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April 2020

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Improving Worker Productivity Through Tailored Performance Feedback: Field Experimental Evidence from Bus Drivers

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April 20, 2020

Abstract

How should performance feedback be tailored to improve worker productivity? In a natural field experiment with bus drivers, we test the potential of two forms of individual feedback: written peer-comparison feedback and in-person coaching.

We find that the announcement of the written feedback program has a substantial and significant effect on fuel economy and outcomes pertaining to passenger comfort; targeted peer-comparison feedback is generally ineffective; in-person coaching generates significant improvements on all dimensions for drivers in the bottom half of the performance distribution for about eight weeks; in-person coaching reduces the impact of written peer-comparison feedback but not vice versa.

JEL classification: D23, J24, M53, Q55.

Keywords: labor productivity, feedback, peer comparisons, field experiment.

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1 Introduction

Giving effective performance feedback is critical in maintaining and enhancing worker productivity, especially in work environments that hinder the use of pay-for-performance schemes (Blader, Gartenberg and Prat 2020, Gosnell, List and Metcalfe 2020). The adoption of digital monitoring technologies at the work floor has made detailed individual-level data on disaggregated productivity measures available and hence greatly expanded managers' scope for giving workers tailored performance feedback (Staats, Dai, Hofmann and Milkman 2017). This increases the need to answer two important yet unsettled questions concerning optimal feedback provision. First, is feedback more effectively delivered in person or via automatically generated individual-specific feedback reports? The combination of finer data granularity and digital storage makes the latter feasible at low marginal cost. Second, which dimensions of worker productivity should the feedback target? The additional detail on the constituent parts of worker productivity gives managers more choice in selecting feedback intensity and in combining positive with negative feedback. Should they provide feedback on all dimensions simultaneously to prevent drivers from underperforming in non-reported dimensions (Hölmstrom and Milgrom 1991, Baker 1992) or should they instead limit feedback to prevent information overload (Simon 1973, Hitt and Brynjolfsson 1997, Edmunds and Morris 2000)?¹

This paper aims to contribute to answering these questions. We run a field experiment at a large public transport company that is in the process of installing electronic on-board recorders (EOBRs) in its entire bus fleet. EOBRs enable the high-frequency measurement of a range of productivity outcomes, such as fuel efficiency and the number of Acceleration, Braking and Cornering events, the so-called ABC comfort dimensions.² Digital monitoring technologies such as EOBRs offer great potential in improving the quantitative evaluation of the effectiveness of different forms of performance feedback. Yet, this potential is thus far largely untapped. Feedback eligibility and feedback intensity are likely to correlate

¹Recent studies that examine how the adoption of electronic monitoring technologies by firms impact worker productivity include Pierce, Snow and McAfee (2015) and Kelley, Lane and Schönholzer (2018).

²More generally, innovations in the transport sector related to on-board monitoring open up novel opportunities to measure worker productivity. See Baker and Hubbard (2003) and Hubbard (2003) for early work incorporating this technology. They study how the adoption of on-board computers has influenced the decision of truckers to integrate or outsource trucking services.

with workers' (relative) productivity outcomes. This sample selection biases estimates of feedback effectiveness that are based on comparisons of worker productivity just before and right after the worker has received feedback.

To avoid such bias, we combine detailed EOBR data from a sample of 409 bus drivers with random treatment variation in feedback format and feedback intensity. This creates a unique opportunity to quantitatively evaluate the effectiveness of different forms of performance feedback, allowing us to present estimates on the causal impacts of varying feedback intensity and feedback channel (written or in person) on worker productivity.

