightarrow (\nu n)P \rightarrow (\nu n)P' \quad \text{[Res]}
\]

\[
P \rightarrow P' \Rightarrow P \parallel Q \rightarrow P' \mid Q \quad \text{[Par]}
\]

\[
P \equiv Q \rightarrow Q' \equiv P' \Rightarrow P \rightarrow P' \quad \text{[Cong]}
\]

Rule [App] defines name application. Rule [Pass] defines a shared or session interaction, depending on the nature of \( n \). Rule [Sel] is the standard rule for labelled choice/selection. Other rules are standard \( \pi \)-calculus rules. We write \( \rightarrow^k \) for a \( k \)-step reduction, and \( \rightarrow^* \) for the reflexive, transitive closure of \( \rightarrow \).

We illustrate HO processes and their semantics by means of an example.

**Example 2.1 (Encoding Name-Passing).** HO lacks name-passing, and so the reduction

\[
n!(m).P \mid \pi?(x).Q \rightarrow P \mid Q[m/x]
\]

is not supported by the language. Still, as explained in [19], name-passing can be encoded in a fully-abstract way using abstraction-passing, by “packing” the name \( m \) in an abstraction. Let \( [\ ] \) be the encoding defined as

\[
[n!(m).P] = n!(\lambda z. \ z?(x).(x \ m)).[P]
\]

\[
[n?((x).Q)] = n?((y).\ (\nu s)(y s \mid \pi!(\lambda x. [Q])))
\]
and as an homomorphism for the other constructs. Reduction (1) can be mimicked as

\[ n!(m).P | π?(x).Q \] = \[ n!(λz. z?(x). (x m)). [P] | n!(y). (\nu s)(y s | π!(λx. [Q])) \]
\[ \rightarrow [P] | (\nu s)(λz. z?(x). (x m) s | π!(λx. [Q])) \]
\[ \rightarrow [P] | (\nu s)(s?(x). (x m) | π!(λx. [Q])) \]
\[ \rightarrow [P] | (λx. [Q]) m \]
\[ \rightarrow [P] | [Q] \{m/x\} \]

\[ < \]

> Remark 2.2 (Polyadic Communication). HO as presented above allows only for monadic communication, i.e., the exchange of tuples of values with length 1. We will find it convenient to use HO with polyadic communication, i.e., the exchange of tuples of values \( \hat{V} \), with length \( k \geq 1 \). In HO, polyadicty appears in session synchronizations and applications, but not in synchronizations on shared names. This entails having the following reduction rules:

\[ (\lambda x \tilde{P}). \tilde{u} \rightarrow P\{\tilde{y}/\tilde{x}\} \]
\[ s!\hat{V}.P | \exists?\langle \tilde{x} \rangle .Q \rightarrow P | Q\{\tilde{V}/\tilde{x}\} \]

where the simultaneous substitutions \( P\{\tilde{y}/\tilde{x}\} \) and \( P\{\tilde{V}/\tilde{x}\} \) are as expected. This polyadic HO can be readily encoded into (monadic) HO [20]; for this reason, by a slight abuse of notation we will often write HO when we actually mean “polyadic HO”.

2.2 Session Types for HO

We give essential definitions and properties for the session type system for HO, following [20].

> Definition 2.3 (Session Types for HO [20]). Let us write \( \odot \) to denote the process type. The syntax of types for HO is defined as follows:

\[
\begin{align*}
U &::= C \rightarrow \odot \mid C \rightarrow \odot \\
C &::= S \mid \langle U \rangle \\
S &::= \text{end} \mid !\langle U \rangle ; S \mid ?\langle U \rangle ; S \mid \odot \{i_s : S_i\}_{i \in I} \mid \&\{i_s : S_i\}_{i \in I} \mid \mu t . S \mid t
\end{align*}
\]

Value types \( U \) include \( C \rightarrow \odot \) and \( C \rightarrow \odot \), which denote shared and linear higher-order types, respectively. Shared channel types are denoted \( \langle S \rangle \) and \( \langle U \rangle \). Session types, denoted by \( S \), follow the standard binary session type syntax [12]. Type \( \text{end} \) is the termination type. The output type \( !\langle U \rangle ; S \) first sends a value of type \( U \) and then follows the type described by \( S \). Dually, \( ?\langle U \rangle ; S \) denotes an input type. The branching type \&\{\( i_s : S_i \)\}_{i \in I} and the selection type \( \odot \{i_s : S_i\}_{i \in I} \) are used to type the branching and selection constructs that define the labeled choice. We assume the recursive type \( \mu t . S \) is guarded, i.e., type \( \mu t . t \) is not allowed.

In session types theories duality is a key notion: implementations derived from dual session types will respect their protocols at run-time, avoiding communication errors. Intuitively, duality is obtained by exchanging \( ! \) by \( ? \) (and vice versa) and \( \odot \) by \& (and vice versa), including the fixed point construction. We write \( S \) dual \( T \) if session types \( S \) and \( T \) are dual according to this intuition; the formal definition is coinductive, and given in [20].

We consider shared, linear, and session environments, denoted \( \Gamma, \Lambda, \) and \( \Delta, \) resp.:

\[
\begin{align*}
\Gamma &::= \emptyset \mid \Gamma, x : C \rightarrow \odot \mid \Gamma, u : \langle U \rangle \\
\Lambda &::= \emptyset \mid \Lambda, x : C \rightarrow \odot \\
\Delta &::= \emptyset \mid \Delta, u : S
\end{align*}
\]
11.6 Minimal Session Types

Γ maps variables and shared names to value types; Λ maps variables to linear higher-order types. Δ maps session names to session types. While Γ admits weakening, contraction, and exchange principles, both Λ and Δ are only subject to exchange. The domains of Γ, Λ, and Δ are assumed pairwise distinct. Δ₁ · Δ₂ is the disjoint union of Δ₁ and Δ₂.

We write Γ \( \setminus x \) to denote Γ \( \setminus \{ x : C \} \), i.e., the environment obtained from Γ by removing the assignment \( x : C \rightarrow \circ \), for some C. Notations \( \Delta \setminus u \) and \( \Gamma \setminus x \) will have expected readings. With a slight abuse of notation, given a tuple of variables \( \bar{x} \), we sometimes write \( (\Gamma, \Delta)(\bar{x}) \) to denote the tuple of types assigned to variables in \( \bar{x} \).

The typing judgements for values \( V \) and processes \( P \) are denoted

\[
\begin{align*}
\Gamma; \emptyset; \emptyset \vdash V \rightarrow C & \quad \text{(PROM)} \\
\Gamma; \emptyset; \emptyset \vdash V \rightarrow C & \quad \text{(EPROM)} \\
\Gamma; A; x : C \rightarrow \circ; \Delta \vdash P \rightarrow \circ & \quad \text{(ABS)} \\
\Gamma; x : C \rightarrow \circ; \Lambda; \Delta \vdash P \rightarrow \circ & \\
\Gamma; x : C \rightarrow \circ; \Lambda; \Delta \rightarrow c_1 & \quad \text{(Abs)} \\
\Gamma; x : C \rightarrow \circ; \Lambda; \Delta \rightarrow c_2 & \quad \text{(Abs)} \\
\end{align*}
\]

Fig. 1 shows selected typing rules; see [20] for a full account. The shared type \( C \rightarrow \circ \) is derived using Rule (PROM) only if the value has a linear type with an empty linear environment. Rule (EPROM) allows us to freely use a shared type variable as linear. Abstraction values are typed with Rule (ABS). Application typing is governed by Rule (App): the type \( C \) of an application name \( u \) must match the type of the application variable \( x \) \( (C \rightarrow \circ \) or \( C \rightarrow \circ) \). In Rule (SEND), the type \( U \) of value \( V \) should appear as a prefix in the session type \( !(U); S \) of \( u \). Rule (RCV) is its dual. Rules (REQ) and (ACC) type interaction along shared names; the type of the sent/received object \( V \) (i.e., \( U \)) should match the type of the subject \( s \) (\( (U) \)).

To state type soundness, we require two auxiliary definitions on session environments. First, a session environment \( \Delta \) is balanced (written \( \text{balanced}(\Delta) \)) if whenever \( s : S_1, \overline{s} : S_2 \in \Delta \) then \( S_1 \) dual \( S_2 \). Second, we define the reduction relation \( \longrightarrow \) on session environments as:

\[
\begin{align*}
\Delta, s : !!(U); S_1, \overline{s} : ?!(U); S_2 & \longrightarrow \Delta, s : S_1, \overline{s} : S_2 \\
\Delta, s : @i : S_i \mid i \in I, \overline{s} : & \& i : S'_i \mid i \in I & \longrightarrow \Delta, s : S_k, \overline{s} : S'_k (k \in I)
\end{align*}
\]

**Theorem 2.4 (Type Soundness [20]).** Suppose \( \emptyset; \Delta \vdash P \rightarrow \circ \) with balanced(\( \Delta \)). Then \( P \rightarrow P' \) implies \( \emptyset; \Delta' \vdash P' \rightarrow \circ \) and \( \Delta = \Delta' \) or \( \Delta \rightarrow \Delta' \) with balanced(\( \Delta' \)).
3 Decomposing Session-Typed Processes

3.1 Key Ideas

Our goal is to transform an HO process $P$, typable with the session types in Def. 2.3, into another HO process, denoted $D(P)$, typable using minimal session types (cf. Def. 3.1 below). By means of this transformation on processes, which we call a decomposition, the sequencing in session types for $P$ is codified in $D(P)$ by using additional actions. To ensure that this transformation on $P$ is sound, we must also decompose its session types; our main result says that if $P$ is well-typed under session types $S_1, \ldots, S_n$, then $D(P)$ is typable using the minimal session types $\mathcal{G}(S_1), \ldots, \mathcal{G}(S_n)$, where $\mathcal{G}(\cdot)$ is a decomposition function that “slices” a session type (as in Def. 2.3) into a list of minimal session types (cf. Def. 3.2 below).

To define the decomposition $D(P)$, in Def. 3.8 we rely on a breakdown function that translates $P$ into a composition of trios processes (or simply trios). A trio is a process with exactly three nested prefixes. Roughly speaking, if $P$ is a sequential process with $k$ nested actions, then $D(P)$ will contain $k$ trios running in parallel: each trio in $D(P)$ will enact exactly one prefix from $P$; the breakdown function must be carefully designed to ensure that trios trigger each other in such a way that $D(P)$ preserves the prefix sequencing in $P$.

We borrow from Parrow [24] some useful terminology and notation on trios. The context of a trio is a tuple of variables $\tilde{x}$, possibly empty, which makes variable bindings explicit. We use a reserved set of propagator names (or simply propagators), denoted with $c_k, \ldots$, to carry contexts and trigger the subsequent trio. A process with less than three sequential prefixes is called a degenerate trio. Also, a leading trio is the one that receives a context, performs an action, and triggers the next trio; a control trio only activates other trios.

The breakdown function works on both processes and values. The breakdown of process $P$ is denoted by $B^P_k(P)$, where $k$ is the index for the propagators $c_k$, and $\tilde{x}$ is the context to be received by the previous trio. Similarly, the breakdown of a value $V$ is denoted by $V_{\tilde{x}}^k(V)$.

We present the decomposition of well-typed HO processes (and its associated typability results) incrementally—this is useful to gradually illustrate our ideas and highlight the several ways in which our developments differ from Parrow’s. In §3.2, we consider a “core fragment” of HO, which contains output and input prefixes, application, restriction, parallel composition, and inaction. Hence, this fragment does not have labeled choice and recursion, nor recursive types. In §3.3 we shall extend the decomposition functions with selection and branching; an extension that supports names with recursive types is presented in §3.4.

3.2 The Core Fragment

We present our approach for a core fragment of HO. We start introducing some preliminary definitions, including the definition of breakdown function. Then we give our main result:
Thm. 3.11 (Page 13) asserts that if process $P$ is well-typed with standard session types, then $D(P)$ is well-typed with minimal session types. This theorem relies crucially on Thm. 3.10 (Page 13), which specifies the way in which the breakdown function preserves typability.

### 3.2.1 Preliminaries

We start by introducing minimal session types as a fragment of Def. 2.3:

> **Definition 3.1 (Minimal Session Types).** The syntax of minimal session types for HO is defined as follows:

\[
U ::= \tilde{C} \rightarrow \diamond \mid \tilde{C} \rightarrow \diamond \\
C ::= M \mid \langle U \rangle \\
M ::= \text{end} \mid !(\langle U \rangle); \text{end} \mid ?(\langle U \rangle); \text{end}
\]

Clearly, this minimal type structure induces a reduced set of typable HO processes. We shall implicitly assume a type system for HO based on these minimal session types by considering the expected specializations of the notions, typing rules, and results summarized in §2.2.

We now define how to “slice” a session type into a list of minimal session types.

> **Definition 3.2 (Decomposing Session Types).** Let $S$ be a session type, $U$ be a higher-order type, $C$ be a name type, and $\langle U \rangle$ be a shared type, all as in Def. 2.3. The type decomposition function $G(\cdot)$ is defined as:

\[
G !(\langle U \rangle); S) = \begin{cases} 
! (G(U)); \text{end} & \text{if } S = \text{end} \\
! (G(U)); \text{end}, G(S) & \text{otherwise}
\end{cases}
\]

\[
G ?(\langle U \rangle); S) = \begin{cases} 
? (G(U)); \text{end} & \text{if } S = \text{end} \\
? (G(U)); \text{end}, G(S) & \text{otherwise}
\end{cases}
\]

\[
G(\text{end}) = \text{end}
\]

\[
G(C \rightarrow \diamond) = G(C) \rightarrow \diamond
\]

\[
G((U)) = \langle G(U) \rangle
\]

\[
G(S_1, \ldots, S_n) = G(S_1), \ldots, G(S_n)
\]

Thus, intuitively, if a session type $S$ contains $k$ input/output actions, the list $G(S)$ will contain $k$ minimal session types. We write $|G(S)|$ to denote the length of $G(S)$.

> **Example 3.3.** Let $S = ?(\text{Int}); ?(\text{Int}); !(\text{Bool}); \text{end}$ be the session type given in §1. Then $G(S)$ is the list of minimal session types given by $?(\text{Int}); \text{end}, ?(\text{Int}); \text{end}, !(\text{Bool}); \text{end}$. <

The breakdown function $B^k_s(\cdot)$ will operate on processes with indexed names (cf. Def. 3.6). Indexes are relevant for session names: a name $s_i$ will execute the $i$-th action in session $s$. For this reason, to extend the decomposition function $G(\cdot)$ to typing environments, we consider names $u_i$ in $\Gamma$ and $\Delta$. To define the decomposition of environments, we rely on the following notation. Given a tuple of names $\tilde{s} = s_1, \ldots, s_n$ and a tuple of (session) types $\tilde{S} = S_1, \ldots, S_n$ of the same length, we write $\tilde{s} : \tilde{S}$ to denote a list of typing assignments $s_1 : S_1, \ldots, s_n : S_n$. 

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The breakdown function $B^k_s(\cdot)$ will operate on processes with indexed names (cf. Def. 3.6). Indexes are relevant for session names: a name $s_i$ will execute the $i$-th action in session $s$. For this reason, to extend the decomposition function $G(\cdot)$ to typing environments, we consider names $u_i$ in $\Gamma$ and $\Delta$. To define the decomposition of environments, we rely on the following notation. Given a tuple of names $\tilde{s} = s_1, \ldots, s_n$ and a tuple of (session) types $\tilde{S} = S_1, \ldots, S_n$ of the same length, we write $\tilde{s} : \tilde{S}$ to denote a list of typing assignments $s_1 : S_1, \ldots, s_n : S_n$. 

Thus, intuitively, if a session type $S$ contains $k$ input/output actions, the list $G(S)$ will contain $k$ minimal session types. We write $|G(S)|$ to denote the length of $G(S)$.

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The breakdown function $B^k_s(\cdot)$ will operate on processes with indexed names (cf. Def. 3.6). Indexes are relevant for session names: a name $s_i$ will execute the $i$-th action in session $s$. For this reason, to extend the decomposition function $G(\cdot)$ to typing environments, we consider names $u_i$ in $\Gamma$ and $\Delta$. To define the decomposition of environments, we rely on the following notation. Given a tuple of names $\tilde{s} = s_1, \ldots, s_n$ and a tuple of (session) types $\tilde{S} = S_1, \ldots, S_n$ of the same length, we write $\tilde{s} : \tilde{S}$ to denote a list of typing assignments $s_1 : S_1, \ldots, s_n : S_n$. 

Thus, intuitively, if a session type $S$ contains $k$ input/output actions, the list $G(S)$ will contain $k$ minimal session types. We write $|G(S)|$ to denote the length of $G(S)$.
We define decomposition.

The degree of names. We shall write \( \tilde{\tau}_k \) and \( \tilde{\tau}_k ! \) to denote input and output prefixes in which the value communicated along \( c_k \) is not relevant. While \( \tilde{\tau}_k ? (\cdot) \) stands for \( \tilde{\tau}_k ? (x) \), \( \tilde{\tau}_k ! (\cdot) \) stands for \( \tilde{\tau}_k ! (\lambda x.0) \). Their corresponding minimal types are \( ?(\text{end} \to \text{o}) \); \( \text{end} \) and \( !(\text{end} \to \text{o}) \); \( \text{end} \), which are denoted by \( ?(\cdot); \text{end} \) and \( !(\cdot); \text{end} \), respectively.

Recall that \( P \) is closed if \( \text{fv}(P) = \emptyset \). We now define the decomposition of a process.

**Definition 3.8 (Decomposing Processes).** Let \( P \) be a closed HO process such that \( \tilde{u} = \text{fn}(P) \). The decomposition of \( P \), denoted \( D(P) \), is defined as:

\[
D(P) = (\nu \tilde{c}) (\tilde{\tau}_k ! (\cdot) . 0 | \mathcal{B}_k^\lambda (P \sigma))
\]

where: \( k > 0 \); \( \tilde{c} = (c_k, \ldots, c_{k+|P|-1}) \); \( \sigma = \{ \text{init}(\tilde{u})/\tilde{u} \} \); and the breakdown function \( \mathcal{B}_k^\lambda (\cdot) \), where \( \tilde{x} \) is a tuple of variables, is defined inductively in §3.2.2.

The bulk of the decomposition of a process is given by the breakdown function, detailed next.
3.2.2 The Breakdown Function

Given a context $\tilde{x}$ and a $k > 0$, the breakdown function $B^k_{\tilde{x}}(\cdot)$ is defined on the structure of initialized processes, relying on the breakdown function on values $V^k_{\tilde{x}}(\cdot)$. The definition relies on type information; we describe each of its cases next.

**Output** The decomposition of $u_! (V).Q$ is the most interesting case: an output prefix sends a value $V$ (i.e., an abstracted process) that has to be broken down as well. We then have:

$$B^k_{\tilde{x}}(u_! (V).Q) = c_k ?(\tilde{x}).u_! (V^{k+1}_{\tilde{x}}(V\sigma)) \cdot \sigma_{k+1}(\tilde{z}) | B^{k+1}_{\tilde{x}}(Q\sigma)$$

Process $B^k_{\tilde{x}}(u_! (V).Q)$ consists of a leading trio that mimics an output action in parallel with the breakdown of the continuation $Q$. The context $\tilde{x}$ must include the free variables of $V$ and $Q$, denoted $\tilde{y}$ and $\tilde{z}$, respectively. These tuples are not necessarily disjoint; variables with shared types can appear free in both $V$ and $Q$. The output object $V$ is then broken down with parameters $\tilde{y}$ and $k + 1$; the latter serves to consistently generate propagators for the trios in the breakdown of $V$, denoted $V^{k+1}_{\tilde{x}}(V\sigma)$ (see below for its definition). The substitution $\sigma$ increments the index of session names; it is applied to both $V$ and $Q$ before they are broken down. We then distinguish two cases:

- If name $u_i$ is linear (i.e., it has a session type) then its future occurrences are renamed into $u_{i+1}$, and $\sigma = \{ u_{i+1}/u_i \}$;
- Otherwise, if $u_i$ is not linear, then $\sigma = \{ \}$.

Note that if $u_i$ is linear then it appears either in $V$ or $Q$ and $\sigma$ affects only one of them. The last prefix in the leading trio activates the breakdown of $Q$ with its corresponding context $\tilde{z}$. To avoid name conflicts with the propagators used in the breakdown of $V$, we use $\sigma_{k+1}$, with $l = |V|$ as a trigger for the continuation.

We remark that the same breakdown strategy is used when $V$ stands for a variable $y$. Since by definition $\{y\} = 0$, $V^k_{\tilde{x}}(y) = y$, and $y\sigma = y$, we have:

$$B^k_{\tilde{x}}(u_! (y).Q) = c_k ?(\tilde{x}).u_! (y) \cdot \sigma_{k+1}(\tilde{z}) | B^{k+1}_{\tilde{x}}(Q\sigma)$$

We may notice that variable $y$ is not propagated further if it does not appear in $Q$.

**Input** The breakdown of an input prefix is defined as follows:

$$B^k_{\tilde{x}}(u_? (y).Q) = c_k ?(\tilde{x}).u_? (y) \cdot \sigma_{k+1}(\tilde{x'}) | B^{k+1}_{\tilde{x}}(Q\sigma)$$

where $\tilde{x'} = fv(Q)$. A leading trio mimics the input action and possibly extends the context with the received variable $y$. The substitution $\sigma$ is defined as in the output case.