Following the launch of the company's EcoManager campaign to promote efficient and comfortable driving, all drivers receive a monthly written feedback report on their driving performance in the preceding month. This part of the campaign is not subjected to experimental variation: the launch date and timing of the monthly feedback are the same for all drivers. To this general report, we add a text box in which we experimentally vary the number of ABC dimensions on which drivers receive information on their relative ranking. This text box is empty for drivers in the control group. Drivers in the first treatment condition receive information on their poor relative performance (if any) on only one of the ABC dimensions, even when performance is relatively poor on multiple dimensions. That is, we deliberately withhold some rankings to allow drivers to focus their effort. The second treatment condition is similar, except that negative feedback is supplemented with positive feedback in case a driver who performs poorly on some dimensions scores well on others. This allows us to assess the value of providing a mix of corrective and positive feedback. In the final condition, all relative positions on driving behaviors are communicated whenever the driver performs poorly compared to a reference group of peers. Together, these interventions enable us to explore the potential of onboard monitoring technologies in customizing written relative performance feedback such that it enhances worker motivation.

In addition to the written peer-comparison feedback, we evaluate the effects of a parallel in-person coaching program with a quasi-experimental design. In this program, designated experienced drivers engage in coaching their colleagues by riding along with a bus driver for a portion of the driver's shift. At the end of the ride, the coach evaluates the trip in detail and gives tailored tips for improvement. Due to the hop-on hop-off approach to coaching and regulations that disallow coaches access to the driver's performance, the timing of the coaching sessions can be considered the outcome of quasi-random assignment: coaches select the drivers they will coach on a given day in a way that is unrelated to a driver's past performance. Our empirical evidence corroborates this. The (quasi-)random assignment of the different feedback designs thus avoids the aforementioned selection problems. We follow drivers for two years in order to establish a long baseline and experimental period. This enables us to measure both the immediate and delayed response to the feedback programs. We evaluate the two feedback formats using over 500,000 trip-level observations.

Our main findings are as follows. First, the launch of the general EcoManager campaign reduces fuel consumption by 0.4 liters/100km (0.40 standard deviation, SD). Distributing the feedback reports generates a further 0.1 SD reduction. For the peercomparison feedback, we find precisely estimated zero effects. Varying the number and nature of peer-comparison feedback messages has no additional impact on worker productivity.

Second, we observe strong and immediate effects of coaching. On the day of coaching the fuel need reduces by 0.6 liters/100km (0.58 SD, p < 0.001) and the number of acceleration events by 1.1 events/10km (0.50 SD, p < 0.001). For braking and cornering behavior, these effects are less pronounced and not (braking) or less (cornering) significant. The improvements due to coaching tend to persist with a smaller magnitude in the ensuing weeks but fade out after about seven to nine weeks. Zooming in, we find the impact of coaching on performance confined to drivers in the bottom half of the performance distribution.

Third, we find a nonreciprocal relation between in-person coaching and written peercomparison feedback: prior exposure to peer-comparison messages does not change the effectiveness of in-person coaching for any of the productivity measures. Peer-comparison feedback, however, is only effective in the group of drivers that did not yet receive inperson coaching. One possible explanation is that once drivers have met a coach who gave them detailed feedback on what they do right and wrong on a trip, they become insensitive to subsequent written messages about their relative performance.

Fourth, in the group of non-coached drivers, those in the treatment with the maximum number of negative messages and no positive comments show the largest improvement in productivity outcomes. In other words, limiting negative feedback or mixing negative with positive feedback does not seem to have any beneficial effect. This shows that it is important to pay attention to interactions between the different elements of job design.

This paper proceeds as follows. Section 2 reviews the related literature. Section 3 describes the field setting of the study. Section 4 elaborates on the research design, provides further details on both feedback programs and presents the data. The empirical analysis of both programs follows in Section 5. Section 6 discusses the results and concludes.

2 Related Literature

A large literature shows that management practices matter for worker productivity (Bloom and van Reenen 2007, Bloom, Eifert, Mahajan, McKenzie and Roberts 2013, Syverson 2011). Despite a considerable body of empirical work, the question how relative performance feedback affects worker productivity has not yet received its definite answer. Previous studies indicate that relative performance feedback can improve worker productivity (Blanes i Vidal and Nossol 2011, Song, Tucker, Murrell and Vinson 2018), sales growth (Delfgaauw, Dur, Sol and Verbeke 2013) and (high school) student performance (Tran and Zeckhauser 2012, Azmat and Iriberri 2010). Other studies, however, report decreased performance following the provision of rank information (Ashraf, Bandiera and Lee 2014, Bandiera, Barankay and Rasul 2013) and improved performance when they are abolished (Barankay 2012). People may exhibit rank incentives (Barankay 2012, Tran and Zeckhauser 2012) when relative performance information affects self-image (Benabou and Tirole 2006) and status (Moldovanu, Sela and Shi 2007). These rank incentives can lead to demotivation at the bottom of the performance distribution, which reduces the average effects of feedback programs that rely on social comparisons (Ashraf et al. 2014). Kuhnen and Tymula (2012) suggest that it may be promising to customize relative performance feedback by tailoring the content or by targeting subsets of workers. Blader,

Gartenberg and Prat (2020) for example find that the provision of relative performance information in plants with(out) a teamwork culture leads to decreased (improved) truck driver performance.

What may account for some of the heterogeneity in results is that rankings are typically reported on final outcomes rather than on the intermediate steps leading to these outcomes. In this form, the message may be demotivating because it gives little guidance on where to improve and signals that improvement requires one big step rather than several small and clear steps. Feedback provision on disaggregated productivity measures can provide much more guidance on where to improve, making it easier for workers to change their behavior. It may empower poor performers by increasing the feeling of control, raising awareness of behaviors that require attention, and by offering suggestions for specific actions that workers can take. The feeling of being in control is a key source of human motivation (Ryan and Deci 2000).

Our research design does exactly that. One possible concern with disaggregated relative performance feedback, however, is that it may aggravate the adverse effects of feedback provision. That is, it may make poor performance even more salient to workers at the bottom of the distribution. When information directly enters the utility function (Golman, Hagmann and Loewenstein 2017), informing workers about poor performance on multiple dimensions may decrease motivation.³ Also, the increased level of detail in the written feedback may trigger adverse effects similar to those caused by feedback overload. Increasing the feedback frequency can lead to more mistakes (Eriksson, Poulsen and Villeval 2009) and reduced task effort due to overwhelmed cognitive resources (Lam, DeRue, Karam and Hollenbeck 2011). This poses a challenge, as poor performers have the biggest room for improvement and are thus precisely the group that one wishes to target with detailed feedback.

Treatment effect heterogeneity may also show in the drivers' response to in-person coaching. A prevalent finding in the literature on peer effects in educational outcomes (Sacerdote 2011) is that high-ability students benefit most from the presence of highability peers (Fruehwirth, 2013, Hoxby and Weingarth, 2005, Lavy, Paserman, and Schlosser,

³Dohmen et al. (2011), for example, show that reward-related brain areas negatively correlate with lower relative incomes.

2011, Lavy, Silva and Weinhardt, 2012) although some studies (Burke and Sass 2013) find that students with the lowest past performance gain most from exposure to higherachieving peers.⁴ Drivers in our design are coached by experienced colleagues assigned the role of coach. Hence, a coaching session explicitly exposes a driver to a high-achieving peer. While recognizing the differences between a school environment and the work environment that we study – both in the nature of the interactions and the outcomes of interest – the cited studies suggest that the effect of in-person coaching may depend on a driver's own past performance. Our study checks whether this result on peer effects carries over to non-educational contexts. A related study is Sandvik, Saouma, Seegert and Stanton (2020) who run a field experiment among salespeople. They similarly find that exposure to a high-achieving peer generates productivity gains but in their setting, the gains persist even after twenty weeks.

Next to contributing to the empirical literature on optimal feedback design in operations management, our findings also address the broader societal challenge of how to combat unsustainable energy consumption practices. While there has been much progress in our understanding of non-financial incentives in residential energy consumption, research on how these insights generalize to firms is scant (Gerarden, Newell and Stavins 2017, Gosnell et al. 2020, Nilekani 2018).⁵ Our work aims to partly fill this gap and should be viewed as part of the emerging literature that looks at the workplace for evidence on the effect of non-financial incentives on conservation efforts (Gosnell et al. 2020). Given that firms increasingly record and store data on multiple dimensions of worker-level productivity, tailoring feedback by decomposing consumption into its underlying sources seems

 $^{^{4}}$ Booij, Leuven and Oosterbeek (2017) find that low-ability students benefit from having low-ability peers but that high-ability students are unaffected by their peer group composition.