**Application** The breakdown of $V u_i$ is as follows:

$$B^k_{\tilde{x}}(V u_i) = c_k ?(\tilde{x}).V^{k+1}_{\tilde{x}}(V) \cdot \tilde{m}$$

A degenerate trio receives a context $\tilde{x}$ and then proceeds with the application. We break down $V$ with $\tilde{x}$ as a context since these variables need to be propagated to the abstracted process. We use $k + 1$ as a parameter to avoid name conflicts. Name $u_i$ is decomposed into a tuple $\tilde{m}$ using type information: if $u_i : C$ then $\tilde{m} = (u_i, \ldots, u_{i+|G(C)|-1})$ and so the length of $\tilde{m}$ is $|G(C)|$; each name in $\tilde{m}$ will perform exactly one action. When $V$ is a variable $y$, we have:

$$B^k_{\tilde{x}}(y u_i) = c_k ?(y) y \cdot \tilde{m}$$

Notice that by construction $\tilde{x} = y$. 
Restriction  We define the breakdown of a restricted process as follows:

\[ B^k_x ((\nu s : C)P') = (\nu \tilde{s} : \mathcal{G}(C)) B^k_x (P' \sigma) \]

By construction, \( \tilde{x} = \mathcal{F}(P') \). Similarly as in the decomposition of \( u_i \) into \( \tilde{m} \) discussed above, we use the type \( C \) of \( s \) to obtain the tuple \( \tilde{s} \) of length \( |\mathcal{G}(C)| \). We initialize the index of \( s \) in \( P' \) by applying the substitution \( \sigma \). This substitution depends on \( C \): if it is a shared type then \( \sigma = \{ s_i / s \} \); otherwise, if \( C \) is a session type, then \( \sigma = \{ s_i / \tilde{m} | s \} \).

Composition  The breakdown of a process \( Q | R \) is as follows:

\[ B^k_x (Q | R) = c_k ? (\tilde{x}).x^{k+1}!(\tilde{y}).x^{k+1}!(\tilde{z}) | B^{k+1}_y (Q) | B^{k+1}_{l+1} (R) \]

A control trio triggers the breakdowns of \( Q \) and \( R \); it does not mimic any action of the source process. The tuple \( \tilde{y} \subseteq \tilde{x} \) (resp. \( \tilde{z} \subseteq \tilde{x} \)) collects the free variables in \( Q \) (resp. \( R \)). To avoid name conflicts, the trigger for the breakdown of \( R \) is \( c_{k+l+1} \), with \( l = |Q| \).

Inaction  To breakdown \( 0 \), we define a degenerate trio with only one input prefix that receives a context that by construction will always be empty, i.e., \( \tilde{x} = \epsilon \): \n
\[ B^k_x (0) = c_k ? (\epsilon).0 \]

Value  In defining the breakdown function for values we distinguish two main cases:
- If \( V = \lambda y : C^\rightarrow. P \), where \( \rightarrow \in \{ \rightarrow, \rightarrow \} \), then we have:
  \[ \mathcal{V}^k \lambda y : C^\rightarrow. P = \lambda \tilde{y} : \mathcal{G}(C)^\rightarrow. (\nu \tilde{c} (\mathcal{P}(\tilde{x})) | B^k_x (P[y/\tilde{y}])) \]

  We use type \( C \) to decompose \( y \) into the tuple \( \tilde{y} \). We abstract over \( \tilde{y} \); the body of the abstraction is the composition of a control trio and the breakdown of \( P \), with name index initialized with the substitution \( \{ y_i / \tilde{y} \} \). If \( \rightarrow = \rightarrow \) then we restrict the propagators \( \tilde{c} = (c_k, \ldots, c_{k+l-1}) \); this enables us to type the value in a shared environment. When \( \rightarrow = \rightarrow \) we do not have to restrict the propagators, and \( \tilde{c} = \epsilon \).
- If \( V = y \), then the breakdown function is the identity: \( \mathcal{V}^k \lambda y = y \).

Tab. 1 summarizes the definition of the breakdown, spelling out the side conditions involved. We illustrate it by means of an example:

**Example 3.9 (Breaking Down Name-Passing).** Consider the following process \( P \), in which a channel \( m \) is passed, through which a Boolean value is sent back:

\[ P = (\nu u)(u! (m). \overline{m}?! (b).0 | \overline{m}?! (x). x! (\text{true}).0) \]

\( P \) is not an \( \text{HO} \) process as it features name-passing. We then use the encoding described in Exam. 2.1 to construct its encoding into \( \text{HO} \). We thus obtain \( [P] = (\nu u) (Q | R) \), where

\[ Q = u! (V). \overline{m}?! (y). (\nu s) (y s | \overline{s}(\lambda b. 0).0) \]

\[ V = \lambda z. z?! (x). (x m) \]

\[ R = \overline{m}?! (y). (\nu s) (y s | \overline{s}(W).0) \]

\[ W = \lambda x. x! (W').0 \text{ with } W' = \lambda z. z?! (x). (x \text{ true}) \]

By Exam. 2.1, we know that \([\cdot]\) requires exactly four reduction steps to mimic a name-passing synchronization. We show here part of the reduction chain of \([P]\):

\[ [P] \rightarrow^4 [\overline{m}?! (b).0 | m! (\text{true}).0] \rightarrow^4 0 \]

We will now investigate the decomposition of \([P]\) and its reduction chain. First, we use Def. 3.5 to compute \(|V| = |W'| = 2\), and so \(|W| = 4\). Then \(|Q| = |y s | \overline{s}(\lambda b. 0).0| + |V| + 2 = 9\), and
After knowing that further along, until $V$ process will be ready to mimic the first action that is performed by interesting process appears after synchronizations on similarly, $\epsilon$. Therefore, $\|P\| = 19$. Following Def. 3.8, we see that $\sigma = \{m_1, \overline{m_i}/m_i\}$, which we silently apply. Using $k = 1$, we then have the decomposition shown in Tab. 2.

Tab. 2 we have omitted substitutions that have no effect and trailing $0$s. The first interesting process appears after synchronizations on $c_1, c_2,$ and $c_{11}$. At that point, the process will be ready to mimic the first action that is performed by $[P]$, i.e., $u_1$ will send $\nu \bar{s} (V)$, the breakdown of $V$. Next, $c_{12}, c_{13},$ and $c_{14}$ will synchronize, and $\nu \bar{s} (V)$ is passed further along, until $s_1$ is ready to be applied to it in the breakdown of $R$. At this point, we know that $[P] \rightarrow^0 (\nu \bar{c})P'$, where $\bar{c} = (c_3, \ldots, c_{10}, c_{15}, \ldots, c_{19})$, and

$$P' = \nu \bar{s}(\bar{y}) \cdot 0 | c_3(\bar{y}) \cdot \overline{m_1} \cdot \nu \bar{s}(y) \cdot \overline{m_1} \cdot \bar{y} \cdot 0$$
$$| (\nu s_1)(c_3(y), \overline{m_1}(y), \overline{m_i}(y), \overline{m_1}(y), \nu \bar{s}(y), y) \cdot s_1 | c_0(\nu \bar{s}(\overline{m_2} (\nu \bar{c}) \cdot \overline{m_1} (y), \overline{m_1} (y), \bar{y} \cdot 0) | c_0(\nu \bar{s}(\bar{y}) \cdot 0)$$
$$| (\nu s_1)(\nu \bar{s}(\nu \bar{s}(\nu \bar{s}(\nu \bar{s}(\nu \bar{s}(\nu \bar{s}(\nu \bar{s}(\nu \bar{s}(\nu \bar{s}(\nu \bar{s}(\nu \bar{s}(\nu \bar{s}(\nu \bar{s}(\nu \bar{s}(\nu \bar{s}(\nu \bar{s}(\nu \bar{s}(\nu \bar{s}(\nu \bar{s}(V)))))))))))))))) \cdot 0 | c_{09}(\nu \bar{s}(\bar{y})) \cdot 0$$

After $s_1$ is applied, the trio guarded by $c_3$ will be activated, where $z_1$ has been substituted.
by $s_1$. Then $\overline{\tau_1}$ and $s_1$ will synchronize, and the breakdown of $W$ is passed along. Then $c_4$ and $c_{19}$ synchronize, and now $m_1$ is ready to be applied to $V_{\epsilon}^{15}(W)$, which was the input for $c_4$ in the breakdown of $V$. After this application, $c_5$ and $c_{15}$ can synchronize with their duals, and we know that $(\nu \tilde{c})P' \rightarrow^{\nu} (\nu \tilde{c}^2)P''$, where $\tilde{c}' = (c_6, \ldots, c_{10}, c_{16}, c_{17}, c_{18})$, and

$$P'' = \overline{\tau_1}(y).\overline{\tau_1}(y).0 \mid m_1!(V_{\epsilon}^{15}(W'')).\overline{\tau_1}10.0 \mid c_{15}?().0$$

$$\mid (\nu s_1)(c_5?().y).\overline{\tau_1}(y).\overline{\tau_1}10.0 \mid c_{15}?().y.s_1 \mid c_5?().\overline{\tau_1}1010.0 \mid c_{15}?().0$$

Remarkably, $P''$ is standing by to mimic the encoded exchange of value true. Indeed, the decomposition of the four-step reduced process in (2) will reduce in three steps to a process that is equal (up to $\equiv_n$) to the process we obtained here. This strongly suggests a tight operational correspondence between a process and its decomposition.

We may now state our technical results:

\textbf{Theorem 3.10 (Typability of Breakdown).} Let $P$ be an initialized process and $V$ be a value.

1. If $\Gamma; \Delta \vdash P \triangleright \bigcirc$ then

$$G(\Gamma); \emptyset; G(\Delta), \Theta \vdash B^{\Delta}_{\epsilon}(P) \triangleright \bigcirc \quad (k > 0)$$

where: $\tilde{x} = \text{fv}(P); \Gamma_1 = \Gamma \setminus \tilde{x}$; and balanced($\Theta$) with $\text{dom}(\Theta) = \{c_k, c_{k+1}, \ldots, c_{k+|\Gamma| - 1}\} \cup \{\tilde{c}_k, \ldots, \tilde{c}_{k+|\Gamma| - 1}\} \cup \Theta(c_k) = ?(M);$ end, where $M = (G(\Gamma), G(\Delta))(\tilde{x})$.

2. If $\Gamma; \Delta \vdash V \triangleright C \dashv \triangleright$ then

$$G(\Gamma); G(\Delta), \Theta \vdash V_{\epsilon}^{\Delta}(V) \triangleright G(C) \dashv \triangleright \quad (k > 0)$$

where: $\tilde{x} = \text{fv}(V)$; and balanced($\Theta$) with $\text{dom}(\Theta) = \{c_k, \ldots, c_{k+|\Gamma| - 1}\} \cup \{\tilde{c}_k, \ldots, \tilde{c}_{k+|\Gamma| - 1}\}$ and $\Theta(c_k) = ?(M);$ end, where $M = (G(\Gamma), G(\Delta))(\tilde{x})$.

3. If $\Gamma; \emptyset; \emptyset \vdash V \triangleright C \dashv \triangleright$ then $G(\Gamma); \emptyset; \emptyset \vdash V_{\epsilon}^{\Delta}(V) \triangleright G(C) \dashv \triangleright$, where $\tilde{x} = \text{fv}(V)$ and $k > 0$.

\textbf{Proof.} By mutual induction on the structure of $P$ and $V$. See Appendix A.2 for details.

Using the above theorem, we can prove our main result:

\textbf{Theorem 3.11 (Typability of the Decomposition).} Let $P$ be a closed HO process with $\tilde{u} = \text{fn}(P)$. If $\Gamma; \emptyset; \emptyset \vdash P \triangleright \bigcirc$ then $G(\Gamma \sigma); \emptyset; G(\Delta \sigma) \vdash D(P) \triangleright \bigcirc$, where $\sigma = \{\text{init}(\tilde{u})/\tilde{u}\}$.

\textbf{Proof.} Direct from the definitions, using Thm. 3.10. See Appendix A.3 for details.
3.3 Extensions (I): Select and Branching

We now show how to extend the decomposition to handle select and branch processes, which implement labeled (deterministic) choice in session protocols, as well as their corresponding session types. As we will see, in formalizing this extension we shall appeal to the expressive power of abstraction-passing. We start by extending the syntax of minimal session types:

Definition 3.12 (Minimal Session Types (with Labeled Choice)). The syntax of minimal session types for HO is defined as follows:

\[
M ::= \text{end} \mid !(\tilde{U}); \text{end} \mid ?(\tilde{U}); \text{end} \mid \oplus \{l_i : M_i\}_{i \in I} \mid \& \{l_i : M_i\}_{i \in I}
\]

where \( U \) and \( C \) are defined as in Def. 3.1.

We may then extend Def. 3.2 to branch and select types as follows:

Definition 3.13 (Decomposing Session Types, Extended (I)). The decomposition function on types as given in Def. 3.2 is extended as follows:

\[
\begin{align*}
\mathcal{G}(\&\{l_i : S_i\}_{i \in I}) &= \&\{l_i : !\mathcal{G}(S_i) \rightarrow \circ\}; \text{end}\}_{i \in I} \\
\mathcal{G}(\oplus\{l_i : S_i\}_{i \in I}) &= \oplus\{l_i : ?\mathcal{G}(S_i) \rightarrow \circ\}; \text{end}\}_{i \in I}
\end{align*}
\]

The above definition for decomposed types already suggests our strategy to breakdown branching and selection processes: we will exploit abstraction-passing to exchange one abstraction per each branch of the labeled choice. This intuition will become clearer shortly.

We now extend the definition of the degree of a process/value (cf. Def. 3.5) to account for branch and select processes:

Definition 3.14 (Degree of a Process, Extended). The degree of a process \( P \), denoted \( |P| \), is as given in Def. 3.5, extended as follows:

\[
|P| = \begin{cases} 
1 & \text{if } P = u_i \triangleright \{l_j : P_j\}_{j \in I} \\
|P'| + 2 & \text{if } P = u_i \triangleleft l_j. P'
\end{cases}
\]

The definition of process decomposition (cf. Def. 3.8) does not require modifications; it relies on the extended definition of the breakdown function for processes \( B^k_\sigma(\cdot) \) that combines the definitions in Tab. 1 with those in Tab. 3 (see below). The breakdown of values \( V^k_\sigma(\cdot) \) is as before, and relies on the extended definition of \( B^k_\sigma(\cdot) \).

We now present and describe the breakdown of branching and selection processes:

Branching The breakdown of a branching process \( u_i \triangleright \{l_j : P_j\}_{j \in I} \) is as follows:

\[
B^k_\sigma(u_i \triangleright \{l_j : P_j\}_{j \in I}) = c_k(\tilde{x}).u_i \triangleright \{l_j : u_i!(N_{u,j})\}_{j \in I}
\]

where \( N_{u,j} = \lambda y^u_j : \mathcal{G}(S_j).((\nu \tilde{c}_j)(\tilde{y}_{k+1}(\tilde{x})) B^k_{\sigma+1}(P_j\{y^u_j/u_i\})) \)

The first prefix receives the context \( \tilde{x} \). The next two prefixes are along \( u_i \): the first one mimics the branching action of \( P \), whereas the second outputs an abstraction \( N_{u,j} \). This output does not have a counterpart in \( P \); it is meant to synchronize with an input in the breakdown of the corresponding selection process (see below). \( N_{u,j} \) encapsulates the breakdown of subprocess \( P_j \). It has the same structure as the breakdown of a value \( \lambda y : C \rightarrow^* P \) in Tab. 1: it is a composition of a control trio and the breakdown of \( P_j \); the generated propagators, denoted \( \tilde{c}_j \), are restricted. We use types to define \( N_{u,j} \): we assume \( S_j \) is the session type of \( u_i \) in the \( j \)-th branch of \( P \). We abstract over \( y^u_j = (y^u_{1,j}, \ldots, y^u_{n(S_j)}) \). We substitute \( u_i \) with \( y^u_j \) in \( P_j \) before breaking it down: this way, \( u_i \) is decomposed and bound by abstraction.
We will investigate the decomposition of

\[ \text{Def. 3.14, we have:} \]

\[ V \text{ allows clients to add or subtract two integers. The server contains two branches: one sends} \]

\[ \text{of selection and branching processes by considering a basic mathematical server} \]

\[ \text{▶ \ for details).} \]

\[ \text{correspond to a form of output and input actions involving labels, respectively.} \]

\[ \text{session type and degree. Interestingly, it follows the intuition that branching and selection} \]

\[ \text{to uniformly handle the fact that the subprocesses of a branching process have a different} \]

\[ \text{Summing up, our strategy for breaking down labeled choices exploits higher-order concurrency} \]

\[ \text{Selection The breakdown of a selection process} \]

\[ \text{The breakdown function for processes (extension with selection and branching).} \]

\[ \text{Table 3} \]

\[ \text{▶} \text{ branchings) of selection and branching.} \]

\[ \text{Selection The breakdown of a selection process} \]

\[ \text{After receiving the context} \]

\[ \text{The breakdown of a selection process} \]

\[ \text{Summing up, our strategy for breaking down labeled choices exploits higher-order concurrency} \]

\[ \text{to uniformly handle the fact that the subprocesses of a branching process have a different} \]

\[ \text{Interestingly, it follows the intuition that branching and selection} \]

\[ \text{Remark 3.15. Theorems 3.10 and 3.11 hold also for the extension with selection and} \]

\[ \text{Example 3.16 (Breaking down Selection and Branching). We illustrate the breaking down} \]

\[ \text{The composition} \]

\[ \text{We will investigate the decomposition of} \]

\[ \text{and its reduction chain. First, by Def. 3.5 and} \]

\[ \text{we have:} |Q| = 1, |R| = 4, \text{and} |P| = 6. \]

\[ \text{following the extension of Def. 3.8, using} \]
We will now follow the chain of reductions of the process \( \mathcal{D}(P) \). First, \( c_1, c_2, \) and \( c_3 \) will synchronize, after which \( c_4 \) will pass the abstraction. Let \( \mathcal{D}(P) \rightarrow^4 P' \), then we know:

\[
P' = (\nu c_3c_4)(\nu u_1)(u_1 \triangleright \{ \text{add} : (\nu c_3c_4)u_1!(\lambda y_1. \overline{c_3}!().0 | B^2_1(y_1!(V_+).0).0) \}) \cdot \nu c_3c_4u_1!(\lambda y_1. \overline{c_3}!().0 | B^2_1(y_1!(V_+).0).0)
\]

The breakdown of \( R \) is obtained by applying the second rule in Tab. 3:

\[
B^2_1(R\sigma_2) = \text{c}3?().\overline{c_3}!(\lambda y_1. \overline{c_3}!().0 | B^2_1(y_1!(V_+).0).0) = \text{add.} \overline{c_3}?().\overline{c_3}!().0 | B^2_1(y_1!(V_+).0).0)
\]

We will now follow the chain of reductions of the process \( \mathcal{D}(P) \). First, \( c_1, c_2, \) and \( c_3 \) will synchronize, after which \( c_4 \) will pass the abstraction. Let \( \mathcal{D}(P) \rightarrow^4 P' \), then we know:

\[
P' = (\nu c_3c_4)(\nu u_1)(u_1 \triangleright \{ \text{add} : (\nu c_3c_4)u_1!(\lambda y_1. \overline{c_3}!().0 | B^2_1(y_1!(V_+).0).0) \}) \cdot \nu c_3c_4u_1!(\lambda y_1. \overline{c_3}!().0 | B^2_1(y_1!(V_+).0).0)
\]

In \( P' \), \( \overline{c_3} \) will be applied to the abstraction with variable \( y_1 \). After that, the choice for the process labeled by \text{add} is made. Process \( P' \) will reduce further as \( P' \rightarrow^2 P'' \rightarrow^2 P''' \), where:

\[
P'' = (\nu c_3c_4)(\nu u_1)(u_1 \triangleright \{ \text{add} : (\nu c_3c_4)u_1!(\lambda y_1. \overline{c_3}!().0 | B^2_1(y_1!(V_+).0).0) \}) \cdot \nu c_3c_4u_1!(\lambda y_1. \overline{c_3}!().0 | B^2_1(y_1!(V_+).0).0)
\]

\[
P''' = (\nu c_3c_4)(\nu u_1)(u_1 \triangleright \{ \text{add} : (\nu c_3c_4)u_1!(\lambda y_1. \overline{c_3}!().0 | B^2_1(y_1!(V_+).0).0) \}) \cdot \nu c_3c_4u_1!(\lambda y_1. \overline{c_3}!().0 | B^2_1(y_1!(V_+).0).0)
\]

Interestingly, \( P''' \) strongly resembles a decomposition of the one-step reduced process in (3). This advocates the operational correspondence between a process and its decomposition.

3.4 Extensions (II): Recursion

We extend the decomposition to handle HO processes in which names can be typed with recursive session types \( \mu t.S \). We consider recursive types which are simple and contractive, i.e., in \( \mu t.S \), the body \( S \neq t \) does not contain recursive types. Unless stated otherwise, we shall handle tail-recursive session types such as \( \epsilon.S \=(\text{Int})/\text{(Bool)}; \text{(Bool)}; t \). Non-tail-recursive session types such as \( \mu t.((\tilde{T}, t) \rightarrow \sigma) \end{end} \), which is essential in the fully abstract encoding of HO\( S \) into HO [19], can also be accommodated; see Rem. 3.29 below.

We start by extending minimal session types (Def. 3.1) with minimal recursive types:

\textbf{Definition 3.17 (Minimal Recursive Session Types).} The syntax of minimal recursive session types for \( HO \) is defined as follows:

\[
M ::= \gamma | !(\tilde{U}); \gamma | ?!(\tilde{U}); \gamma | \mu t.M
\]

\[
\gamma ::= \text{end} | t
\]

Thus, types such as \( \mu t.!(U); t \) and \( \mu t.?((U); t \) are minimal recursive session types: in fact they are tail-recursive session types with exactly one session prefix. We extend Def. 3.2 as follows:
We shall also use the function \( \mathcal{G}(\cdot) \) (such as \( \mathcal{G}(t_0) = t \)).

We address both issues by devising a mechanism that propagates names with recursive types.

There are several issues with this breakdown. One of them is typability: we have that

\[ \langle \mu.t.1 \rangle \texttt{Int} \]

1

if \( \mu.t.1 \texttt{Int} \) is typable under a linear environment containing \( \mu.t.1 \texttt{Int} \).

Further,

\[ \mathcal{G}((\mu.t.1 \texttt{Int}); t, \mathcal{R}(S)) \]

\[ \mathcal{G}((\mu.t.1 \texttt{Int}); t, \mathcal{R}(S)) \]

We illustrate Def. 3.18 with two examples:

\[ \mathcal{G}(\mu.t.1 \texttt{Int}); t, \mathcal{R}(S)) \]

\[ \mathcal{G}(\mu.t.1 \texttt{Int}); t, \mathcal{R}(S)) \]

We now explain how to decompose processes whose names are typed with recursive types.

In the core fragment, we decompose a name \( u \) into a sequence of names \( \tilde{u} = (u_1, \ldots, u_n) \):

\[ \text{each } u_i \in \tilde{u} \text{ is used exactly by one trio to perform exactly one action; the session associated to } u_i \text{ ends after its single use, as prescribed by its minimal session type.} \]

The situation is different when names can have recursive types, for the names \( \tilde{u} \) should be propagated in order to be used infinitely many times. As a simple example, consider the process

\[ R = r.?x(r).r!x(V).r \]

where name \( r \) has type \( S = \mu.t.1 \texttt{Int}; t \) and the higher-order type of \( V \) is \( S \rightarrow \circ \).

Processes of this form are key in the encoding of recursion given in [19]. A naive decomposition of \( R \), using the approach we defined for processes without recursive types, would result into

\[ B^1_1(R) = c_1.?x(r).r!x(V).r \quad c_2.?x(r).r!x(V).r \]

There are several issues with this breakdown. One of them is typability: we have that

\[ r_1 : \mu.t.1 \texttt{Int}; t \]

but subprocess \( r_2.?x(V).r \) is not typable under a linear environment containing such a judgment. Another, perhaps more central, issue concerns \( r \): the last trio (which mimics application) should apply to the sequence of names \( (r_1, r_2) \), rather than to \( (r_3, r_4) \).

We address both issues by devising a mechanism that propagates names with recursive types (such as \( (r_1, r_2) \)) among the trios that use some of them. This entails decomposing \( R \) in...
such a way that the first two trios propagate \( r_1 \) and \( r_2 \) after they have used them; the trio simulating \( V r \) should then have a way to access the propagated names \( (r_1, r_2) \).

We illustrate the key insights underpinning our solution by means of two examples. The first one illustrates how to break down input and output actions on names with recursive types (the “first part” of \( R \)). The second example shows how to break down an application where a value is applied to a tuple of names with recursive names (the “second part” of \( R \)).

**Example 3.21** (Decomposing Processes with Recursive Names (I)). Let \( P = r?(x).r!(x).P' \) be a process where \( r \) has type \( S = \mu t.(\text{Int})::!(\text{Int}); t \) and \( r \in \text{fn}(P') \). To define \( B_1^1(P) \) in a compositional way, names \( (r_1, r_2) \) should be provided to its first trio; they cannot be known beforehand. To this end, we introduce a new control trio that will hold these names:

\[
e^r(\langle b \rangle, (r_1, r_2))
\]

where the *shared* name \( e^r \) provides a decomposition of the (recursive) name \( r \). The intention is that each name with a recursive type \( r \) will get its own dedicated propagator channel \( e^r \).

Since there is only one recursive name in \( P \), its decomposition will be of the following form:

\[
D(P) = (\nu \bar{c})(\nu e^r)(e^r(\langle b \rangle, (r_1, r_2)) | \text{\( \tau \)}!, 0 | B_1^1(P))
\]

The new control trio can be seen as a server that provides names: each trio that mimics some action on \( r \) should request the sequence \( \bar{r} \) from the server on \( e^r \). This request will be realized by a higher-order communication: trios should send an abstraction to the server; such an abstraction will contain further actions of a trio and it will be applied to the sequence \( \bar{r} \). Following this idea, we may refine the definition of \( D(P) \) by expanding \( B_1^1(P) \):

\[
D(P) = (\nu \bar{c})(\nu e^r)(e^r(\langle b \rangle, (r_1, r_2)) | \text{\( \tau \)}!, 0 | c_1?(\langle N_1 \rangle).0 | c_2?(y).c^r!(\langle N_2 \rangle).0 | B_1^2(P'))
\]

The trios involving names with recursive types have now a different shape. After being triggered by a previous trio, rather than immediately mimicking an action, they will send an abstraction to the server available on \( e^r \). The abstractions \( N_1 \) and \( N_2 \) are defined as follows:

\[
N_1 = \lambda (z_1, z_2). z_1?(x).\text{\( \tau \)}!\langle x \rangle.e^r(\langle b \rangle, (z_1, z_2)) \quad N_2 = \lambda (z_1, z_2). z_2!(x).\text{\( \tau \)}!\langle \rangle.e^r(\langle b \rangle, (z_1, z_2))
\]

Hence, the formal arguments for these values are meant to correspond to \( \bar{r} \). The server on name \( e^r \) will appropriately instantiate these names. Notice that all names in \( \bar{r} \) are propagated, even if the abstractions only use some of them. For instance, \( N_1 \) only uses \( r_1 \), whereas \( N_2 \) uses \( r_2 \). After simulating an action on \( r_1 \) and activating the next trio, these values restate the server on \( e^r \) for the benefit of future trios mimicking actions on \( r \).

**Example 3.22** (Decomposing Processes with Recursive Names (II)). Let \( S = \mu t.(\text{Int})::!(\text{Int}); t \) and \( T = \mu t.!(\text{Bool}); t \) and define \( Q = V(u, v) \) as a process where \( u : S \) and \( v : T \), where \( V \) is some value of type \( (S, T) \rightarrow \text{\( \alpha \)} \). The decomposition of \( Q \) is as in the previous example, except that now we need two servers, one for \( u \) and one for \( v \):

\[
D(Q) = (\nu \bar{c})(\nu e^r)(e^r(\langle b \rangle, (u_1, u_2)) | e^r(\langle b \rangle, (v_1, v_2)) | \text{\( \tau \)}!, 0 | B_1^1(Q))
\]

where \( \bar{c} = (c_2, \ldots, c_{|Q|}) \). We should break down \( Q \) in such a way that it could communicate with both servers to collect sequences \( \bar{u} \) and \( \bar{v} \). To this end, we define a process in which abstractions are nested using output prefixes and whose innermost process is an application. After successive communications with multiple servers this innermost application will have collected all names in \( \bar{u} \) and \( \bar{v} \). We apply this idea to breakdown \( Q \):

\[
B_1^1(Q) = c_1?().c^u!(\langle x_1, x_2 \rangle).c^v!(\langle y_1, y_2 \rangle).V^2(V)(x_1, x_2, y_1, y_2).0.0
\]
Observe that we use two nested outputs, one for each name with recursive types in Q. We now look at the reductions of \( \mathcal{D}(Q) \) to analyze how the communication of nested abstractions allows us to collect all name sequences needed. After the first reduction along \( c_1 \) we have:

\[
\mathcal{D}(Q) \rightarrow (\nu \tilde{c})(\nu c^n c^r)(\exists \sigma \xi (\lambda x_1, x_2). c^n! (\lambda y_1, y_2). V^2 (V) (x_1, x_2, y_1, y_2)). \sigma.0 = R^1
\]

From \( R^1 \) we have a synchronization along name \( c^n \):

\[
R^1 \rightarrow (\nu \tilde{c})(\nu c^n c^r)(\lambda x_1, x_2). c^n! (\lambda y_1, y_2). V^2 (V) (x_1, x_2, y_1, y_2)). \sigma (u_1, u_2) | e^{c'}(?)(b) (v_1, v_2) = R^2
\]

Upon receiving the value, the server applies it to \((u_1, u_2)\) obtaining the following process:

\[
R^2 \rightarrow (\nu \tilde{c})(\nu c^n c^r)(\lambda \nu c_1, \nu c_2, \nu c_3) (\nu \nu c_3)?(b) (u_1, u_2, y_1, y_2)). \sigma (u_1, u_2) | e^{c'}(?)(b) (v_1, v_2) = R^3
\]

Up to here, we have partially instantiated name variables of a value with the sequence \( \tilde{u} \). Next, the first trio in \( R^3 \) can communicate with the server on name \( c^r \):

\[
R^3 \rightarrow (\nu \tilde{c})(\nu c^n c^r)(\lambda \nu c_1, \nu c_2, \nu c_3) (\nu \nu c_3)?(b) (u_1, u_2, y_1, y_2) (v_1, v_2))
\]

This completes the instantiation of name variables with appropriate sequences of names with recursive types. At this point, \( \mathcal{D}(Q) \) can proceed to mimic the application in \( Q \).

These two examples illustrate the main ideas of the decomposition of processes that involve names with recursive types. Tab. 4 presents a formal account of the extension of the definition of process decomposition given in Def. 3.8. Before explaining the table in detail, we require an auxiliary definition.

Given an unfolded recursive session type \( S \), the auxiliary function \( f(S) \) returns the position of the top-most prefix of \( S \) within its body. (Whenever \( S = \mu t.S' \), we have \( f(S) = 1 \).)

**Definition 3.23 (Index function).** Let \( S \) be an (unfolded) recursive session type. The function \( f(S) \) is defined as follows:

\[
f(S) = \begin{cases} 
  f'_0(S'/t) & \text{if } S = \mu t.S' \\
  f'_0(S) & \text{otherwise}
\end{cases}
\]

where: \( f'_0(\mu t.S) = |R(S)| - l + 1 \), \( f'_0(!t); S = f'_{l+1}(S) \), \( f'_0(?t); S = f'_{l+1}(S) \).

**Example 3.24.** Let \( S'=?!(\text{Bool})!?(\text{Bool})!\). We where \( S \) is as in Exam. 3.19. Then \( f(S') = 2 \) since the top-most prefix of \( S' \) (\( ?!(\text{Bool})!\)) is the second prefix in the body of \( S \).

Given a typed process \( P \), we write \( \text{rn}(P) \) to denote the set of free names of \( P \) whose types are recursive. As mentioned above, for each \( r \in \text{rn}(P) \) with \( r : S \) we shall rely on a control trio of the form \( e^n!(b).b \tilde{r} \), where \( \tilde{r} = r_1, \ldots, r_{|S|} \).

**Definition 3.25 (Decomposition of a Process with Recursive Session Types).** Let \( P \) be a closed \( \lambda \) process with \( \tilde{u} = \text{fn}(P) \) and \( \tilde{v} = \text{rn}(P) \). The decomposition of \( P \), denoted \( \mathcal{D}(P) \), is defined as:

\[
\mathcal{D}(P) = (\nu \tilde{c})(\nu c^n c^r)(\prod_{r \in \tilde{v}} e^n!(b).b \tilde{r} | c^n!().0 | B^n (P \sigma))
\]

where: \( k > 0 \); \( \tilde{c} = (c_k, \ldots, c_{k+|P|-1}) \); \( \tilde{c}_r = \bigcup_{c \in \tilde{c}} c \); \( \sigma = \{ \text{init}(\tilde{u})/\tilde{u} \} \).
We now describe the required extensions for the function $B^k_2(\cdot, \cdot)$. We will use predicate $\text{tr}(S)$ on types to indicate that $S$ is a tail-recursive session type. Tab. 4 describes the breakdown of prefixes whose type is recursive; all other prefixes can be treated as in Tab. 1.

**Output** The breakdown of process $r!\langle V \rangle.Q$, when $r$ has a recursive type $S$, is as follows:

$$B^k_2(r!\langle V \rangle.Q) = c_k?\langle \tilde{x} \rangle.c^!\langle N_V \rangle \mid B^{k+1}_{w}(Q)$$

where $N_V = \lambda \tilde{z}.z_{f(S)}!\langle V_0 \rangle.\tilde{c}_{k+1}\langle \tilde{w} \rangle.c^\nu?\langle b \rangle.(b \tilde{z})$

The decomposition consists of a leading trio that mimics the output action running in parallel with the breakdown of $Q$. After receiving the context $\tilde{x}$, the leading trio sends an abstraction $N_V$ along $c^\nu$. Value $N_V$ performs several tasks. First, it collects the sequence $\tilde{r}$; then, it mimics the output action of $P$ along one of them ($r_{f(S)}$) and triggers the next trio, with context $\tilde{w}$; finally, it reinstates the server on $c^\nu$ for the next trio that...
The breakdown of process

**Application**

For simplicity we consider applications

**Value**

The polyadic value

**Restriction**

The restriction process

We decompose

We rely on types to decompose every name in

The breakdown follows the lines of the output case, but also of the linear case in Tab. 1,

The breakdown of a value application of the form

applies it to the sequence

for

introduces two servers in parallel with the breakdown of

mimics the application in the source process. By this abstraction nesting we bind all

abstraction abstracts over

each abstraction binds

n

abstractions that occur nested within output prefixes: for each

for each

orders in names and multiple names with non-recursive types is as expected. We have:

The breakdown follows the lines of the output case, but also of the linear case in Tab. 1,

with additional structure needed to implement the reception of

using one of the received names (r_f(S)) as a subject for the input action and propagating those names further.

**Application** For simplicity we consider applications V(\tilde{r}, u_i), where names in \tilde{r} have recursive types and only name u_i has a non-recursive type; the general case involving different orders in names and multiple names with non-recursive types is as expected. We have:

We rely on types to decompose every name in (\tilde{r}, u_i). Letting |\tilde{r}| = n and i \in \{1, \ldots, n\}, for each r_i \in \tilde{r} (with r_i : S_i) we generate a sequence \tilde{z}_i = (z_i^1, \ldots, z_i^{|R_f(S_i)|}) as in the output case. Since name u_i has a non-recursive session type, we decompose it as in Tab. 1. Subsequently, we define an output action on propagator c^\sigma that sends a value containing n abstractions that occur nested within output prefixes: for each j \in \{1, \ldots, n-1\}, each abstraction binds \tilde{z}_j and sends the next abstraction along c^{\sigma_{j+1}}. The innermost abstraction abstracts over \tilde{z}_n and encapsulates process V^{k+1}_B(V(\tilde{z}_1, \ldots, \tilde{z}_n, m)) which mimics the application in the source process. By this abstraction nesting we bind all variables \tilde{z}_i in Q. This structure can be seen as an encoding of partial application: by virtue of a single synchronization on c^\sigma part of variables (i.e., \tilde{z}_i) will be instantiated.

The breakdown of a value application of the form y(\tilde{r}, u_i) results into a specific form of the breakdown:

We rely on types to decompose every name in (\tilde{r}, u_i). Letting |\tilde{r}| = n and i \in \{1, \ldots, n\}, for each r_i \in \tilde{r} (with r_i : S_i) we generate a sequence \tilde{z}_i = (z_i^1, \ldots, z_i^{|R_f(S_i)|}) as in the output case. Since name u_i has a non-recursive session type, we decompose it as in Tab. 1. Subsequently, we define an output action on propagator c^\sigma that sends a value containing n abstractions that occur nested within output prefixes: for each j \in \{1, \ldots, n-1\}, each abstraction binds \tilde{z}_j and sends the next abstraction along c^{\sigma_{j+1}}. The innermost abstraction abstracts over \tilde{z}_n and encapsulates process V^{k+1}_B(V(\tilde{z}_1, \ldots, \tilde{z}_n, m)) which mimics the application in the source process. By this abstraction nesting we bind all variables \tilde{z}_i in Q. This structure can be seen as an encoding of partial application: by virtue of a single synchronization on c^\sigma part of variables (i.e., \tilde{z}_i) will be instantiated.

The breakdown of a value application of the form y(\tilde{r}, u_i) results into a specific form of the breakdown:

The restriction process (νs : μt.S)P' is translated as follows:

We decompose s into \tilde{s} = (s_1, \ldots, s_{|R(S)|}) and \bar{s} into \tilde{s} = (\bar{s}_1, \ldots, \bar{s}_{|R(S)|}). The breakdown introduces two servers in parallel with the breakdown of P'; these servers provide names for s and \bar{s} along c^\sigma and c^\bar{\sigma}, respectively. The server on c^\sigma (resp. c^\bar{\sigma}) receives a value and applies it to the sequence \tilde{s} (resp. \bar{s}). We restrict over \tilde{s} and propagators c^\sigma and c^\bar{\sigma}.

**Value**

The polyadic value \lambda(y, z) : (\tilde{S}, C, P) is decomposed as follows:

We assume variables in \tilde{y} have recursive session types \tilde{S} and variable z has some non-recursive session type C; the general case involving different orders in variables and
The decomposition relies twice on the breakdown of value where arbitrary observe that the entire sequence by reinstating a server defined as a control trio. Interestingly, this scheme names; then, it uses one of such names to mimic the appropriate action; finally, it propagates the entire sequence by reinstating a server defined as a control trio. Interestingly, this scheme for name propagation follows the implementation of the encoding of name-passing in HO.