⁵Existing studies on non-financial incentive schemes in the residential sector stress the importance of feedback and social approval in increasing welfare (Allcott and Mullainathan 2010). For example, incorporating social comparisons in feedback reports reduces household consumption of energy (Allcott 2011, Ayres, Rasemand and Shih 2013) and water (Ferraro and Price 2013), with long-run effectiveness depending on whether households alter their capital stock of habits or physical technologies (Allcott and Rogers 2014). Recent research, however, also notes that social comparisons can trigger asymmetric effects (Holladay, LaRiviere, Novgorodsky and Price 2016) and may interact with other non-financial incentives when stimulating green behavior (Hahn, Metcalfe, Novgorodsky and Price 2016). This has reinforced the need for detailed evaluations of non-financial incentives pertaining to energy efficiency and also raises the question how these findings generalize to workers. Allcott and Kessler (2019) emphasize the importance of incorporating the (moral and emotional) costs incurred by nudge recipients in assessing the welfare effects of social comparisons.

a viable and promising approach to creating novel data-driven designs of conservation incentives (Brynjolfsson and McElheran 2016). The setting of a transport company is apt as the transport sector takes a heavy toll on the environment, accounting for onefifth of global primary energy use and one-quarter of energy-related carbon dioxide (CO_2) emissions (IEA 2012). Indeed, the International Council on Clean Transportation hails fuel-efficient driving as low-hanging fruit to improve conservation levels (ICCT 2013).⁶ However, picking this fruit can be challenging when drivers have no financial stake.

3 Field Setting

3.1 Industry

Our field partner is Arriva, a European-wide passenger transport company operating various transport modes in public transport. Bus transport is the firm's largest business unit.⁷ In the Netherlands, bus concessions are granted to companies by means of a tendering procedure.⁸ Winning a tender gives companies the exclusive rights to operate in a designated area for a number of years. To stimulate firms to engage in environmentally friendly behavior and to improve the living conditions of its citizens, local governments let environmental objectives feature prominently in the requirements tendering parties need to meet.⁹ This has geared public transport companies toward the use of environmentally friendly technologies.¹⁰ In the long run, this trend may drive bus companies to buy vehicles with a hybrid or electric fuel technology. On a shorter time horizon, the installment of electronic on-board recorders (EOBRs) helps the companies to meticulously measure performance on several dimensions of driving behavior. For example, the version used by Arriva records trip-level performance on fuel consumption and comfort dimensions such

⁶Barkenbus (2010) has sketched the potential of multidimensional eco-driving campaigns and feedback mechanisms for personal transportation. We instead examine the extent to which this potential can be realized in public transportation.

⁷At the time of the study, Arriva Group is part of Deutsche Bahn, employs over 60,000 people and annually delivers more than 2.2 billion passenger journeys in 14 European countries.

⁸See the Passenger Transport Act 2000.

⁹Interested companies are commonly requested to submit a sustainability plan in which they indicate how they decrease the ecological footprint of public transport in the concession area.

¹⁰The Dutch Ministry of Infrastructure mentions public transport as a "trend setter" in the area of sustainable technologies (MIVW, 2010, p. 87).

as acceleration, braking and cornering (ABC). Each driver logs into the system with a unique personnel number to match the performance records and trip-related background variables. This enables precise monitoring and provides managers and researchers with a wealth of high-frequency data on worker productivity and conservation efforts.

The system works as follows for the comfort dimensions. Based on test rides under different circumstances, threshold performance levels are formulated by the company for every dimension. Technically, the thresholds relate to minimum G-force measurements by a three-axis accelerometer in the bus. During each trip, the EOBR records an 'event' whenever an action by the driver is in excess of these thresholds. The performance measure of the ABC dimensions is the number of events per 10km, with fewer events indicating better driving behavior. The outcome data can subsequently be linked with centralized databases containing information on a host of driver and trip characteristics. This allows us to get a detailed picture of driver performance over time under various on-the-road conditions.

3.2 Research Setting

As part of its EcoManager campaign, Arriva Netherlands installed new EOBRs in its entire fleet in the time period 2015-2017. The EOBR data will be used as input to monthly feedback reports that will be distributed among the drivers. In addition, a new coaching program is introduced in which drivers receive real-time feedback and advice from an experienced colleague during on-the-road sessions. The new technology and the feedback programs are phased in over time in the concession areas.

We join the implementation process in the first concession area, comprising about two-thirds of a province in the Netherlands and serving about 5.16 million travelers in a year.¹¹ The majority of drivers in this area are tenured employees, while a small number (about 14%) operates on a temporary contract. Most of the drivers are experienced and have a long career of driving buses or other vehicles. They are typically not involved in other tasks within the organization. Opportunities for promotion are limited and the

¹¹Based on the official number of electronic check-ins with the public transport card in 2015.

work council is against using financial incentives to reward good performances.¹² In the past, drivers received no personal feedback.

Each driver belongs to one of the six base locations (usually a municipality) in the area and operates on routes that are stipulated by the concession. For five locations, virtually all routes are between cities and in rural areas. Routes are based on timetables and do not vary much over time. One location (the largest one) has a mixture of urban and rural routes. Urban trips are mostly operated by a special bus type that runs on natural gas. Within a location, drivers' weekly shifts rotate. This implies that the worker faces week-to-week variation in his or her assignment to trips and the schedule repeats after about 14 weeks. This way of scheduling ensures that drivers are familiar with their routes and drive each route under different on-the-road circumstances. The schedules provide ample within-location variation in the type of trips, such that all drivers face a more or less similar mixture of relatively easy and difficult trips. Because of the rotation of shifts multiple drivers are assigned a given route. Together this variation allows us to include a rich set of fixed effects in our empirical analysis.

3.3 Scope for Improvement

Before discussing the research design, we wish to get an idea of the potential scope for improvement by considering the factors that influence driver performance on fuel economy and the ABC dimensions. What part of performance can be influenced by the driver and what part is caused by external factors such as weather and traffic conditions? For fuel economy, we observe sizable between-driver variation in performance. To drive 100km, the average driver uses 24.91 liters of fuel, with a standard deviation of $\sigma = 2.30$.¹³ Table 1 shows that part of this variation can be attributed to differences in driving conditions.

The first column shows that the bus type accounts for 27.9 percent of the between-

 $^{^{12}}$ Within firms, the design of conservation incentives is often dictated by institutional constraints that hinder the use of pay-for-performance schemes. See e.g. Freeman (1981), who finds that withinestablishment dispersion of wages is narrower in unionized establishments. He attributes this in large part to unions' wage practices, such as the adoption of uniform wages (rather than merit-based pay).

 $^{^{13}25}$ liters/100km ~ 10.6 gallon/100miles. Throughout the text, we will state (changes in) fuel economy in l/km instead of km/l because of the miles-per-gallon (MPG) illusion (Larrick and Soll 2008). Figure A3 shows the entire distribution of driver fixed effects for the outcome variable fuel economy.

trip variation in fuel economy, with the Intouro and longer buses having a sizable and significantly worse fuel economy. The impact of weather conditions (column (2)) seems limited. Fuel economy is – as one expects – negatively correlated with the number of stops per kilometer, the number of passengers, evening rush hours and the bus running late. These variables seem to capture most of the day-to-day variation in fuel economy, as adding day fixed effects only slightly improves the R^2 . Structural differences in driver performance explain an additional eight percentage points of variation in trip-level fuel economy (column (5)). When we control for the rich set of trip characteristics as in column (5) of Table 1, the variation in performance between drivers as measured by the residual standard deviation is $\sigma_r = 1.03$.¹⁴ Hence, the potential for improvement is economically significant: A policy able to move a driver's average fuel economy from the 90th percentile to the 10th percentile reduces this driver's fuel bill by 2.46 liters/100km or about 10%.