Example 3.26 (Breakdown of Recursion Encoding). Consider the recursive process \( P = \mu X.a?(m).a!(m).X \), which is not an HO process. \( P \) can be encoded into HO as follows [19]:

\[
\llbracket P \rrbracket = a?(m).a!(m).\langle \nu s \rangle (V (a, s) \mid s!(V) \cdot 0)
\]

where the value \( V \) is an abstraction that potentially reduces to \( \llbracket P \rrbracket \):

\[
V = \lambda(x_a, y_1, y_i)(z_x).x_a?(m).a!(m).\langle \nu s \rangle (z_x (x_a, s) \mid s!(z_x) \cdot 0)
\]

We compose \( \llbracket P \rrbracket \) with an appropriate client process to illustrate the encoding of recursion:

\[
\llbracket P \rrbracket \mid a!(W).a?(b).R
\]

\[→^2 (\nu s)(V (a, s) \mid s!(V) \cdot 0) \mid R
\]

\[→ (\nu s)(s?(z_x).a?(m).a!(m).\langle \nu s \rangle (z_x (a, s) \mid s!(z_x) \cdot 0) \mid s!(V) \cdot 0) \mid R
\]

\[→ a?(m).a!(m).\langle \nu s \rangle (V (a, s) \mid s!(V) \cdot 0) \mid R = \llbracket P \rrbracket \mid R
\]

where \( R \) is some unspecified process such that \( a \in \text{rn}(R) \). We now analyze \( \mathcal{D}(\llbracket P \rrbracket) \) and its reduction chain. By Def. 3.5, we have \( \llbracket P \rrbracket = 7 \), and \( |V| = 0 \). Then, we choose \( k = 1 \) and observe that \( \sigma = \{a_1(\overline{V})/a_2\} \). Following Def. 3.25, we get:

\[
\mathcal{D}(\llbracket P \rrbracket) = (\nu c_1, \ldots, c_7)(\nu c^a)(c^a?(b).b(a_1, a_2) \mid \overline{c_1(\overline{V})} \cdot 0 \mid B_1^0(\llbracket P \rrbracket)\sigma)
\]

\[
B_1^0(\llbracket P \rrbracket) = c_1()\cdot c^a!(\lambda(z_1, z_2).z_1?(m).\overline{x_1(\overline{V})} \cdot 0 \mid c^a!(b)(z_1, z_2))\cdot 0
\]

\[\mid c_2(m).c^a!(\lambda(z_1, z_2).z_2!(m).\overline{c_2(\overline{V})} \cdot 0 \mid c^a!(b)(z_1, z_2))\cdot 0
\]

\[\mid (\nu s_1)(c_3()\cdot \overline{x_1(\overline{V})} \cdot 0 \mid c_3()\cdot \overline{c_2(\overline{V})} \cdot 0 \mid \lambda(z_1, z_2).\llbracket V \rrbracket (z_1, z_2, s_1))\cdot 0
\]

\[\mid c_4()\cdot \overline{s_1(\overline{V})} \cdot 0 \mid c_7()\cdot 0
\]

The decomposition relies twice on the breakdown of value \( V \), so we give \( \llbracket V \rrbracket \) here for arbitrary \( |Q| = 7 \). For this, we observe that \( V \) is an abstraction of a process \( Q \) with \( |Q| = 7 \).

\[
\llbracket V \rrbracket = \lambda(x_a, x_a, y_1).\langle \nu c_k, \ldots, c_{k+6} \rangle(c^a?(b).b(x_a, x_a) \mid \overline{c_8(\overline{V})} \cdot 0 \mid B_8^0(\llbracket Q \rrbracket)
\]

\[
B_8^0(\llbracket Q \rrbracket) = c_8()\cdot y_1?(z_x)\cdot \overline{x_9(\overline{x_9})} \cdot 0
\]

\[\mid c_{k+1}(z_x).c_9\overline{?}(\lambda(z_1, z_2).z_1?(m).\overline{x_{k+2}(\overline{z_x, m})} \cdot 0 \mid c^a!(b)(z_1, z_2))\cdot 0
\]

\[\mid c_{k+2}(z_x).c_9\overline{?}(\lambda(z_1, z_2).z_2!(m).\overline{x_{k+3}(\overline{z_x})} \cdot 0 \mid c^a!(b)(z_1, z_2))\cdot 0
\]

\[\mid (\nu s_1)(c_{k+3}(z_x)\cdot \overline{x_{k+4}(\overline{z_x})} \cdot 0 \mid c_{k+4}?\overline{z_x} \cdot 0 \mid (\nu s_1)\cdot c_{k+5}(z_x)\cdot \overline{s_9(\overline{z_x})} \cdot 0 \mid c_{k+5}()\cdot 0 \mid c_{k+6}()\cdot 0
\]

We follow the reduction chain on \( \mathcal{D}(\llbracket P \rrbracket) \) until it is ready to mimic the first action with channel \( a \), which is an input. First, \( c_1 \) will synchronize, after which \( c^a \) sends the abstraction
to which then \((a_1, a_2)\) is applied. We obtain 
\[ D[[P]] \rightarrow \nu \nu c_2, c_7, c_8 \ P', \]
where
\[ P' = a_1? \langle m \rangle. \sigma_2\langle m \rangle. c_8? \langle b \rangle. b(a_1, a_2) \]
\[ | c_2? \langle m \rangle. c_8! \langle \lambda(z_1, z_2). z_2! \langle m \rangle. \sigma_2\langle ! \rangle. c_8? \langle b \rangle. b(z_1, z_2) \rangle. 0 \]
\[ | (\nu s_1) (c_3? \langle ! \rangle. \sigma_2\langle ! \rangle. c_8? \langle \lambda(z_1, z_2). \sigma_7\langle V \rangle (z_1, z_2, s_1) \rangle. 0) \]
\[ | c_5? \langle ! \rangle. z_1! \langle V \rangle. \sigma_2\langle ! \rangle. 0 \ | c_7? \langle ! \rangle. 0 \]

Note that this process is awaiting an input on channel \(a_1\), after which \(c_2\) can synchronize with its dual. At that point, \(c_8\) is ready to receive another abstraction that mimics an input on \(a_1\). This strongly suggests a tight operational correspondence between a process \(P\) and its decomposition in the case where \(P\) performs higher-order recursion.

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From Trios to Duos  We can simplify the breakdown functions by replacing trios with duos, i.e., processes with exactly two sequential prefixes. The idea is to transform trios such as \( c_k \langle \bar{x} \rangle . u! (V) . x_{k+1} ! (\bar{y}) \) into the composition of a duo with a control trio:

\[
\begin{align*}
  c_k \langle \bar{x} \rangle . c_{k+1} ! (\{ u! (V) . c_{k+2} ! (\bar{z}) \}) & \mid c_{k+1} ? (b) . (\text{run } b) \\
\end{align*}
\]

The first action is as before; the two remaining prefixes are encapsulated into a thunk. This thunk is sent via a propagator to the control trio that activates it upon reception. This transformation involves an additional propagator, denoted \( c_{k+2} \) above. This requires minor modifications in the definition of the degree function \( | \cdot | \) (cf. Def. 3.5).

In some cases, the breakdown function in §3.2 already produces duos. Breaking down input and output prefixes and parallel composition involves proper trios; following the scheme illustrated by (4), we can define a map \( [[ \cdot ]] \) to transform these trios into duos:

\[
\begin{align*}
  \{ c_k \langle \bar{x} \rangle . u_1 ! (V) . x_{k+1} ! (\bar{z}) \} = c_k \langle \bar{x} \rangle . c_{k+1} ! (\{ u_1 ! (V) . x_{k+2} ! (\bar{z}) \}) & \mid c_{k+1} ? (b) . (\text{run } b) \\
  \{ c_k \langle \bar{x} \rangle . u_1 ! (y) . x_{k+1} ! (\bar{z}) \} = c_k \langle \bar{x} \rangle . x_{k+1} ! (\{ u_1 ! (y) . x_{k+2} ! (\bar{z}) \}) & \mid c_{k+1} ? (b) . (\text{run } b) \\
  \{ c_k \langle \bar{x} \rangle . x_{k+1} ! (\bar{y}) . x_{k+2} ! (\bar{z}) \} = c_k \langle \bar{x} \rangle . x_{k+1} ! (\{ x_{k+2} ! (\bar{y}) . x_{k+2} ! (\bar{z}) \}) & \mid c_{k+1} ? (b) . (\text{run } b) \\
\end{align*}
\]

In the breakdown given in §3.3 there is a proper trio, which can be transformed as follows:

\[
\begin{align*}
  \{ u_i < l_j . u_i , \langle \bar{x} \rangle . x_{i+1} ! (\bar{z}) . \bar{y} \} = u_i < l_j . x_{i+1} ! (\{ u_i ! (\bar{z}) . x_{i+2} ! (\bar{z}) . \bar{y} \}) & \mid c_k ? (b) . (\text{run } b) \\
\end{align*}
\]

Similarly, in the breakdown function extended with recursion (cf. §3.4) there is only one trio pattern, which can be transformed into a duo following the same idea.

From Polyadic to Monadic Communication  Since we consider closed HO processes, we can dispense with polyadic communication in the breakdown function. We can define a monadic decomposition, \( D(P) \), that simplifies Def. 3.8 as follows:

\[
D(P) = (\nu \bar{c})(c_k ? (b) . (\text{run } b) \mid B^k (P \sigma))
\]

where \( k > 0, \bar{c} = (c_k , \ldots , c_{k+|P|-1}) \), and \( \sigma \) is as in Def. 3.8. Process \( c_k ? (b) . (\text{run } b) \) activates a thunk received from \( B^k (\cdot) \), the monadic breakdown function that simplifies the one in Tab. 1 by using only one parameter, namely \( k \):

\[
\begin{align*}
  B^k (u_i ? (x) . Q) & = (\nu c_x)(\tau_{\bar{c}} ! (\{ u_i ? (x) . c_{k+1} ! (b) . (x . u) \}) \mid B^{k+1} (Q \sigma)) \\
  B^k (u_i ! (x) . Q) & = \tau_{\bar{c}} ! (\{ c_x ? (x) . u_i ! (x) . c_{k+1} ! (b) . (\text{run } b) \}) \mid B^{k+1} (Q \sigma) \\
  B^k (u_i ! (V) . Q) & = \tau_{\bar{c}} ! (\{ u_i ! (V_{k+1} (V \sigma)) . c_{k+1} ! (b) . (\text{run } b) \}) \mid B^{k+1} (Q \sigma) \\
  B^k (x . u) & = \tau_{\bar{c}} ! (\{ c_x ? (x) . (x . u) \}) \\
  B^k (V . u) & = \tau_{\bar{c}} ! (\{ V_{k+1} (V) . u \}) \\
  B^k ((\nu s) P') & = (\nu \bar{c}) B^k (P' \sigma) \\
  B^k (Q \mid R) & = \tau_{\bar{c}} ! (\{ c_{k+1} ! (b) . \text{run } b \mid c_{k+1} | Q_{k+1} ? (b) . \text{run } b \}) \mid B^{k+1} (Q) \mid B^{k+1} (Q_{k+1} = R) \\
\end{align*}
\]

Above, \( \sigma \) is as in Tab. 1. \( B^k (\cdot) \) propagates values using thugs and a dedicated propagator \( c_x \) for each variable \( x \). We describe only the definition of \( B^k (u_i ? (x) . Q) \); it illustrates key ideas common to all other cases. It consists of an output of a thunk on \( c_k \) composed in parallel with \( B^{k+1} (Q \sigma) \). The thunk will be activated by a process \( c_k ? (b) . (\text{run } b) \) at the top-level; this activation triggers the input action on \( u_i \), and prepares the activation for the next thunk (exchanged on name \( c_{k+1} \)). Upon reception, such a thunk is activated in
parallel with \( c_x! (x) \), which propagates the value received on \( u_i \). The scope of \( c_x \) is restricted to include input actions on \( c_x \) in \( B^{k+1} (Q \sigma) \); such actions are the first in the thunks present in, e.g., \( B^k (u_i! (x), Q) \). We also need to revise the breakdown function for values \( V^k (\cdot) \). The breakdown functions given in §3.3 and §3.4 (cf. Tables 3 and 4) can be made monadic following similar lines.

These two optimizations can be combined by transforming the trios of the monadic breakdown into duos, following the key idea of the first optimization (cf. (4)).

5 Related Work

Our developments are related to results by Parrow [24], who showed that every process in the untyped, summation-free \( \pi \)-calculus with replication is weakly bisimilar to its decomposition into trios processes (i.e., \( P \approx D(P) \)). We draw inspiration from insights developed in [24], but pursuing different goals in a different technical setting: our decomposition treats processes from a calculus without name-passing but with higher-order concurrency (abstraction-passing), supports labeled choices, and accommodates recursive types. Our goals are different than those in [24] because trios processes are relevant to our work in that they allow us to formally justify minimal session types; however, they are not an end in themselves. Still, we opted to retain the definitional style and terminology for trios from [24], which are elegant and clear.

Our main result connects the typability of a process with that of its decomposition; this is a static guarantee. Based on our examples, we conjecture that the behavioral guarantee given by \( P \approx D(P) \) in [24] holds in our setting too, under an appropriate typed weak bisimilarity. An obstacle here is that known notions of typed bisimilarity for session-typed processes, such as those given by Kouzapas et al. [20], are not adequate: they only relate processes typed under the same typing environments. We need a relaxed equivalence that (i) relates processes typable under different environments (e.g., \( \Delta \) and \( G(\Delta) \)) and (ii) admits that actions along \( s \) from \( P \) can be matched by \( D(P) \) using actions along \( s_k \), for some \( k \) (and vice versa). Defining this notion precisely and studying its properties goes beyond the scope of this paper.

Our approach is broadly related to works that relate session types with other type systems for the \( \pi \)-calculus (cf. [17, 3, 4, 5, 10]). Kobayashi [17] encoded a finite session \( \pi \)-calculus into a \( \pi \)-calculus with linear types with usages (without sequencing); this encoding uses a continuation-passing style to codify a session name using multiple linear channels. Dardha et al. [3, 4] formalize and extend Kobayashi’s approach. They use two separate encodings, one for processes and one for types. The former uses a freshly generated linear name to mimic each session action; this fresh name becomes an additional argument in communications. Polyadicity is thus an essential ingredient in [3, 4], whereas in our work it is convenient but not dispensable (cf. §4). The encoding of types in [3, 4] codifies sequencing in session types by nesting payload types. In contrast, we “slice” the \( n \) actions occurring in a session \( s \) along indexed names \( s_1, \ldots, s_n \) with minimal session types, i.e., slices of the type for \( s \). All in all, an approach based on minimal session types appears simpler than that in [3, 4].

Works by Padovani [23] and Scalas et al. [25] is also related: they rely on [3, 4] to develop verification techniques based on session types for OCaml and Scala programs, respectively.

Gay et al. [10] formalize how to encode a monadic \( \pi \)-calculus, equipped with a finite variant of the binary session types of [9], into a polyadic \( \pi \)-calculus with an instance of the generic process types of [16]. The work of Demangeon and Honda [5] encodes a session \( \pi \)-calculus into a linear/affine \( \pi \)-calculus with subtyping based on choice and selection types. Our developments differ from these previous works in an important respect: we relate two formulations of session types, namely standard session types and minimal session types.
Indeed, while [17, 3, 4, 5, 10] target the relative expressiveness of session-typed process languages, our work emerges as the first study of absolute expressiveness in this context.

Finally, we elaborate further on our choice of \( \text{HO} \) as source language. \( \text{HO} \) is a sub-calculus of \( \text{HO} \pi \), whose basic theory and expressivity were studied by Kouzapas et al. [19, 20] as a hierarchy of session-typed calculi based on relative expressiveness. Our developments enable us to include \( \text{HO} \) with minimal session types within this hierarchy. Still, our approach does not rely on having \( \text{HO} \) as source language, and can be adapted to other typed frameworks based on session types, such as the type discipline for first-order \( \pi \)-calculus processes in [26].

6 Concluding Remarks

Session types are a class of behavioral types for message-passing programs. We presented a decomposition of session-typed processes in [19, 20] using minimal session types, in which there is no sequencing. The decomposition of a process \( P \), denoted \( D(P) \), is a collection of trios processes that trigger each other mimicking its sequencing. We prove that typability of \( P \) using standard session types implies the typability of \( D(P) \) with minimal session types. Our results hold for all session types constructs, including labeled choices and recursive types.

Our contributions can be interpreted in three ways. First, from a foundational standpoint, our study of minimal session types is a conceptual contribution to the theory of behavioral types, in that we precisely identify sequencing as a source of redundancy in all preceding session types theories. As remarked in §1, there are many session types variants, and their expressivity often comes at the price of an involved underlying theory. Our work contributes in the opposite direction, as we identified a simple yet expressive fragment of an already minimal session-typed framework [19, 20], which allows us to justify session types in terms of themselves. Understanding further the underlying theory of minimal session types (e.g., notions such as type-based compatibility) is an exciting direction for future work.

Second, our work can be seen as a new twist on Parrow’s decomposition results in the untyped setting [24]. While Parrow’s work indeed does not consider types, in fairness we must observe that when Parrow’s work appeared (1996) the study of types for the \( \pi \)-calculus was rather incipient (for instance, binary session types appeared in 1998 [12]). That said, we should stress that our results are not merely an extension of Parrow’s with session types, for types in our setting drastically narrow down the range of conceivable decompositions. Also, we exploit features not supported in [24], most notably higher-order concurrency.

Last but not least, from a practical standpoint, we believe that our approach paves a new avenue to the integration of session types in programming languages whose type systems lack sequencing, such as Go. It is natural to envision program analysis tools which, given a message-passing program that should conform to protocols specified as session types, exploit our decomposition as an intermediate step in the verification of communication correctness. Remarkably, our decomposition lends itself naturally to an implementation—in fact, we generated our examples automatically using MISTY, an associated artifact written in Haskell.

References


A Appendix to §3.2

A.1 Auxiliary Results

Remark A.1. We derive polyadic rules for typing HOπ as an expected extension of HO typing rules:

\[
\begin{align*}
\text{PolyVar} & : \quad \Gamma, \tilde{x} : \tilde{U}; \tilde{y} : \tilde{U}; \emptyset \vdash \tilde{x}\tilde{y} : \tilde{U}\tilde{U} \\
\text{PolySess} & : \quad \Gamma ; \tilde{u} : S \vdash \tilde{u} \triangleright S \\
\text{PolyRev} & : \quad \Gamma ; \Lambda_1 ; \Delta, u : S \vdash P \triangleright \circ \quad \Gamma ; \Lambda_2 ; \emptyset \vdash \tilde{x} \triangleright \tilde{U} \\
\text{PolySend} & : \quad \Gamma ; \Lambda_1 ; \Lambda_2 ; (\Delta \setminus u : S), u : !\tilde{U} ; S \vdash u!(\tilde{x}) P \triangleright \circ \\
\text{PolyRec} & : \quad \Gamma ; \delta \in \{\leftarrow \to \} \quad \Gamma ; \Lambda ; \Delta_1 \vdash V \triangleright \tilde{C} \sim \circ \quad \Gamma ; \emptyset ; \Delta_2 \vdash \tilde{u} \triangleright \tilde{C} \\
\text{PolyAbs} & : \quad \Gamma ; \tilde{a} : (\tilde{U}) ; \Lambda ; \Delta \vdash P \\
\text{PolyRes} & : \quad \Gamma ; \Lambda ; \Delta, \tilde{s} : \tilde{S}_1, \tilde{s} : \tilde{S}_2 \vdash P \\
\text{PolyResS} & : \quad \Gamma ; \Lambda ; \Delta \vdash (\nu \tilde{s}) P
\end{align*}
\]

Lemma A.2 (Substitution Lemma [19]). If \( \Gamma ; \Lambda ; \Delta, x : S \vdash P \triangleright \circ \) and \( u \notin \text{dom}(\Gamma, \Lambda, \Delta) \) implies \( \Gamma ; \Lambda ; \Delta, u : S \vdash P[y/x] \triangleright \circ \).

Lemma A.3 (Shared environment weakening). If \( \Gamma ; \Lambda ; \Delta \vdash P \triangleright \circ \) and \( x \notin \text{fv}(P) \) then \( \Gamma \setminus x ; \Lambda ; \Delta \vdash P \triangleright \circ \).

Lemma A.4 (Shared environment strengthening). If \( \Gamma ; \Lambda ; \Delta \vdash P \triangleright \circ \) and \( x \notin \text{fn}(P) \) then \( \Gamma \setminus x ; \Lambda ; \Delta \vdash P \triangleright \circ \).
A.2 Proof of Thm. 3.10

Proof. By mutual induction on the structure of $P$ and $V$. The proof of the output case in Part (1) relies on Parts (2) and (3), whereas the proof of Parts (2) and (3) relies on Part (1). We analyze each part of the theorem separately, following the definition of $B^k_x(\cdot)$ in Tab. 1:

1. By assumption, $\Gamma; \Lambda; \Delta \vdash P$. We consider six cases, depending on the shape of $P$:

   a. Case $P = \text{Nil}$. The only rule that can be applied here is $\text{Nil}$. By inversion of this rule, we have: $\Gamma; \emptyset \vdash \text{Nil}$. We shall then prove the following judgment:

   $\mathcal{G}(\Gamma); \emptyset; \Theta \vdash B^k_x(\emptyset) \triangleright \diamond$

   where $\tilde{x} = \text{fv}(\emptyset) = \emptyset$ and $\Theta = \{c_k : (? \rightarrow \rightarrow \circ) ; \text{end}\}$. By Tab. 1: $B^k_x(\emptyset) = c_k(?).0$. By convention we know that $c_k(?).0$ stands for $c_k(?)(y).0$ with $c_k : (? \rightarrow \circ) ; \text{end}$. The following tree proves this case:

   \[
   \begin{array}{ccc}
   \text{Nil} & \text{End} & \text{Rcv} \\
   \Gamma'; \emptyset; \emptyset \vdash 0 \triangleright \diamond & \text{LVar} & \text{EProm} \\
   \Gamma'; \emptyset; \emptyset \vdash 0 \triangleright \diamond & \text{G(}\Gamma); \emptyset; \Theta \vdash 0 \triangleright \diamond & \end{array}
   \]

   where $\Gamma' = \mathcal{G}(\Gamma)$, $y : \text{end} \rightarrow \circ$. We know $c_k \notin \text{dom}(\Gamma)$ since we use reserved names for propagators channels.

   b. Case $P = u_i.(y).P'$. We distinguish two sub-cases: (i) $u_i \in \text{dom}(\Lambda)$ and (ii) $u_i \in \text{dom}(\Gamma)$. We consider sub-case (i) first. For this case Rule Rcv can be applied:

   $\Gamma; \Lambda; \Delta', u_i : S \vdash P' \triangleright \diamond$

   $\Gamma; \Lambda_1 \setminus \Delta' ; \emptyset \vdash y \triangleright U$

   $\Gamma; \Lambda_2 ; \emptyset \vdash y \triangleright U$

   Let $\tilde{x} = \text{fv}(P)$ and $\tilde{x}' = \text{fv}(P')$. Also, let $\Gamma'_i = \Gamma \setminus \tilde{x}'$ and $\Theta_1$ be a balanced environment such that

   $\text{dom}(\Theta_1) = \{c_{k+1}, \ldots, c_{k+|P'|}\} \cup \{\overline{c_{k+2}}, \ldots, \overline{c_{k+|P'|}}\}$

   and $\Theta_1(c_{k+1}) = ?(M') ; \text{end}$ where $M' = (\mathcal{G}(\Gamma), \mathcal{G}(\Lambda_1))(\tilde{x})$. Then, by IH on the first assumption of (6) we know:

   $\mathcal{G}(\Gamma'_1); \emptyset; \mathcal{G}(\Delta', u_i : S), \Theta_1 \vdash B^{k+1}_y(P') \triangleright \diamond$

   By Def. 3.2 and Def. 3.4 and the second assumption of (6) we have:

   $\mathcal{G}(\Gamma); \mathcal{G}(\Lambda_2); \emptyset \vdash y \triangleright \mathcal{G}(U)$

   (8)