We use the residual variation σ_r to compute the coefficient of variation $c_v = \sigma_r/\mu$ as a standardized measure of dispersion to compare the relative scope for improvements in fuel economy and in the ABC dimensions. For fuel economy, this coefficient equals $0.04 \ (= 1.03/24.91)$. The numbers for the ABC dimensions are shown in Table 2. The coefficients of variation show that in relative terms, between-driver dispersion is larger for the ABC dimensions than for fuel economy. However, for braking and cornering the average number of events per 10km is relatively close to the absolute lower bound of zero, thereby limiting the upward potential for a large fraction of drivers.

Of course, the different outcomes are related: more acceleration events for instance increase fuel consumption. Table 2 shows the residual correlation between the fuel economy and comfort dimensions after controlling for the same set of trip-level characteristics as in column (4) of Table 1. Fuel economy is correlated with acceleration and, to a lesser extent, with cornering. This supports the focus on the ABC dimensions in our peer-comparison treatments. Next to being worker productivity measures in their own right, improvements in either of them also contribute to fuel economy.

¹⁴Appendix section D.1 provides detail on the estimation of σ_r and section D.2 contains the corresponding tables for the ABC dimensions.

4 Experimental Design

4.1 Time Path

Figure 1 depicts the timeline of the study. First, we use the old on-board system to establish a long baseline of fuel consumption, starting in January 2015. At this stage, drivers are not informed about the upcoming feedback, nor that they are being monitored. The new EOBR system enables the collection of comfort dimensions baseline data in the months September and October 2015. The company sent promotion material about the EcoManager-project to the different locations on October 5, 2015. The project was officially launched with a kickoff event at November 9, 2015. At this date, the LED-array in the buses is also switched on, providing drivers with some instant feedback.¹⁵ At the event, all drivers were informed about the digital monitoring and the introduction of monthly individualized feedback reports starting in December 2015.

Peer-comparison feedback The second period (Nov. 9-Dec. 15, 2015) is used to disentangle effects of the announcement and LED activation from the feedback effect. In the third period (Dec. 15, 2015-Nov. 15, 2016) drivers receive their monthly feedback reports with peer-comparison feedback. Finally, the post-experimental period (Nov. 15, 2016 - Jan. 31, 2017) starts with a one-time notification to the drivers that the peer-comparison messages are no longer included in the reports.¹⁶

Previous research has shown that workers adjust their effort in response to a feedback announcement, even though they have not yet learned any new information from the first feedback round (Blanes i Vidal and Nossol 2011). The company's decision to separate these events is a convenient feature of our research setting. Drivers were informed during the announcement period that the feedback will not be used in formal evaluations. This

¹⁵The LED-array contains eight LEDs: three green, two amber and three red. The green LEDs illuminate when the driver is in the 'sweet spot zone', determined by the (vehicle dependent) rotations per minute of the engine. The LEDs indicate the occurrence of an ABC event by flashing three times one second. As these events can only be timed when an action by a driver exceeds the threshold, any LED-array indication happens ex post.

¹⁶The precise text of this message is as follows (translated from Dutch): "Dear colleague, starting this month, this report will no longer include information about your performance relative to your colleagues". This message was part of the report that was distributed in November 2016 to all drivers that were part of the treatment conditions with peer-comparison feedback (all drivers except those in the control condition).

may rule out career concerns as an alternative explanation, but note that it runs counter to the firm's objectives to follow through on this claim (Hölmstrom 1979).

Apart from the feedback programs under consideration, no other incentives were used by the company to promote conservation efforts among workers. In the spirit of Barankay (2012), the one-time notification message is included at the end of the experiment in order to examine the effect of a withdrawal of peer-comparison messages.