   We define $\Theta = \Theta_1, \Theta'$, where

   $\Theta' = c_k : (? \rightarrow \rightarrow \circ) ; \overline{(M')}; \text{end}$

   with $M = (\mathcal{G}(\Gamma), \mathcal{G}(\Lambda_1 \setminus \Lambda_2))(\tilde{x})$. By Def. 3.5, $|P| = |P'| + 1$ so

   $\text{dom}(\Theta) = \{c_k, \ldots, c_{k+|P|-1}\} \cup \{\overline{c_{k+1}}, \ldots, \overline{c_{k+|P|-1}}\}$

   and $\Theta$ is balanced since $\Theta(c_{k+1})$ dual $\Theta(\overline{c_{k+1}})$ and $\Theta_1$ is balanced. By Tab. 1:

   $B^k_x(u_i.(y).P') = c_k(?)(\tilde{x}), u_i.(y).\overline{c_{k+1}}(\tilde{x}'), 0 \vdash B^{k+1}_y(P' \{u_i+1/u_i\})$
Let $\Gamma_1 = \Gamma \setminus \tilde{x}$. We shall prove the following judgment:

$$G(\Gamma_1 \setminus y) ; \emptyset; G(\Delta', u_i : ?(U) ; S) , \Theta_1 \vdash B_{k+1}^{l_1} (u_i, y). P'$$

The left-hand side component of $B_{k+1}^{l_1} (u_i, y). P'$ is typed using some auxiliary derivations:

$$\begin{align*}
\text{End} & \quad G(\Gamma) ; \emptyset; \overline{\text{Nil}} & \quad \emptyset \vdash \tilde{x} \triangleright M' \\
\text{PolySend} & \quad G(\Gamma) ; G(\Lambda_1), G(\Delta_2) ; \overline{\text{c}_{k+1}} \vdash \text{t}(M') & \quad \text{end} \quad \overline{\text{c}_{k+1}} (\tilde{x}') . \emptyset \triangleright \circ \\
\text{End} & \quad G(\Gamma) ; G(\Lambda_1), G(\Delta_2) ; \overline{\text{c}_{k+1}} \vdash \text{t}(M') & \quad \text{end} \quad u_i : \text{end} \quad \overline{\text{c}_{k+1}} (\tilde{x}') . \emptyset \triangleright \circ
\end{align*}$$

(9)

$$\begin{align*}
\text{Rcv} & \quad G(\Gamma) ; G(\Lambda_1), G(\Delta_2) ; u_i : ?(U) ; \Theta \vdash \overline{\text{c}}_{k+1} \vdash \text{t}(\tilde{x}') . \emptyset \triangleright \circ \\
\text{End} & \quad G(\Gamma) ; G(\Lambda_1), G(\Delta_2) ; u_i : ?(U) ; \Theta \vdash \overline{\text{c}}_{k+1} \vdash \text{t}(\tilde{x}') . \emptyset \triangleright \circ
\end{align*}$$

(10)

$$\begin{align*}
\text{PolyRcv} & \quad G(\Gamma) ; G(\Lambda_1), G(\Delta_2) ; \emptyset \vdash \tilde{x} \triangleright M \\
& \quad G(\Gamma_1 \setminus y) ; \emptyset; u_i : ?(U) ; \Theta' \vdash \overline{\text{c}}_k \vdash \text{t}(\tilde{x}) . \emptyset \triangleright \circ
\end{align*}$$

(11)

The following tree proves this case:

$$\begin{align*}
\text{(Lem. A.2) with } \overline{\text{t}}/\overline{\text{u}} & \quad (7) \\
\text{Par} & \quad G(\Gamma_1 \setminus y) ; \emptyset; G(\Delta', u_{i+1} : S) , \Theta_1 \vdash B_{k+1}^{l_1} (P' \{ u_{i+1} / u_i \}) \triangleright \circ \\
& \quad G(\Delta', u_{i+1} : S) \{ \overline{\text{t}}/\overline{\text{u}} \} = G(\Delta', u_{i+1} : S) \\
& \quad B_{k+1}^{l_1} (P' \{ u_{i+1} / u_i \}) \{ \overline{\text{t}}/\overline{\text{u}} \} = B_{k+1}^{l_1} (P' \{ u_{i+1} / u_i \})
\end{align*}$$

(12)

where $\overline{u} = (u_{i+1}, \ldots, u_{i+|S|})$ and $\overline{u}_i = (u_{i}, \ldots, u_{i+|S_i|-1})$. We may notice that if $y \in \text{fv}(P')$ then $\Gamma' = \Gamma \setminus \overline{y}$. On the other hand, when $y \notin \text{fv}(P')$ then $\Gamma' = \Gamma$ so we need to apply Lem. A.4 with $y$ after Lem. A.2 to (7) in (12). Note that we have used the following for the right assumption of (12):

$$G(\Delta', u_{i+1} : S) \{ \overline{\text{t}}/\overline{\text{u}} \} = G(\Delta', u_{i+1} : S)$$

$$B_{k+1}^{l_1} (P' \{ u_{i+1} / u_i \}) \{ \overline{\text{t}}/\overline{\text{u}} \} = B_{k+1}^{l_1} (P' \{ u_{i+1} / u_i \})$$

This concludes sub-case (i). We now consider sub-case (ii), i.e., $u_i \in \text{dom}(\Gamma)$. Here Rule Acc can be applied:

$$\text{Acc} \quad \Gamma ; \emptyset; \vdash u_i \triangleright U \quad \Gamma ; \Lambda_1 ; \Delta \vdash P' \triangleright \circ \quad \Gamma ; \Lambda_2 ; \emptyset \vdash y \triangleright U$$

(13)

Let $\tilde{x} = \text{fv}(P)$ and $\tilde{x}' = \text{fv}(P')$. Furthermore, let $\Theta_1$, $\Theta$, $\Gamma_1$, and $\Gamma_1'$ be defined as in sub-case (i). By IH on the second assumption of (13) we have:

$$G(\Gamma_1) ; \emptyset; G(\Delta) , \Theta_1 \vdash B_{k+1}^{l_1} (P') \triangleright \circ$$

(14)
By Def. 3.2 and Def. 3.4 and the first assumption of (13) we have:
\[ G(\Gamma); \emptyset; \emptyset \vdash u_i \triangleright \{G(U)\} \]
(15)

By Def. 3.2, Def. 3.4, and the third assumption of (13) we have:
\[ G(\Gamma); G(\Lambda_2); \emptyset \vdash y \triangleright G(U) \]
(16)

By Tab. 1, we have:
\[ B^k_2(u_i?(y).P') = c_k?(x).u_i?(y).x_{k+1}!(\overline{x}').0 \mid B^{k+1}_{2'}(P'\{u_i+1/u_i\}) \]
(17)

We shall prove the following judgment:
\[ G(\Gamma_1 \setminus y); \emptyset; G(\Delta), \Theta \vdash B^k_2(u_i?(y).P') \triangleright \circ \]
(18)

To this end, we use some auxiliary derivations:
\[
\begin{align*}
\text{End} & \qquad \frac{G(\Gamma); \emptyset; \emptyset \vdash 0 \triangleright \circ \quad \text{PolyVar} \quad \frac{G(\Gamma); G(\Lambda_1); \emptyset \vdash x_i \triangleright M'}{G(\Gamma); G(\Lambda_1); \emptyset \vdash x_i \triangleright M'} \\
\text{PolySend} & \qquad \frac{\emptyset \vdash 0 \triangleright \circ \quad \text{End} \quad \frac{G(\Gamma); G(\Lambda_1); \emptyset \vdash x_i \triangleright M'}{G(\Gamma)\setminus y; G(\Lambda_1 \setminus \Lambda_2); \emptyset \vdash x_i \triangleright M'} \\
\text{PolyRev} & \qquad \frac{G(\Gamma)\setminus y; G(\Lambda_1 \setminus \Lambda_2); \emptyset \vdash x_i \triangleright M'}{G(\Gamma)\setminus y; G(\Lambda_1 \setminus \Lambda_2); \emptyset \vdash x_i \triangleright M'} \\
\text{End} & \qquad \frac{G(\Gamma)\setminus y; G(\Lambda_1 \setminus \Lambda_2); \emptyset \vdash x_i \triangleright M'}{G(\Gamma)\setminus y; G(\Lambda_1 \setminus \Lambda_2); \emptyset \vdash x_i \triangleright M'} \\
\text{Acc} & \quad \frac{G(\Gamma)\setminus y; G(\Lambda_1 \setminus \Lambda_2); \emptyset \vdash x_i \triangleright M'}{G(\Gamma)\setminus y; G(\Lambda_1 \setminus \Lambda_2); \emptyset \vdash x_i \triangleright M'}
\end{align*}
\]
(19)

The following tree proves this sub-case:
\[
\begin{align*}
\text{Par} & \quad \frac{G(\Gamma_1 \setminus y); \emptyset; G(\Delta), \Theta \vdash x_i?.(x).u_i?.(y).x_{k+1}!(\overline{x}').0 \mid B^{k+1}_{2'}(P') \triangleright \circ}{\Gamma_1 \setminus y; \emptyset; G(\Delta), \Theta \vdash x_i?.(x).u_i?.(y).x_{k+1}!(\overline{x}').0 \mid B^{k+1}_{2'}(P') \triangleright \circ}
\end{align*}
\]
(20)

As in sub-case (i), we may notice that if \( y \not\in \text{fv}(P') \) then \( \Gamma_i' = \Gamma_1 \setminus y \). On the other hand, if \( y \in \text{fv}(P') \) then \( \Gamma_i' = \Gamma_1 \setminus y \), so we need to apply Lem. A4 with \( y \) to (14) in (22).

This concludes the analysis for the input case \( P = u_i!(V).P' \).

c. Case \( P = u_i!(V).P' \). We distinguish two sub-cases: (i) \( u_i \in \text{dom}(\Delta) \) and (ii) \( u_i \in \text{dom}(\Gamma) \). We consider sub-case (i) first. For this case Rule SEND can be applied:

\[
\begin{align*}
\text{Send} & \quad \frac{G(\Gamma_1 \setminus y); \emptyset; G(\Delta), \Theta \vdash c_k?.(x).u_i?.(y).x_{k+1}!(\overline{x}').0 \mid B^{k+1}_{2'}(P') \triangleright \circ}{\Gamma_1 \setminus y; \emptyset; G(\Delta), \Theta \vdash c_k?.(x).u_i?.(y).x_{k+1}!(\overline{x}').0 \mid B^{k+1}_{2'}(P') \triangleright \circ}
\end{align*}
\]
(21)

Let \( \overline{z} = \text{fv}(P') \) and \( l = |V| \). Also, let \( \Gamma_i' = \Gamma_1 \setminus \overline{z} \) and \( \Theta_1 \) be a balanced environment such that
\[
\text{dom}(\Theta_1) = \{c_{k+l+1}, \ldots, c_{k+l+|P'|}\} \cup \{c_{k+l+1}, \ldots, c_{k+l+|P'|+1}\}
\]

and \( \Theta_1(c_{k+l+1}) = ?(M_1) \); \text{end} where \( M_1 = (G(\Gamma), G(\Lambda_1))(\overline{z}) \).

Then, by IH on the first assumption of (23) we have:
\[
G(\Gamma_1'); \emptyset; G(\Delta_1), \Theta_1 \vdash B^{k+l+1}_{2'}(P') \triangleright \circ
\]
(24)
Let $\bar{y} = \text{fv}(V)$ and $\Gamma_2' = \Gamma \setminus \bar{y}$. There are two cases: $U = C \rightarrow \emptyset$ or $U = C \rightarrow \circ$. We consider the first case. If $U = C \rightarrow \emptyset$ then let $\Theta_2$ be a balanced environment such that

$$\text{dom}(\Theta_2) = \{c_{k+1}, \ldots, c_{k+|V|}\} \cup \{\ell_k, \ldots, \ell_{k+|V|}\}$$

$\Theta_2(c_{k+1}) = ?(\tilde{M}_2); \text{end}$, and $\Theta_2(c_{k+l}) = !(\tilde{M}_2); \text{end}$ where $\tilde{M}_2 = (G(\Gamma), G(\Lambda_2))$. Then, by IH (Part 2) on the second assumption of (23) we have:

$$G(\Gamma); G(\Lambda_2); G(\Delta_2) \vdash V_g^{k+1}(V) \triangleright G(U)$$

(25)

We comment the second case for $U$. We may notice that if $U = C \rightarrow \circ$ we can define $\Theta_2 = \emptyset$ and apply the IH (Part 3) to the second assumption to reach (25) with $\Lambda_2 = \emptyset$ and $\Delta_2 = \emptyset$.

Let $\tilde{x} = \text{fv}(P)$. We define $\Theta = \Theta_1, \Theta_2, \Theta'$, where:

$$\Theta' = c_k : ?(\tilde{M}); \text{end}, c_{k+l+1} : !(\tilde{M}); \text{end}$$

with $\tilde{M} = (G(\Gamma), G(\Lambda_1, \Lambda_2))$. By Def. 3.5, we know $|P| = |V| + |P'| + 1$, so

$$\text{dom}(\Theta) = \{c_k, \ldots, c_{k+|P'-1|}\} \cup \{\ell_{k+1}, \ldots, \ell_{k+|P|-1}\}$$

By construction $\Theta$ is balanced since $\Theta(c_{k+l+1})$ dual $\Theta(\ell_{k+l+1})$ and $\Theta_1$ and $\Theta_2$ are balanced. By Tab. 1, we have:

$$B^k_x(u_l!\langle V \rangle.P') = c_k?(\tilde{x}), u_l!(V_g^{k+1}(V\{u_{l+1}/u_l\})) \triangleright c_{k+l+1}(\tilde{z}), \emptyset \triangleright B^{k+l+1}_x(u_l!\langle V \rangle.P') \triangleright \emptyset$$

(26)

We know $\text{fv}(P') \subseteq \text{fv}(P)$ and $\text{fv}(V) \subseteq \text{fv}(P)$ that is $\tilde{z} \subseteq \tilde{x}$ and $\tilde{y} \subseteq \tilde{x}$. Let $\Gamma_1 = \Gamma \setminus \tilde{x}$. We shall prove the following judgment:

$$G(\Gamma_1); \emptyset; G(((\Delta_1, \Delta_2) \setminus \{u_i : S\}), u_i : !(U); S), \emptyset \vdash B^k_x(u_l!\langle V \rangle.P') \triangleright \emptyset$$

(27)

Let $\sigma = \{u_{l+1}/u_l\}$. To type the left-hand side component of $B^k_x(u_l!\langle V \rangle.P')$ we use some auxiliary derivations:

$$G(\Gamma); \emptyset; G(\Lambda_1); \emptyset \vdash \emptyset \triangleright \emptyset \triangleright \emptyset$$

(28)

(29)
We consider sub-case (ii). For this sub-case Rule Req can be applied:

\[ \text{Req} : \Gamma; \emptyset \vdash u : (U) \quad \Gamma; \Lambda; \Delta_1 \vdash P' \triangleright \circ \quad \Gamma; \emptyset; \Delta_2 \vdash V \triangleright U \]

Let \( \tilde{z} = \text{fv}(P') \) and \( l = |V| \). Further, let \( \Gamma'_1 = \Gamma \setminus \tilde{z} \) and let \( \Theta_1 \) and \( \Theta_2 \) be environments defined as in sub-case (i).

By IH on the second assumption of (32) we have:

\[ \mathcal{G}(\Gamma'_1); \emptyset; \mathcal{G}(\Delta_1), \Theta_1 \vdash B^k_{\tilde{x}}(P') \triangleright \circ \]

Let \( \tilde{y} = \text{fv}(V) \). By IH on the second assumption of (23) we have:

\[ \mathcal{G}(\Gamma); \emptyset; \mathcal{G}(\Delta_2), \Theta_2 \vdash V^k_{\tilde{y}}(V) \triangleright \mathcal{G}(U) \]

Let \( \tilde{x} = \text{fv}(P) \) and \( \Gamma_1 = \Gamma \setminus \tilde{x} \). We define \( \Theta = \Theta_1, \Theta_2, \Theta' \), where:

\[ \Theta' = c_k : (?M); \text{end}, c_{k+1} : (?M); \text{end} \]

with \( \tilde{M} = (\mathcal{G}(\Gamma), \mathcal{G}(\Lambda))(\tilde{x}) \). By Def. 3.5, we know \(|P| = |V| + |P'| + 1\), so

\[ \text{dom}(\Theta) = (c_k, \ldots, c_{k+|P|-1}) \cup (c_{k+1}, \ldots, c_{k+|P'|-1}) \]

By construction \( \Theta \) is balanced since \( \Theta(c_{k+|P|+1}) \) and \( \Theta_1 \) and \( \Theta_2 \) are balanced. By Tab. 1, we have:

\[ B^k_{\tilde{x}}(u_i!(V), P') = c_k ?(\tilde{x}), u_i!(V^k_{\tilde{y}}(V)): \tilde{x}_{k+|P'|+1}(\tilde{x}) \circ B^k_{\tilde{x}}(P') \]

We know \( \text{fv}(P') \subseteq \text{fv}(P) \) and \( \text{fv}(V) \subseteq \text{fv}(P) \) that is \( \tilde{z} \subseteq \tilde{x} \) and \( \tilde{y} \subseteq \tilde{x} \).

To prove that \( \mathcal{G}(\Gamma_1); \emptyset; \mathcal{G}(\Delta_1, \Delta_2), \Theta \vdash B^k_{\tilde{x}}(u_i!(V), P') \), we use some auxiliary derivations:

\begin{align*}
\text{End} & : \mathcal{G}(\Gamma); \emptyset; \circ \quad \text{PolySend} : \mathcal{G}(\Gamma); \emptyset; \circ \quad \text{PolyVar} : \mathcal{G}(\Gamma); \emptyset; \circ \quad \text{End} \quad \text{PolySend} \quad \text{PolyVar} \\
\text{Nil} & : \mathcal{G}(\Gamma); \emptyset; \circ \quad \text{End} : \mathcal{G}(\Gamma); \emptyset; \circ \quad \text{PolyVar} : \mathcal{G}(\Gamma); \emptyset; \circ \\
\text{End} & : \mathcal{G}(\Gamma); \emptyset; \circ \quad \text{PolySend} : \mathcal{G}(\Gamma); \emptyset; \circ \quad \text{PolyVar} : \mathcal{G}(\Gamma); \emptyset; \circ \\
\end{align*}

\[ \mathcal{G}(\Gamma); \emptyset; \circ \quad \text{End} : \mathcal{G}(\Gamma); \emptyset; \circ \quad \text{PolyVar} : \mathcal{G}(\Gamma); \emptyset; \circ \]

\[ \mathcal{G}(\Gamma); \emptyset; \circ \quad \text{End} : \mathcal{G}(\Gamma); \emptyset; \circ \quad \text{PolyVar} : \mathcal{G}(\Gamma); \emptyset; \circ \]
The following tree proves this case:

\[
\begin{array}{c}
\text{PolyRev} & \text{PolyVar} & \text{Par} \\
\hline
(36) & \mathcal{G}(\Gamma); \mathcal{G}(\Lambda); \emptyset \vdash \vec{x} \triangleright M \\
\hline
(37) & \mathcal{G}(\Gamma_1); \emptyset; \mathcal{G}(\Delta_2), \Theta_2, \Theta' \vdash c_k ?(\vec{x}).u_i !(V_y^{k+1}(V)).c_{k+1}!_{M}(\vec{x}).\Theta \triangleright \circ \\
\hline
(38) & \mathcal{G}(\Gamma_1); \emptyset; \mathcal{G}(\Delta_1), \Theta_1 \vdash B_2^k(u_i !(V).P') \triangleright \circ \\
\end{array}
\]

This concludes the analysis for the output case \( P = u_i !(V).P' \). We remark that the proof for the case when \( V = y \) is specialization of above the proof where \( l = |y| = 0, \tilde{y} = f\nu(y) = y, V_y^{k+1}(y) = y \) and it holds that \( y\sigma = y \).

d. Case \( P = V u_i \). For this case only Rule \textit{App} can be applied:

\[
\begin{array}{c}
\text{App} \\
\hline
\longrightarrow \in \{-\circ, \rightarrow\} \\
\hline
\Gamma; \Lambda; \Delta_1 \vdash V \triangleright C \rightarrow \circ \quad \Gamma; \emptyset; \Delta_2 \vdash u_i \triangleright C \\
\hline
\text{App} \\
\hline
\end{array}
\]

\[
(39) \quad \Gamma; \Lambda; \Delta_1, \Delta_2 \vdash V u_i \triangleright \circ
\]

We distinguish two sub-cases based on the higher-order type: \( i \rightarrow = \circ \) or \( i \rightarrow = \rightarrow \).

We consider sub-case \( i \) first. Let \( \tilde{x} = f\nu(V) \) and let \( \Theta_1 \) be a balanced environment such that

\[
\text{dom}(\Theta_1) = \{c_{k+1}, \ldots, c_{k+|V|}\} \cup \{e_{k+1}, \ldots, e_{k+|V|}\}
\]

and \( \Theta_1(c_{k+1}) = \nu.(\tilde{M}); \text{end} \) and \( \Theta_1(e_{k+1}) = !.(\tilde{M}); \text{end} \) where \( \tilde{M} = (\mathcal{G}(\Gamma), \mathcal{G}(\Lambda))(\tilde{x}) \).

Then, by IH (Part 2) on the second assumption of (39) we have:

\[
\mathcal{G}(\Gamma); \mathcal{G}(\Lambda); \mathcal{G}(\Delta_1), \Theta_1 \vdash V_{\tilde{x}}^{k+1}(V) \triangleright \mathcal{G}(U)
\]

By Def. 3.2 and Def. 3.4 and (39) we have:

\[
\mathcal{G}(\Gamma); \emptyset; \mathcal{G}(\Delta_2) \vdash \bar{m} \triangleright \mathcal{G}(C)
\]

\[
(41) \quad \mathcal{G}(\Gamma); \emptyset; \mathcal{G}(\Delta_2) \vdash \bar{m} \triangleright \mathcal{G}(C)
\]

where \( \bar{m} = (u_i, \ldots, u_i + |\mathcal{G}(C)| = 1) \). We define \( \Theta = \Theta_1, c_k :?(\tilde{M}); \text{end} \). By Def. 3.5, \(|P| = |V| + 1 \) so \( \text{dom}(\Theta) = \{c_k, \ldots, c_{k+|P|-1}\} \cup \{e_{k+1}, \ldots, e_{k+|P|-1}\} \). By construction \( \Theta \) is balanced since \( \Theta_1 \) is balanced.

By Tab. 1, we have:

\[
B_{\tilde{x}}^k(V u_i) = c_k ?(\vec{x}).V_{\tilde{x}}^{k+1}(V) \bar{m}
\]

\[
(42) \quad B_{\tilde{x}}^k(V u_i) = c_k ?(\vec{x}).V_{\tilde{x}}^{k+1}(V) \bar{m}
\]

We shall prove the following judgment:

\[
\mathcal{G}(\Gamma_1); \emptyset; \mathcal{G}(\Delta_1), \Delta_2, \Theta \vdash c_k ?(\vec{x}).V_{\tilde{x}}^{k+1}(V) \bar{m} \triangleright \circ
\]

\[
(43) \quad \mathcal{G}(\Gamma_1); \emptyset; \mathcal{G}(\Delta_1), \Delta_2, \Theta \vdash c_k ?(\vec{x}).V_{\tilde{x}}^{k+1}(V) \bar{m} \triangleright \circ
\]

We use auxiliary derivation:

\[
\begin{array}{c}
\text{PolyApp} \\
\hline
(40) & (41) \\
\hline
\mathcal{G}(\Gamma); \mathcal{G}(\Lambda); \mathcal{G}(\Delta_1), \Delta_2, \Theta \vdash V_{\tilde{x}}^{k+1}(V) \bar{m} \triangleright \circ
\end{array}
\]

The following tree proves this case:
In applying (40) and (41) we may notice that by Def. 3.2: $G(U) = G(C) \rightarrow \circ$. This concludes sub-case (i).

We now consider sub-case (ii). For this case we know that $\Lambda = \emptyset$ and $\Delta_1 = \emptyset$ in (39). Let $\tilde{x} = f \nu (V)$. Then, by IH (Part 3) on the second assumption of (39) we have:

$$G(\Gamma); \emptyset; \nu \vdash V^{k+1}_V(V) \triangleright G(U)$$

By Def. 3.2, Def. 3.4, and (39) we have:

$$G(\Gamma); \emptyset; G(\Delta_2) \vdash \tilde{m} \triangleright G(C)$$

where $\tilde{m} = (u_1, \ldots, u_i; G(C) - 1)$. By Tab. 1, we have:

$$G^{k+1}_V(V u_i) = c_k \nu (\tilde{x}). V^k_\Sigma(V) \tilde{m}$$

We define $\Theta = c_k \nu (\tilde{M})$; end with $\tilde{M} = G(\Gamma)(\tilde{x})$.

We shall prove the following judgment:

$$G(\Gamma_1); \emptyset; G(\Delta_2), \Theta \vdash c_k \nu (\tilde{x}). V^k_\Sigma(V) \tilde{m} \triangleright \circ$$

The following tree proves this case:

$$\frac{G(\Gamma); \emptyset; \nu \vdash V^{k+1}_V(V) \triangleright G(U)}{\text{PolyApp}} \quad \frac{G(\Gamma); \emptyset; \nu \vdash V^{k+1}_V(V) \triangleright G(U)}{\text{PolyRecv}} \quad \frac{G(\Gamma); \emptyset; \nu \vdash V^{k+1}_V(V) \triangleright G(U)}{\text{PolyVar}}$$

In applying (46) and (41) we may notice that by Def. 3.2: $G(U) = G(C) \rightarrow \circ$. We remark that the proof for the case when $r = |y| = 0$, $\tilde{x} = f \nu (y) = y$, $V^{k+1}_\Sigma(y) = y$ and it holds that $y \sigma = y$.

**Case** $P = (\nu s : C) P'$. We distinguish two sub-cases: (i) $C = S$ and (ii) $C = (U)$.

Firstly, we $\alpha$-convert $P$ as follows:

$$P \equiv_{\alpha} (\nu s_1 : C) P' \{s_1 \Sigma / s\Sigma\}$$

We consider sub-case (i) first. For this case Rule ResS can be applied:

$$\frac{\text{ResS} \quad \Gamma; \Lambda \vdash \Delta, s_1 : S, \Sigma \vdash P' \{s_1 \Sigma / s\Sigma\} \triangleright \circ}{\Gamma; \Lambda \vdash (\nu s_1 : S) P' \{s_1 \Sigma / s\Sigma\} \triangleright \circ}$$

Let $\tilde{x} = f \nu (P')$ and let $\Theta_1$ be a balanced environment such that

$$\text{dom}(\Theta_1) = \{c_k, \ldots, c_k + |P| - 1\} \cup \{c_{k+1}, \ldots, c_{k+|P| - 1}\}$$
and $\Theta_1(c_k) = \langle \overrightarrow{M} \rangle$; end with $\overrightarrow{M} = (\mathcal{G}(\Gamma), \mathcal{G}(\Lambda))(\overrightarrow{x})$. Then, by IH on the assumption of (51) we have:

$$\mathcal{G}(\Gamma); \emptyset; \mathcal{G}(\Delta, s_1 : S, \overrightarrow{s_1} : \overrightarrow{S}), \Theta_1 \vdash \text{B}^R_{\overrightarrow{s}^2}(P'\{s_1 \overrightarrow{s}/\overrightarrow{S}\}) \triangleright$$

Note that we take $\Theta = \Theta_1$ since $fv(P) = fv(P')$ and $|P| = |P'|$. By Def. 3.2 and Def. 3.4 and (56), we know that:

$$\mathcal{G}(\Gamma); \emptyset; \mathcal{G}(\Delta, \overrightarrow{s} : \mathcal{G}(S), \overrightarrow{s} : \mathcal{G}(\overrightarrow{S})), \Theta_1 \vdash \text{B}^R_{\overrightarrow{s}}(P'\{s_1 \overrightarrow{s}/\overrightarrow{S}\}) \triangleright$$

where $\overrightarrow{s} = (s_1, \ldots, s_{|\mathcal{G}(S)|})$ and $\overrightarrow{s} = (\overrightarrow{s_1}, \ldots, \overrightarrow{s}_{|\mathcal{G}(S)|})$. By Tab. 1, we have:

$\text{B}^\ell_{\overrightarrow{s}}((\nu s)P') = (\nu \overrightarrow{s} : \mathcal{G}(S))\text{B}^\ell_{\overrightarrow{s}}(P'\{s_1 \overrightarrow{s}/\overrightarrow{S}\})$

The following tree proves this sub-case:

$$\text{PolyResS} \quad \mathcal{G}(\Gamma); \emptyset; \mathcal{G}(\Delta) \vdash (\nu \overrightarrow{s} : \mathcal{G}(S))\text{B}^\ell_{\overrightarrow{s}}(P'\{s_1 \overrightarrow{s}/\overrightarrow{S}\}) \triangleright$$

We now consider sub-case (ii). Similarly to sub-case (i) we first $\alpha$-convert $P$ as follows:

$$P \equiv_\alpha (\nu s_1)P'\{s_1/s\}$$

For this sub-case Rule Res can be applied:

$$\begin{align*}
\text{Res} & \quad \Gamma, s_1 : \langle U \rangle; \Delta; \vdash P'\{s_1/s\} \triangleright \\
& \quad \Gamma; \Delta; \vdash (\nu s_1)P'\{s_1/s\} \triangleright
\end{align*}$$

Let $\overrightarrow{x} = fv(P')$ and let $\Theta_1$ be defined as in sub-case (i).

By IH on the first assumption of (55) we have:

$$\mathcal{G}(\Gamma, s_1 : \langle U \rangle); \emptyset; \mathcal{G}(\Delta), \Theta_1 \vdash \text{B}^R_{\overrightarrow{s}}(P'\{s_1/s\}) \triangleright$$

Here we also take $\Theta = \Theta_1$ since $fv(P) = fv(P')$ and $|P| = |P'|$. We notice that by Def. 3.2 and Def. 3.4 and (56):

$$\mathcal{G}(\Gamma, s_1 : \mathcal{G}(\langle U \rangle)); \emptyset; \mathcal{G}(\Delta), \Theta_1 \vdash \text{B}^R_{\overrightarrow{s}}(P'\{s_1/s\}) \triangleright$$

By Tab. 1, we have:

$\text{B}^\ell_{\overrightarrow{s}}((\nu s)P') = (\nu s_1 : \mathcal{G}(\langle U \rangle))\text{B}^\ell_{\overrightarrow{s}}(P'\{s_1/s\})$

where $\overrightarrow{s} = s_1$ since $|\mathcal{G}(\langle U \rangle)| = 1$. The following tree proves this sub-case:

$$\begin{align*}
\text{Res} & \quad \mathcal{G}(\Gamma); \emptyset; \mathcal{G}(\Delta), \Theta \vdash (\nu s_1 : \mathcal{G}(\langle U \rangle))\text{B}^\ell_{\overrightarrow{s}}(P'\{s_1/s\}) \triangleright
\end{align*}$$

f. Case $P = Q \mid R$. For this case only Rule Par can be applied:

$$\begin{align*}
\text{Par} & \quad \Gamma; \Lambda_1; \Delta_1 \vdash Q \triangleright \\
& \quad \Gamma; \Lambda_2; \Delta_2 \vdash R \triangleright \\
& \quad \Gamma; \Lambda_1, \Lambda_2; \Delta_1, \Delta_2 \vdash Q \mid R \triangleright
\end{align*}$$

Let $\overrightarrow{y} = fv(Q)$ and let $\Theta_1$ be a balanced environment such that

$$\text{dom}(\Theta_1) = \{c_{k+1}, \ldots, c_{k+|Q|}\} \cup \{c_{k+2}, \ldots, c_{k+|Q|}\}$$
and \( \Theta_1(c_{k+1}) = \pi(M_1) \); end with \( M_1 = (G(\Gamma), G(\Lambda_1))(\vec{y}) \). Let \( \Gamma_1 = \Gamma \setminus \vec{y} \). Then, by IH on the first assumption of (59) we have:

\[
G(\Gamma_1) ; \emptyset; G(\Delta_1), \Theta_1 \vdash B^{k+1}_y(Q) > \oslash
\]

(60)

Let \( \vec{z} = f_v(R) \) and \( l = |Q| \). Also, let \( \Theta_2 \) be a balanced environment such that

\[
\text{dom}(\Theta_2) = \{c_0, c_1, \ldots, c_{k+l+|R|} \} \cup \{c_{k+l+2}, \ldots, c_{k+l+|R|} \}
\]

and \( \Theta_2(c_{k+l+1}) = \pi(M_2) \); end with \( M_2 = (G(\Gamma), G(\Lambda_2))(\vec{z}) \).

Let \( \Gamma_2 = \Gamma \setminus \vec{z} \). Then, by IH on the second assumption of (59) we have:

\[
G(\Gamma_2) ; \emptyset; G(\Delta_2), \Theta_2 \vdash B^{k+1}_z(R) > \oslash
\]

(61)

Let \( \vec{x} = f_v(P) \) and \( \vec{M} = (G(\Gamma), G(\Lambda_1, \Lambda_2))(\vec{x}) \). We may notice that \( M_i \subseteq \vec{M} \) for \( i \in \{1, 2\} \). We define \( \Theta = \Theta_1, \Theta_2, \Theta' \) where:

\[
\Theta' = c_k : \pi(\vec{M}) \end{end} \Theta, \bar{c}_{k+1} !:\!(\vec{M}_1) ; \end{end} \Theta, \bar{c}_{k+l+1} !:\!(\vec{M}_2) ; \end{end}
\]

By construction \( \Theta \) is balanced since \( \Theta(c_{k+1}) \) dual \( \Theta(\bar{c}_{k+1}) \), \( \Theta(c_{k+l+1}) \) dual \( \Theta(\bar{c}_{k+l+1}) \), and \( \Theta_1 \) and \( \Theta_2 \) are balanced.

By Tab. 1 we have:

\[
B^{k+1}_y(Q \mid R) = c_k ?(\vec{x}) . \bar{c}_{k+l+1} !:\!(\vec{y}) . \bar{c}_{k+l+1} !:\!(\vec{z}) . \emptyset \mid B^{k+1}_y(Q) \mid B^{k+l+1}_z(R)
\]

Let \( \Gamma_1 = \Gamma \setminus \vec{x} \). We shall prove the following judgment:

\[
G(\Gamma_1) ; \emptyset; G(\Lambda_1, \Lambda_2), \Theta \vdash c_k ?(\vec{x}) . \bar{c}_{k+l+1} !:\!(\vec{y}) . \bar{c}_{k+l+1} !:\!(\vec{z}) . \emptyset \mid B^{k+1}_y(Q) \mid B^{k+l+1}_z(R) > \oslash
\]

To type the trio, which is the left-hand side component, we use some auxiliary derivations:

\[
\begin{array}{c}
\text{End} \quad \frac{G(\Gamma) ; \emptyset; \bar{c}_{k+l+1} \end{end} \emptyset \vdash \emptyset}{G(\Gamma) ; \emptyset; \bar{c}_{k+l+1} \end{end} \emptyset \vdash \emptyset} \\
\text{PolySend} \quad \frac{G(\Gamma) ; \emptyset; \bar{c}_{k+l+1} \end{end} \emptyset \vdash \emptyset \oslash \vec{M}_2}{G(\Gamma) ; \emptyset; \bar{c}_{k+l+1} \end{end} \emptyset \vdash \vec{M}_2 \oslash} \\
\text{PolyVar} \quad \frac{G(\Gamma) ; \emptyset; \bar{c}_{k+l+1} \end{end} \emptyset \vdash \emptyset \oslash \vec{M}_2}{G(\Gamma) ; \emptyset; \bar{c}_{k+l+1} \end{end} \emptyset \vdash \emptyset \oslash \vec{M}_2} \\
\text{End} \quad \frac{G(\Gamma) ; \emptyset; \bar{c}_{k+l+1} \end{end} \emptyset \vdash \emptyset \oslash \vec{M}_2}{G(\Gamma) ; \emptyset; \bar{c}_{k+l+1} \end{end} \emptyset \vdash \emptyset \oslash \vec{M}_2} \\
\text{PolyRecv} \quad \frac{G(\Gamma_1) ; \emptyset; \emptyset \vdash \vec{x} \oslash \vec{M}}{G(\Gamma_1) ; \emptyset; \emptyset \vdash \vec{x} \oslash \vec{M}} \\
\text{(Lem. A.4) with } \vec{x} \setminus \vec{y} \quad \frac{G(\Gamma_1) ; \emptyset; G(\Delta_1), \Theta_1 \vdash B^{k+1}_y(Q) > \oslash}{G(\Gamma_1) ; \emptyset; G(\Delta_1), \Theta_1 \vdash B^{k+1}_y(Q) > \oslash}
\end{array}
\]

(62)  (63)  (64)  (65)
3. This is the first case concerning values when $V = y$. By assumption $\Gamma; \Lambda; \Delta \vdash y \triangleright C \rightsquigarrow \circ$. For this case only Rule R_VAR can be applied and by inversion $\Delta = \{ y \triangleright C \rightsquigarrow \circ \}$ and $\Delta = \emptyset$. By Tab. 1 we have $V_b^y(y) = y$ and by Def. 3.2 and Def. 3.4 we have $G(\Delta) = \{ G(C \rightsquigarrow \circ) \}$. Hence, we prove the following judgment by applying Rule R_VAR:

$$G(\Gamma); G(\Delta); \emptyset \vdash V_b^y(y) \triangleright G(C \rightsquigarrow \circ)$$

2. This is the second case concerning values when $V = \lambda y. P$. By assumption we have $\Gamma; \Lambda; \Delta \vdash V \triangleright C \rightsquigarrow \circ$. Here we distinguish two sub-cases (1) $\rightsquigarrow \circ \rightsquigarrow \circ$ and (2) $\rightsquigarrow \circ \rightsquigarrow \circ$.

By assumption $\Gamma; \Lambda; \Delta \vdash V \triangleright C \rightsquigarrow \circ$. In this case Rule R_VAR can be applied. Firstly, we $\alpha$-convert value $V$ as follows:

$$V \equiv \alpha \lambda y_1. P[y_1/y]$$

For this case only Rule R_VAR can be applied:

$$\frac{\text{Abs}}{\Gamma; \Lambda; \Delta_1 \vdash P[y_1/y] \triangleright \circ \quad \Gamma; \emptyset; \Delta_2 \vdash y_1 \triangleright C \quad \Gamma \setminus y_1; \Lambda; \Delta_1 \setminus \Delta_2 \vdash \lambda y_1. P[y_1/y] \triangleright C \rightsquigarrow \circ}$$

Let $\vec{x} = \text{fv}(P)$ and $\Gamma_1 = \Gamma \setminus \vec{x}$. Also, let $\Theta_1$ be a balanced environment such that

$$\text{dom}(\Theta_1) = \{ c_k, \ldots, c_{k+|P|-1} \} \cup \{ c_{k+1}, \ldots, c_{k+|P|-1} \}$$

and $\Theta_1(c_k) = \vec{M}$ with $\vec{M} = (G(\Gamma \setminus y_1), G(\Lambda))(\vec{x})$. Then, by IH (Part 1) on the first assumption of (69) we have:

$$G(\Gamma_1); \emptyset; G(\Delta_1), \Theta_1 \vdash B^k_2(P[y_1/y]) \triangleright \circ$$

By Def. 3.2 and Def. 3.4 and the second assumption of (69) we have:

$$G(\Gamma); \emptyset; G(\Delta_2) \vdash \vec{y} \triangleright G(C)$$

where $\vec{y} = (y_1, \ldots, y_{|G(C)|})$.

We define $\Theta = \Theta_1, \vec{x} : ! (\vec{M})$; end. By Tab. 1, we have:

$$V_b^y(\lambda y_1. P) = \lambda \vec{y} : G(C), \vec{x} : ! (\vec{x}). \emptyset \vdash B^k_2(P[y_1/y])$$
By construction \( \Theta \) is balanced since \( \Theta(c_k) \) dual \( \Theta(\tau_{\pi}) \) and \( \Theta_1 \) is balanced. We use an auxiliary derivation:

\[
\begin{align*}
\text{Nil} & \quad \frac{\not \quad \ast}{\mathcal{G}(\Gamma); \emptyset; \emptyset \vdash \emptyset \triangleright \circ} \\
\text{End} & \quad \frac{\mathcal{G}(\Gamma); \emptyset; c_k \text{ end} \vdash \emptyset \triangleright \circ}{\mathcal{G}(\Gamma); \emptyset \vdash c \triangleright \lambda_k M} \\
\text{PolyVar} & \quad \frac{\mathcal{G}(\Gamma); \emptyset \vdash c \triangleright \lambda_k M}{\mathcal{G}(\Gamma); \emptyset \vdash \overline{c} \triangleright \circ}
\end{align*}
\]

(72)

By construction \( \Theta \) is balanced since \( \Theta(c_k) \) dual \( \Theta(\tau_{\pi}) \) and \( \Theta_1 \) is balanced. We use an auxiliary derivation:

\[
\begin{align*}
\text{Nil} & \quad \frac{\not \quad \ast}{\mathcal{G}(\Gamma); \emptyset; \emptyset \vdash \emptyset \triangleright \circ} \\
\text{End} & \quad \frac{\mathcal{G}(\Gamma); \emptyset; c_k \text{ end} \vdash \emptyset \triangleright \circ}{\mathcal{G}(\Gamma); \emptyset \vdash c \triangleright \lambda_k M} \\
\text{PolyVar} & \quad \frac{\mathcal{G}(\Gamma); \emptyset \vdash c \triangleright \lambda_k M}{\mathcal{G}(\Gamma); \emptyset \vdash \overline{c} \triangleright \circ}
\end{align*}
\]

(72)

\[
\begin{align*}
\text{Par} & \quad \frac{\not \quad \ast}{\mathcal{G}(\Gamma); \emptyset; \mathcal{G}(\Delta_1), \Theta_1 \vdash B_{\pi}^k(P\{y/y\}) \triangleright \circ}
\end{align*}
\]

(73)

The following tree proves this part:

\[
\begin{align*}
\text{Abs} & \quad \frac{\not \quad \ast}{\mathcal{G}(\Gamma \backslash y_1); \mathcal{G}(\Delta), \Theta_1 \vdash B_{\pi}^k(P\{y/y\}) \triangleright \circ}
\end{align*}
\]

(74)

\[
\begin{align*}
\text{Abs} & \quad \frac{\not \quad \ast}{\mathcal{G}(\Gamma \backslash y_1); \mathcal{G}(\Delta), \Theta_1 \vdash B_{\pi}^k(P\{y/y\}) \triangleright \circ}
\end{align*}
\]

(74)

The following tree proves this part:

\[
\begin{align*}
\text{Abs} & \quad \frac{\not \quad \ast}{\mathcal{G}(\Gamma \backslash y_1); \mathcal{G}(\Delta), \Theta_1 \vdash B_{\pi}^k(P\{y/y\}) \triangleright \circ}
\end{align*}
\]

(74)

\[
\begin{align*}
\text{Abs} & \quad \frac{\not \quad \ast}{\mathcal{G}(\Gamma \backslash y_1); \mathcal{G}(\Delta), \Theta_1 \vdash B_{\pi}^k(P\{y/y\}) \triangleright \circ}
\end{align*}
\]

(74)

The following tree proves this part:

\[
\begin{align*}
\text{Abs} & \quad \frac{\not \quad \ast}{\mathcal{G}(\Gamma \backslash y_1); \mathcal{G}(\Delta), \Theta_1 \vdash B_{\pi}^k(P\{y/y\}) \triangleright \circ}
\end{align*}
\]

(74)

The following tree proves this part:

\[
\begin{align*}
\text{Abs} & \quad \frac{\not \quad \ast}{\mathcal{G}(\Gamma \backslash y_1); \mathcal{G}(\Delta), \Theta_1 \vdash B_{\pi}^k(P\{y/y\}) \triangleright \circ}
\end{align*}
\]

(74)

The following tree proves this part:

\[
\begin{align*}
\text{Abs} & \quad \frac{\not \quad \ast}{\mathcal{G}(\Gamma \backslash y_1); \mathcal{G}(\Delta), \Theta_1 \vdash B_{\pi}^k(P\{y/y\}) \triangleright \circ}
\end{align*}
\]

(74)
A.3 Proof of Thm. 3.11

Proof. By assumption, $\Gamma; \emptyset; \Delta \vdash P \triangleright \diamondsuit$. Then, by applying Lem. A.2 we have:

$$\Gamma \sigma; \emptyset; \Delta \sigma \vdash \sigma P \triangleright \diamondsuit \quad (81)$$

By Def. 3.8, we shall prove the following judgment:

$$G(\Gamma \sigma); \emptyset; G(\Delta \sigma) \vdash (\nu \bar{c})(\bar{c}k!)0 | B^k(\sigma P) \triangleright \diamondsuit$$

where $\bar{c} = (c_k, \ldots, c_{k+|P|-1})$ and $k > 0$. Since $P \sigma$ is an initialized process, we apply Thm. 3.10 to (81) to get:

$$G(\Gamma \sigma); \emptyset; G(\Delta \sigma), \Theta \vdash B^k(\sigma P) \triangleright \diamondsuit$$

where $\Theta$ is balanced with $\text{dom}(\Theta) = \{c_k, c_{k+1}, \ldots, c_{k+|P|-1}\} \cup \{\bar{c}k, \ldots, \bar{c}k+k!|P|-1\}$ and $\Theta(c_k) = ?(\cdot)$; end. By assumption, $\nu(P) = \emptyset$.

The following tree concludes the proof:

$\text{Send} \quad \frac{\begin{array}{c} G(\Gamma \sigma); \emptyset; \emptyset \vdash 0 \triangleright \diamondsuit \\ \text{PolyResS} \quad G(\Gamma \sigma); \emptyset; \emptyset \vdash 0 \triangleright \diamondsuit \end{array}}{\text{Par} \quad G(\Gamma \sigma); \emptyset; G(\Delta \sigma), \Theta \vdash B^k(\sigma P) \triangleright \diamondsuit}$

Rule PolyResS can be used: the environment obtained by extending $\Theta$ with $\bar{c}k ! (\cdot)$; end is balanced, and for each $c_j \in \bar{c}$ such that $c_j : S$ there is a $\bar{c}j : T$, with $S$ dual $T$.  

B Appendix to §3.3

Thm. 3.10 holds also for the extension with selection and branching. We now present the additional cases of the proof.

Proof (Extension of Thm. 3.10 with Selection/Branching). The proof is as before. We need to consider two additional cases for Part (1) of the theorem:

1. Case $P = u_i \triangleright \{l_j : P_j\}_{j \in I}$. For this case Rule BRA can be applied:

$$\frac{\forall j \in I \quad \Gamma; \Lambda; \Delta, u_i : S_j \vdash P_j \triangleright \diamondsuit}{\Gamma; \Lambda; \Delta, u_i : \& \{l_j : S_j\}_{j \in I} \vdash u_i \triangleright \{l_j : P_j\}_{j \in I} \triangleright \diamondsuit} \quad (85)$$

Let $\vec{x} = \nu(P)$ and $\vec{x}_j = \nu(P_j)$ for all $j \in I$. Notice that $\vec{x}_j \subseteq \vec{x}$, for all $j \in I$. Also, $\Gamma_{j,1} = \Gamma \setminus \vec{x}_j$ and let $\Theta_j$ be a balanced environment such that $\text{dom}(\Theta_j) = \{c_{k+1}, \ldots, c_{k+|P_j|-1}\} \cup \{\bar{c}k+2, \ldots, \bar{c}k+|P_j|-1\}$, $\Theta_j(c_{k+1}) = ?(\vec{M}_j); \text{end}$ with $\vec{M}_j = (G(\Gamma), G(\Lambda))((\vec{x}_j))$. Then, by IH on the assumption of (85) we have for all $j \in I$:

$$G(\Gamma \setminus \vec{x}_j); \emptyset; G(\Delta, u_i : S_j), \Theta_j \vdash B^{k+1}_{\vec{x}_j}(P_j) \triangleright \diamondsuit \quad (86)$$

We define $\Theta = c_k ?(\vec{M}); \text{end}$ with $(G(\Gamma), G(\Lambda))(\vec{x}) = \vec{M}$. By construction, $\Theta$ is balanced. By Def. 3.14, $|P| = 1$ and so $\text{dom}(\Theta) = \{c_k\}$. Let $y_j^0 = (y_j^1, \ldots, y_j^{|S_j|})$. By the function defined in Tab. 3 we have:

$$B^1_j(u_i \triangleright \{l_j : P_j\}_{j \in I}) = c_k ?(\vec{x}).u_i \triangleright \{l_j : u_i!(N_{u,j}).0\}_{j \in I}$$

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where \( N_{u,j} = \lambda \bar{y}_j : \mathcal{G}(S_j). (\nu \tilde{c}_j)(\overline{c_{k+1}}(\bar{x}).0 \mid B_x^{k+1}(P_j\{y_j/u_j\})) \) and \( \tilde{c}_j = (c_{k+1}, \ldots, c_{k+|P_j|}) \).

Let \( \Gamma_1 = \Gamma \setminus \bar{x} \). We shall prove the following judgment:

\[
\mathcal{G}(\Gamma_1); \emptyset; \mathcal{G}(\Delta, u_i : \&\{l_j : S_j\}_{j \in I}), \Theta \vdash B_x^k(u_i \triangleright \{l_j : P_j\}_{j \in I}) \triangleright \diamond
\]

We define \( \Theta_{j,1} = \Theta_j, \overline{c_{k+1}} !! (\bar{M}) \); \textbf{end}. We use some auxiliary derivations for all \( j \in I \):

\[
\frac{\text{Nil} \quad \mathcal{G}(\Gamma); \emptyset; \emptyset \vdash 0 \triangleright \diamond}{\text{End}} \quad \frac{\text{PolySend} \quad \mathcal{G}(\Gamma); \emptyset; \overline{c_{k+1}} : \text{end} \vdash 0 \triangleright \diamond}{\mathcal{G}(\Gamma); \mathcal{G}(\Lambda); \emptyset \vdash \bar{x} \triangleright \bar{M}} \quad (87)
\]

\[
\frac{\text{PolyVar} \quad \mathcal{G}(\Gamma); \emptyset; \mathcal{G}(\Delta), \tilde{y}_j : \mathcal{G}(S_j), \Theta_{j,1} \vdash B_x^{k+1}(P_j\{y_j/u_j\}) \triangleright \diamond}{\mathcal{G}(\Gamma); \emptyset; \mathcal{G}(\Delta), \tilde{y}_j : \mathcal{G}(S_j), (\nu \tilde{c}_j)(\overline{c_{k+1}}(\bar{x}).0 \mid B_x^{k+1}(P_j\{y_j/u_j\})) \triangleright \diamond} \quad (88)
\]

where \( \sigma = \{\tilde{y}_j/\bar{u}\} \) with \( \bar{u} = (u_i, \ldots, u_i + |\mathcal{G}(S_j)|) \).

\[
\frac{\text{PolyAbs} \quad \mathcal{G}(\Gamma); \emptyset; \tilde{y}_j : \mathcal{G}(S_j) \vdash \tilde{y}_j \triangleright \mathcal{G}(S_j)}{\mathcal{G}(\Gamma); \emptyset; \tilde{y}_j : \mathcal{G}(S_j) \vdash (\nu \tilde{c}_j)(\overline{c_{k+1}}(\bar{x}).0 \mid B_x^{k+1}(P_j\{y_j/u_j\})) \triangleright \diamond} \quad (89)
\]

\[
\frac{\text{Send} \quad \mathcal{G}(\Gamma); \emptyset; \emptyset \vdash 0 \triangleright \diamond}{\text{End}} \quad \frac{\text{PolyVar} \quad \mathcal{G}(\Gamma_1); \emptyset \vdash \bar{x} \triangleright \bar{M}}{\mathcal{G}(\Gamma_1); \emptyset; \mathcal{G}(\Delta, u_i : \&\{l_j : S_j\}_{j \in I}), \Theta \vdash B_x^k(u_i \triangleright \{l_j : P_j\}_{j \in I}) \triangleright \diamond} \quad (90)
\]

Here we may notice that by Def. 3.4 and Def. 3.13 we have:

\[
\mathcal{G}(u_i : \&\{l_j : S_j\}_{j \in I}) = u_i : \&\{l_i : !(\mathcal{G}(S_j) \rightarrow \diamond); \text{end}\}_{j \in I}
\]

\[
\forall j \in I \quad \frac{\text{Bra} \quad \mathcal{G}(\Gamma); \mathcal{G}(\Delta, u_i : \&\{l_j : S_j\}_{j \in I}) \vdash u_i \triangleright \{l_j : u_i!(N_{u,j}).0\}_{j \in I} \triangleright \diamond}{\mathcal{G}(\Gamma); \mathcal{G}(\Delta, u_i : \&\{l_j : S_j\}_{j \in I}), c_k : \text{end} \vdash u_i \triangleright \{l_j : u_i!(N_{u,j}).0\}_{j \in I} \triangleright \diamond} \quad (91)
\]

The following tree proves this case:
2. Case $P = u_i \triangleleft j.P'$. For this case Rule Sel can be applied:

\[
\frac{\Gamma; \Delta, u_i : S_j \vdash P' \triangleright \bigcirc}{\Gamma; \Delta, u_i : \oplus \{l_j : S_j\}_{j \in I} \vdash u_i \triangleleft j.P' \triangleright \bigcirc}
\]  
(92)

Let $\overline{x} = \text{fv}(P')$ and $\Gamma_1 = \Gamma \setminus \overline{x}$. Also, let $\Theta_1$ be a balanced environment such that $\text{dom}(\Theta_1) = \{c_{k+2}, \ldots, c_{k+|P'|-1}\} \cup \{r_{k+2}, \ldots, r_{k+1+|P'|}\}$ and $\Theta_1(c_{k+2}) = ?(\overline{M})$; end where $\overline{M} = (\mathcal{G}(\Gamma), \mathcal{G}(\Lambda)) (\overline{x})$. Then, by IH on the first assumption of (92) we have:

\[
\mathcal{G}(\Gamma_1); \emptyset; \mathcal{G}(\Delta, u_i : S_j), \Theta_1 \vdash B_{k+2}^j (P') \triangleright \bigcirc
\]  
(93)

We define $\Theta = \Theta_1, \Theta'$ where:

\[
\Theta' = c_k : ?(\overline{M}); \text{end}, c_{k+1} : ?(\mathcal{G}(\overline{S}_j) - \triangleright \bigcirc); \text{end}, r_{k+1} : !((\mathcal{G}(\overline{S}_j) - \triangleright \bigcirc) \triangleright \bigcirc); \text{end}, r_{k+2} : !(\overline{M}); \text{end}
\]

By Def. 3.14, $|P| = |P'| + 2$, so

\[
\text{dom}(\Theta) = \{c_k, c_{k+1}, \ldots, c_{k+|P'|-1}\} \cup \{r_{k+1}, \ldots, r_{k+1+|P'|-2}\}
\]

By construction $\Theta$ is balanced since $\Theta(c_{k+2})$ dual $\Theta(r_{k+2})$ and $\Theta_1$ and $\Theta'$ are balanced. Let $\overline{y} = (y_1, \ldots, y_{\mathcal{G}(S_j)})$. By Tab. 3:

\[
B_{k+2}^j (u_i \triangleleft j.P') = c_k ?(\overline{x}), r_{k+1} !((\lambda y. u_i \triangleleft j, u_i ?(z), r_{k+1} !((\overline{x}), z \overline{y})), 0 | (\nu \overline{u} : (\mathcal{G}(S_j))) (c_{k+1} ?(y).
\]

where $\overline{u} = (u_{i+1}, \ldots, u_i + |\mathcal{G}(S_j)|)$ and $\tilde{\overline{u}} = (\overline{u}_{i+1}, \ldots, \overline{u}_i + |\mathcal{G}(S_j)|)$. We shall prove the following judgment:

\[
\mathcal{G}(\Gamma); \emptyset; \mathcal{G}(\Delta, u_i : \oplus \{l_j : S_j\}_{j \in I}), \Theta \vdash B_{k+2}^j (u_i \triangleleft j.P') \triangleright \bigcirc
\]

For this, we will use the following auxiliary derivations for the left-hand side component:

\[
\frac{\text{IVar} \quad \mathcal{G}(\Gamma); z : \mathcal{G}(\overline{S}_j) \triangleright \bigcirc; \emptyset \vdash z \triangleright \mathcal{G}(\overline{S}_j) \triangleright \bigcirc \quad \text{PolyApp} \quad \mathcal{G}(\Gamma); \emptyset; \overline{y} : \mathcal{G}(\overline{S}_j) \vdash \overline{y} \triangleright \mathcal{G}(\overline{S}_j)}{\mathcal{G}(\Gamma); z : \mathcal{G}(\overline{S}_j) \triangleright \bigcirc; \overline{y} : \mathcal{G}(\overline{S}_j) \vdash z \triangleright \overline{y} \triangleright \mathcal{G}(\overline{S}_j) \triangleright \bigcirc}
\]  
(94)

\[
\frac{\text{PolySend} \quad \mathcal{G}(\Gamma); \mathcal{G}(\Lambda), z : \mathcal{G}(\overline{S}_j) \triangleright \bigcirc; \overline{y} : \mathcal{G}(\overline{S}_j), r_{k+2} !!(M); \text{end} \vdash r_{k+2} !((\overline{x}), z \overline{y} \triangleright \bigcirc) \quad \text{End} \quad \frac{\mathcal{G}(\Gamma); \mathcal{G}(\Lambda), z : \mathcal{G}(\overline{S}_j) \triangleright \bigcirc; \overline{y} : \mathcal{G}(\overline{S}_j), r_{k+2} !!(M); \text{end}, u_i : \oplus \{l_j : S_j\}_{j \in I} \vdash \overline{u}_i \triangleright \overline{y} \triangleright \bigcirc}{\mathcal{G}(\Gamma); \mathcal{G}(\Lambda), z : \mathcal{G}(\overline{S}_j) \triangleright \bigcirc; \overline{y} : \mathcal{G}(\overline{S}_j), r_{k+2} !!(M); \text{end}, u_i \vdash \overline{u}_i \triangleright \overline{y} \triangleright \bigcirc}
\]  
(95)

\[
\frac{\text{Recv} \quad \mathcal{G}(\Gamma); \mathcal{G}(\Lambda), z : \mathcal{G}(\overline{S}_j) \triangleright \bigcirc; \emptyset \vdash z \triangleright \mathcal{G}(\overline{S}_j) \triangleright \bigcirc \quad \text{Sel} \quad \frac{\mathcal{G}(\Gamma); \mathcal{G}(\Lambda), u_i : \oplus \{l_j : S_j\}_{j \in I} \vdash u_i \triangleright \overline{y} \triangleright \bigcirc \quad \text{end}, \overline{y} : \mathcal{G}(\overline{S}_j), r_{k+2} !!(M); \text{end} \vdash u_i \triangleright \overline{y} \triangleright \bigcirc}{\mathcal{G}(\Gamma); \mathcal{G}(\Lambda), u_i : \oplus \{l_j : S_j\}_{j \in I} \vdash u_i \triangleright \overline{y} \triangleright \bigcirc \quad \text{end}, \overline{y} : \mathcal{G}(\overline{S}_j), r_{k+2} !!(M); \text{end} \vdash u_i \triangleright \overline{y} \triangleright \bigcirc}
\]  
(96)
The following auxiliary derivations are used to type the right-hand side component:

\[
\begin{align*}
\text{LVar} & \quad \frac{G(\Gamma); y : \text{G}(S_j) \rightarrow o; \emptyset \vdash \langle y \rangle \triangleright \text{G}(S_j) \rightarrow o}{G(\Gamma); y : \text{G}(S_j) \rightarrow o; \emptyset \vdash \langle y \rangle \triangleright \text{G}(S_j) \rightarrow o} \\
\text{App} & \quad \frac{G(\Gamma); y : \text{G}(S_j) \rightarrow o; \emptyset \vdash \langle y \rangle \triangleright \text{G}(S_j) \rightarrow o}{G(\Gamma); y : \text{G}(S_j) \rightarrow o; \emptyset \vdash \langle y \rangle \triangleright \text{G}(S_j) \rightarrow o}
\end{align*}
\]

\[
\begin{align*}
\text{Recv} & \quad \frac{G(\Gamma); \emptyset; c_{k+1} : ?(\text{G}(S_j) \rightarrow o); \emptyset \vdash \text{G}(S_j) \rightarrow o}{G(\Gamma); \emptyset; c_{k+1} : ?(\text{G}(S_j) \rightarrow o); \emptyset \vdash \text{G}(S_j) \rightarrow o}
\end{align*}
\]

\[
\begin{align*}
\text{Par} & \quad \frac{G(\Gamma); \emptyset; G(\Delta, u_{i+1} : S_j) \vdash B_{k+2}^2(P' \cup \{u_{i+1} / u_i\}) \triangleright o}{G(\Gamma); \emptyset; G(\Delta, u_{i+1} : S_j) \vdash B_{k+2}^2(P' \cup \{u_{i+1} / u_i\}) \triangleright o}
\end{align*}
\]

\[
\begin{align*}
\text{PolyResS} & \quad \frac{G(\Gamma); \emptyset; G(\Delta, \Theta_1, c_{k+1} : ?(\text{G}(S_j) \rightarrow o); \emptyset \vdash (\nu \tilde{\mu} : \text{G}(S_j))(c_{k+1}(y), y, \tilde{\mu}) \triangleright B_{k+2}^2(P' \cup \{u_{i+1} / u_i\})) \triangleright o}{G(\Gamma); \emptyset; G(\Delta, \Theta_1, c_{k+1} : ?(\text{G}(S_j) \rightarrow o); \emptyset \vdash (\nu \tilde{\mu} : \text{G}(S_j))(c_{k+1}(y), y, \tilde{\mu}) \triangleright B_{k+2}^2(P' \cup \{u_{i+1} / u_i\})) \triangleright o}
\end{align*}
\]

where \( \sigma = \{ \tilde{\mu} / \tilde{n} \} \) with \( \tilde{n} = (u_i, \ldots, u_{i + |G(S_j)| - 1}) \). The following tree proves this case:

\[
\begin{align*}
\text{Par} & \quad \frac{G(\Gamma); \emptyset; G(\Delta, u_i : \oplus \{l_j : S_j \}_{j \in I}, \Theta \vdash B_{k+2}^2(u_i \triangleright l_j, P') \triangleright o}{G(\Gamma); \emptyset; G(\Delta, u_i : \oplus \{l_j : S_j \}_{j \in I}, \Theta \vdash B_{k+2}^2(u_i \triangleright l_j, P') \triangleright o}
\end{align*}
\]

\[\]
\section{Proof of Thm. 3.27}

\textbf{Proof.} By mutual induction on the structure of \( P \) and \( V \). Here, we analyze only Part (1) of the theorem, as Part (2) and Part (3) are proven similarly:

1. By assumption \( \Gamma; \Delta, \Delta_\mu \vdash P \triangleright \triangleright \). There are four cases, depending on the shape of \( P \).

   \textbf{a. Case} \( P = \tau! (V).P' \), when \( V \) is not a variable. We consider case: \( r : S \in \Delta_\mu \). For this case Rule \textsc{Send} can be applied:

   \[
   \frac{\text{Send}}{\Gamma; \Delta_1, \Delta_\mu_2 \vdash P' \triangleright \triangleright} \quad \frac{\Gamma; \Delta_2, \Delta_\mu_2 \vdash V \triangleright U \quad r : S \in \Delta_\mu_1, \Delta_\mu_2}{\Gamma; \Delta_1, \Delta_2, ((\Delta_\mu_1, \Delta_\mu_2) \setminus \{r : S\}), r :! (U); S \vdash \tau! (V).P' \triangleright \triangleright}
   \]  
   \[
   (103)
   \]

   Let \( \bar{w} = f_v(P') \) and \( l = |V| \). Let \( \Theta_1, \Theta_2, \Theta' \) and \( \Theta \) be defined as in the corresponding case of Thm. 3.10 proof. Also, let \( \Gamma'_1 = \Gamma \setminus \bar{w} \). We define:

   \[
   \Phi_i = \prod_{r \in \text{dom}(\Delta_\mu_1)} c' : (\mathcal{R}^* (\Delta_\mu_1 (r)) \rightarrow \triangleright) \text{ for } i \in \{1, 2\}
   \]  
   \[
   (104)
   \]

   Then, by IH on the first assumption of (103) we have:

   \[
   G(\Gamma'_1), \Phi_1; \emptyset; G(\Delta_1), \Theta_1 \vdash B_{\bar{w}}^{k+i+1} (P') \triangleright \triangleright
   \]

   Let \( \Gamma'_2 = \Gamma \setminus \bar{y} \). Then, by IH (Part 2) on the second assumption of (103) we have:

   \[
   G(\Gamma'_2), \Phi_2; G(\Delta_2), \Theta_2 \vdash V_{\bar{y}}^{k+1} (V) \triangleright G(U)
   \]  
   \[
   (106)
   \]

   By Tab. 4 we have:

   \[
   B_{\bar{x}}^k (P) = c_k (\bar{x}).c'! (N_V).0 | B_{\bar{w}}^{k+i+1} (P')
   \]

   where \( N_V = \lambda \bar{z}. \bar{z} \cdot z \cdot f_v(S)! (V \cdot V_{\bar{y}}^{k+1} (V)).c'! (b). (b \bar{z}) \)

   We notice that \( r \in \text{rn}(V), \text{rn}(P) \) since \( r \) has recursive type \( S \). Hence, by (104) we know \( (\Phi_1, \Phi_2)(c') = (\mathcal{R}^* (S) \rightarrow \triangleright) \). Further, we know that \( S = ! (U); S' \) and by Def. 3.18, \( \mathcal{R}^* (S) = \mathcal{R}^* (S') \). So we define \( \Phi = \Phi_1, \Phi_2 \). Let \( \Gamma_1 = \Gamma \setminus \bar{x} \) where \( \bar{x} = f_v(P) \). We shall prove the following judgment:

   \[
   G(\Gamma_1), \Phi; \emptyset; G(\Delta_1, \Delta_2), \Theta \vdash B_{\bar{x}}^k (r! (V).P') \triangleright \triangleright
   \]

   We use auxiliary derivations:

   \[
   \frac{\text{LVar}}{G(\Gamma_1), \Phi; b : \mathcal{R}^* (S) \rightarrow \triangleright \emptyset \vdash b \triangleright} \quad \frac{\text{PolySess}}{G(\Gamma_1), \Phi; \bar{z} : \mathcal{R}^* (S) \vdash \bar{z} \triangleright \mathcal{R}^* (S)}
   \]

   \[
   \text{PolyApp} \quad \frac{G(\Gamma_1), \Phi; b : \mathcal{R}^* (S) \rightarrow \triangleright \emptyset \vdash b \triangleright \bar{z} \triangleright \mathcal{R}^* (S)}{G(\Gamma_1), \Phi; b : \mathcal{R}^* (S) \rightarrow \triangleright \emptyset \vdash b \triangleright \bar{z} \triangleright \mathcal{R}^* (S)}
   \]  
   \[
   (107)
   \]

   \[
   \frac{\text{Sh}}{G(\Gamma_1), \Phi; \emptyset \vdash c' \triangleright (\mathcal{R}^* (S) \rightarrow \triangleright)} \quad \frac{\text{LVar}}{G(\Gamma_1), \Phi; b : \mathcal{R}^* (S) \rightarrow \triangleright \emptyset \vdash b \triangleright \mathcal{R}^* (S) \rightarrow \triangleright}
   \]

   \[
   \text{Acc} \quad \frac{G(\Gamma_1), \Phi; \emptyset; \Theta^* \vdash c' \triangleright \mathcal{R}^* (S) \rightarrow \triangleright \emptyset \vdash c' \triangleright (b). (b \bar{z}) \triangleright \triangleright}{G(\Gamma_1), \Phi; \emptyset; \Theta^* \vdash c' \triangleright (b). (b \bar{z}) \triangleright \triangleright}
   \]  
   \[
   (108)
   \]
We define:

\[ u \vdash \bar{M} \]

We consider only sub-case (i) since the other is similar. For this case Rule \( \Theta \) and that can be applied:

\[ \Gamma \vdash \bar{M} \]

By Lem. C.1 we know that if \( \bar{z} : R^\ast(S) \) then \( z_f(S) : \mu !_! (G(U)); t. \)

The following tree proves this case:

\[ \Gamma \vdash \bar{M} \]

b. Case \( P = V (\bar{r}, u_i) \). We assume a certain order in the tuple \( (\bar{r}, u_i) \): names in \( \bar{r} \) have recursive session types \( \bar{r} = (r_1, \ldots, r_n) \): \( (S_1, \ldots, S_n) \), and \( u_i \) has non-recursive session type \( u_i : C \). We distinguish two sub-cases: (i) \( V : \bar{S}C \to \circ \) and (ii) \( V : \bar{S}C \to \circ \). We will consider only sub-case (i) since the other is similar. For this case Rule POLYAPP can be applied:

\[ \Gamma \vdash (\bar{r}, u_i) \]

Let \( \bar{x} = \bar{f}V \) and \( (\bar{r}, u_i) \); end

We define:

\[ \Phi_1 = \prod_{r \in \text{dom}(\Delta_{\mu_1})} c^r : (R^\ast(\Delta_{\mu_1}(r)) \to \circ) \]
Then, by IH (Part 2) on the first assumption of (115) we have:

\[ \mathcal{G} (\Gamma), \Phi, \emptyset; \mathcal{G} (\Delta_1), \Theta_1 \vdash \mathcal{V}^{k+1}_0 (V) \triangleright \mathcal{G} (S \mathcal{C}) \rightarrow \phi \]  

By Def. 3.4 and Def. 3.18 and the second assumption of (115) we have:

\[ \mathcal{G} (\Gamma); \emptyset; \mathcal{G} (\Delta_2), \mathcal{G} (\Delta_{\mu_2}) \vdash (\vec{r}_1, \ldots, \vec{r}_n, \vec{m}) : \mathcal{G} (S \mathcal{C}) \]  

where \( \vec{r}_i = (r^i_1, \ldots, r^i_{i+|G(C)|-1}) \) for \( i \in \{1, \ldots, n\} \) and \( \vec{m} = (u_i, \ldots, u_{i+|G(C)|-1}) \).

We define \( \Phi = \Phi_1, \Phi_2 \) where:

\[ \Phi_2 = \prod_{r \in \text{dom}(\Delta_{\mu_2})} c^r : \langle R^* (\Delta_{\mu_2}(r)) \rightarrow \phi \rangle \]

We define \( \Theta = \Theta_1, c_k : (? (\vec{M}); \cdot \). We will first consider the case where \( n = 3 \); the proof is then generalized for any \( n \geq 1 \):

- If \( n = 3 \) then \( P = V (r_1, r_2, r_3, u_1) \). By Tab. 4 we have:

\[ B^k_3 (V (r_1, r_2, r_3, u_1)) = c_k (\bar{x}), e^{c^r} (\lambda_{\bar{x}_1}. e^{c^r} (\lambda_{\bar{x}_2}. e^{c^r} (\lambda_{\bar{x}_3} (Q), \emptyset), 0).0 \]

where \( Q = \mathcal{V}^{k+1}_0 (V) (\bar{z}_1, \ldots, \bar{z}_m, \vec{m}) \); \( \bar{z}_i = (z^i_1, \ldots, z^i_{i+|G(S_i)|-1}) \) for \( i \in \{1, 2, 3\} \); \( \vec{m} = (u_1, \ldots, u_{i+|G(C)|-1}) \).

We shall prove the following judgment:

\[ \mathcal{G} (\Gamma), \Phi, \emptyset; \mathcal{G} (\Delta_1 \Delta_2), \Theta \vdash V (\vec{r}, u_1) \triangleright \phi \]  

We use auxiliary derivations:

\[ \frac{\text{(Lem. A.3)} \text{ with } \Phi_2}{\mathcal{G} (\Gamma), \Phi, \emptyset; \mathcal{G} (\Delta_1), \Theta_1 \vdash \mathcal{V}^{k+1}_0 (V) \triangleright \mathcal{G} (S \mathcal{C}) \rightarrow \phi} \]

\[ \frac{\text{(Lem. A.2)} \text{ with } \sigma}{\mathcal{G} (\Gamma), \Phi, \emptyset; \mathcal{G} (\Delta_2), \mathcal{G} (\Delta_{\mu_2}) \vdash (\bar{z}_{1}, \bar{z}_2, \bar{z}_3, \vec{m}) \triangleright \mathcal{G} (S \mathcal{C})} \]

\[ \frac{\text{PolyApp}}{\mathcal{G} (\Gamma), \Phi, \emptyset; \mathcal{G} (\Delta_1 \Delta_2), \Theta_1, \mathcal{G} (\Delta_{\mu_2}) \vdash \mathcal{V}^{k+1}_0 (V) (\bar{z}_{1}, \bar{z}_2, \bar{z}_3, \vec{m})} \]

where \( \sigma = \{ \bar{n}_i / \bar{z}_i \} \cdot \{ \bar{n}_j / \bar{z}_j \} \cdot \{ \bar{n}_k / \bar{z}_k \} \) with \( \bar{n}_i = (r^i_1, \ldots, r^i_{i+|G(S_i)|-1}) \) for \( i \in \{1, 2, 3\} \).

\[ \frac{\text{PolyAbs} \quad \text{PolySess}}{\mathcal{G} (\Gamma), \Phi, \emptyset; \mathcal{G} (\Delta_1 \Delta_2), \Theta_1 \vdash \lambda \bar{z}_3, Q \triangleright \mathcal{G} (S_3) \rightarrow \phi} \]

\[ \frac{\text{Req} \quad \text{PolyAbs} \quad \text{PolySess}}{\mathcal{G} (\Gamma), \Phi, \emptyset; \mathcal{G} (S_2) \triangleright \bar{z}_2 \triangleright \mathcal{G} (S_2) \rightarrow \phi} \]
The following tree proves this case:

\[
\begin{align*}
\text{PolyRec} & \quad \frac{\text{PolyVar}}{\frac{\text{PolyAbs}}{\frac{\text{Req}}{\frac{\text{Nil}}{\text{G}(\Gamma), \Phi; \emptyset; \emptyset \vdash 0}}}}{\frac{\text{G}(\Gamma), \Phi; G(A); G(\Delta_1 \Delta_2), \Theta_1, \tilde{z}_1 : G(S_1) \vdash \lambda \tilde{z}_2, c^r! (\lambda \tilde{z}_2, c^r! (\lambda \tilde{z}_3, Q), 0), 0 \triangleright \emptyset}{\text{G}(\Gamma), \Phi; G(A); G(\Delta_1 \Delta_2), \Theta_1 \vdash c^r! (\lambda \tilde{z}_2, c^r! (\lambda \tilde{z}_3, Q), 0), 0}}}
\end{align*}
\]

Now we consider the general case for any \( n \geq 1 \):

By Tab. 4 we have:

\[
B_k(V \tilde{r}) = c_k ?(\tilde{x}), c^{r_1}! (\lambda \tilde{z}_1 \ldots c^{r_n}! (\lambda \tilde{z}_n, Q) \ldots)
\]

where \( Q = \bigvee_{i=2}^{k+1} (V (\tilde{r}_1, \ldots, \tilde{r}_n, \tilde{m})) \) with: \( \tilde{z}_i = (z_{i_1}, \ldots, z_{i_{|G(S_i)|}}) \) for \( i = \{1, \ldots, n\} \) and \( \tilde{m} = (u_{i_1}, \ldots, u_{i_{|G(C)|-1}}) \).

We shall prove the following judgment:

\[
G(\Gamma), \Phi; G(\Delta_1 \Delta_2), \Theta \vdash B_k(V (\tilde{r}, u_i)) \triangleright \emptyset \tag{129}
\]

We construct auxiliary derivations parametrized by \( k \) and denoted by \( d(k) \). If \( k = n \), derivation \( d(n) \) is defined as:

\[
\begin{align*}
\text{Lem. A.3 with } \Phi_2 & \quad \frac{\text{Nil}}{\text{G}(\Gamma), \Phi; G(A); G(\Delta_1), \Theta_1 \vdash \bigvee_{i=2}^{k+1} (V) \triangleright G(\tilde{S}C) \rightarrow \emptyset} \quad \text{Req} \quad \frac{\text{Nil}}{\text{G}(\Gamma), \Phi; \emptyset; \emptyset \vdash 0} \tag{130} \\
\text{PolyAbs} & \quad \frac{\text{G}(\Gamma), \Phi; G(A); G(\Delta_1 \Delta_2), \Theta_1 \vdash \lambda \tilde{z}_2, c^r! (\lambda \tilde{z}_2, c^r! (\lambda \tilde{z}_3, Q), 0), 0 \triangleright \emptyset}{\text{G}(\Gamma), \Phi; G(A); G(\Delta_1 \Delta_2), \Theta_1 \vdash c^r! (\lambda \tilde{z}_2, c^r! (\lambda \tilde{z}_3, Q), 0), 0} \tag{128} \\
\text{PolyVar} & \quad \frac{\text{G}(\Gamma), \Phi; G(A); \Theta \vdash B_k(V (\tilde{r}, u_i)) \triangleright \emptyset}{\text{G}(\Gamma), \Phi; G(A); \Theta \vdash B_k(V (\tilde{r}, u_i)) \triangleright \emptyset} \tag{131}
\end{align*}
\]

where \( \sigma = \prod_{i \in \{1, \ldots, n\}} [\tilde{m}_i/\tilde{z}_i] \) with \( \tilde{m}_i = (r_{i_1}, \ldots, r_{i_{|G(S_i)|-1}}) \) for \( i = \{1, \ldots, n\} \).
Otherwise, if \( k \in \{1, \ldots, n-1 \} \), derivation \( d(k) \) is as follows:

\[
\begin{align*}
\text{PolyAbs} & \quad d(k + 1) \quad \text{PolyVar} \\
\frac{G(\Gamma), \Phi; \emptyset; \tilde{z}_k : G(S_k) \vdash \tilde{z}_k \triangleright G(S_k)}{G(\Gamma), \Phi; G(\Lambda); G(\Delta_1, \Delta_2), \Theta_1, (\tilde{z}_1, \ldots, \tilde{z}_{k-1}) : (G(S_1), \ldots, G(S_{k-1})) \vdash} \\
& \quad \lambda \tilde{z}_k. \, c^{\ell_{k+1}}((\lambda \tilde{z}_{k+1}, \ldots, c^{\ell_n}(\lambda \tilde{z}_n, Q), 0, \ldots).0) \triangleright G(S_1) \rightarrow \circ \\
& \quad \Theta \quad (133)
\end{align*}
\]

\[
\begin{align*}
\text{Acc} & \quad (\Gamma), \Phi; \emptyset; \emptyset \vdash c^\ell \triangleright (G(S_1) \rightarrow \circ) \\
\frac{G(\Gamma), \Phi; G(\Lambda); G(\Delta_1, \Delta_2), \Theta_1, (\tilde{z}_1, \ldots, \tilde{z}_{k-1}) : (G(S_1), \ldots, G(S_{k-1})) \vdash}{c^{\ell_n}(\lambda \tilde{z}_{k+1}, \ldots, c^{\ell_n}(\lambda \tilde{z}_n, Q), 0, \ldots).0} \\
& \quad \Theta \quad (134)
\end{align*}
\]

The following tree proves this case:

\[
\begin{align*}
\text{PolyRcv} & \quad d(1) \quad \text{PolyVar} \\
\frac{G(\Gamma_1), \Phi; G(\Lambda); G(\Delta_1, \Delta_2), \Theta \vdash B^k_2(V(\tilde{r}, u_1)) \triangleright \circ}{G(\Gamma_1), \Phi; G(\Lambda); G(\Delta_1, \Delta_2), \Theta \vdash} \\
& \quad \Theta \quad (135)
\end{align*}
\]

\section{C.2 Proof of Thm. 3.28}

\textbf{Proof.} By assumption \( \Gamma; \emptyset; \Delta, \Delta_\mu \vdash P \triangleright \circ \). Then, by applying Lem. A.2 we have:

\[
\Gamma \sigma; \emptyset; \Delta \sigma, \Delta_\mu \sigma \vdash P \sigma \triangleright \circ \\
\text{(135)}
\]

By Thm. 3.27 on (135) we have:

\[
G(\Gamma_1 \sigma), \Phi; G(\Delta \sigma), \Theta \vdash B^k_2(P \sigma) \triangleright \circ \\
\text{(136)}
\]

where \( \Theta \) is balanced with \( \text{dom}(\Theta) = \{c_k, c_{k+1}, \ldots, c_{k+|P|-1}\} \cup \{r_{k+1}, \ldots, r_{|P|+|\sigma|-1}\} \), and \( \Theta(c_k) = ?(\cdot); \text{end} \), and \( \Phi = \prod_{r \in \text{dom}(\Delta \sigma)} c^r : (\text{R}^*(\Delta_\mu(r)) \rightarrow \circ) \). By assumption, \( \text{fv}(P) = \emptyset \).

By Def. 3.25, we shall prove the following judgment:

\[
\begin{align*}
G(\Gamma \sigma); \emptyset; G(\Delta \sigma), G(\Delta_\mu \sigma) & \vdash (\nu \tilde{v}) (\nu \tilde{v}_r) \left( \prod_{r \in \tilde{v}} c^{\ell}(b, 0, b \tilde{r} \mid \tau_r!().0 \mid B^k_2(P \sigma) \right) \\
\text{where:} & \quad k > 0; \tilde{v} = \text{rn}(P); \tilde{r} = (r_1, \ldots, r_{|G(S)|}) \text{ for each } r \in \tilde{v}.
\end{align*}
\]

We know \( \text{dom}(\Delta_\mu) = \tilde{v} \). We assume that recursive session types are unfolded. By Def. 3.4 and Def. 3.18, for \( r \in \text{dom}(\Delta_\mu) \) we have:

\[
G(\Delta_\mu)(r) = \text{R}(\Delta_\mu(r)) = \text{R}^*(\Delta_\mu(r))
\]

We use a family of auxiliary derivations parametrized by \( r \in \tilde{v} \).

\[
\begin{align*}
\text{LVar} & \quad G(\Gamma \sigma), \Phi; b : \text{R}^*(\Delta_\mu(r)) \rightarrow \circ; \emptyset \vdash b \triangleright \text{R}^*(\Delta_\mu(r)) \rightarrow \circ \\
\text{PolyApp} & \quad G(\Gamma \sigma), \Phi; b : \text{R}^*(\Delta_\mu(r)) \rightarrow \circ; \emptyset \vdash G(\Gamma \sigma), \Phi; b : \text{R}^*(\Delta_\mu(r)) \rightarrow \circ; \emptyset \vdash \text{R}^*(\Delta_\mu(r)) \vdash (b \tilde{r}) \\
\text{PolySess} & \quad G(\Gamma \sigma), \Phi; b : \text{R}^*(\Delta_\mu(r)) \rightarrow \circ; \emptyset \vdash G(\Gamma \sigma), \Phi; b : \text{R}^*(\Delta_\mu(r)) \rightarrow \circ; \emptyset \vdash \text{R}^*(\Delta_\mu(r)) \vdash (b \tilde{r}) \\
\text{PolyVar} & \quad G(\Gamma \sigma), \Phi; \emptyset ; \emptyset \vdash c^{\ell} \triangleright (G(S_1) \rightarrow \circ) \\
\end{align*}
\]

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We will then use:

\[
\text{Par}_{\{\tilde{v}\} - 1 \times} \quad (138)
\]

where we apply Rule `Par_{\{\tilde{v}\} - 1 \times}` and for every \( r \in \tilde{v} \) we apply derivation (138). Notice that by Def. 3.4 and Def. 3.18 we have \( G(\Delta_\mu \sigma) = \prod_{r \in \tilde{v}} c_{\tilde{r}} : R^{\ast}(\Delta_\mu(r)) \).