In-person coaching The face-to-face coaching program that runs in parallel starts around the kickoff event in November 2015. Most drivers receive their first coaching in the weeks following the kickoff event.¹⁷ During this period, the company reserved extra time for the coaches to ride along with drivers and to answer questions related to the upcoming feedback. Coaching intensity gradually decreases until it levels off after the first feedback report in mid December 2015. In a few cases, drivers participated in additional coaching sessions (55 drivers, 18% of all coached drivers). We control for these additional sessions in our analyses. We have complete coach logs for the period till April 30, 2016. Some coaches indicated that they no longer provided or kept track of coaching after April 2016. For this reason, we restrict attention to the period till April 30, 2016, in our evaluation of the coaching program. Thirty-two drivers (10% of all coached drivers) received coaching prior to the feedback announcement.

4.2 Peer-Comparison Treatments

Fueled by the conviction that the biggest gains in fuel-efficient and comfortable driving can be made when behaviors with the largest room for improvement are targeted, the company wants the peer-comparison feedback messages to emphasize the dimensions on which the driver can improve. The treatment variation in peer-comparison messages is integrated into the monthly feedback report received by all drivers.¹⁸

Drivers are randomly assigned an experimental condition, stratified along the dimensions of base location, gender, and years of service at the company. We construct reference

¹⁷See Figure A4 of the online Appendix.

¹⁸A sample feedback report is provided in Figure A2 of the online Appendix.

groups in which driver performance on each comfort dimension is compared to colleagues with the same base location and treatment status.¹⁹ This creates a natural and homogeneous comparison group for drivers in which competition is likely to generate strong incentives (Lazear and Rosen 1981, Delfgaauw et al. 2013). The comfort dimensions are disaggregated measures of driving behavior over which drivers have a strong direct influence, thereby making the feedback as concrete and useful as possible to the recipients.

At the start of each month, the company shares with us a summary of each driver's performance during the previous month. We use this information to assess how a driver performed compared to his/her peers and to assign peer-comparison messages.²⁰ Dependent on treatment assignment, a number of negative (positive) messages are provided if a driver belongs to the bottom 50% (top 25%) of the reference group.

Treatment T1 [0n0p] is the control condition with no peer-comparison messages. In treatment T2 [1n0p], one negative message is provided if drivers underperform on a particular dimension. That is, they are explicitly informed that they rank poorly compared to peers and are encouraged to improve. In T3 [1n1p], drivers additionally have a chance of receiving one positive message. In this case, they are made aware of their good ranking and are encouraged to keep up the good work. If a driver performs poor (or well) on multiple dimensions, one will be randomly chosen. Finally, in T4 [3n0p], drivers run the risk of receiving corrective feedback on all comfort dimensions. Using T3 [1n1p] as an example, the precise (translated) text of the messages reads as follows:

Dear colleague,

You are doing excellent on this dimension!

In terms of braking, you belong to the bottom 50 percent of the bus drivers in your location.

You can improve on this dimension!

In terms of taking corners, you belong to the top 25 percent of the bus drivers in your location.

¹⁹This is because pre-treatment information revealed that high and low scores are occasionally concentrated in base locations. Limiting peer-comparison groups to drivers with the same treatment status ensures that reference groups are relatively small – such that drivers have a reasonable chance of earning (avoiding) a positive (negative) message – and avoids indirect treatment interference.

²⁰The performance summary contains information on the bus-specific percentile rank of the driver on each driving dimension (compared to all drivers in the concession area who also operated on that bus type in the previous month). The final percentile rank for each driving dimension is the sum of the percentile ranks of the driver on each bus type, weighted by the number of kilometers driven on that bus type in that month. Within a reference group, a driver's final percentile rank determines how (s)he has performed compared to his/her peers.

A printed version of the report is delivered around the 15th day of each feedback month via the team manager or pigeonhole. Drivers in the control condition receive the same feedback report but without the targeted messages, so as to account for general feedback effects.²¹ The report contains general feedback in the form of a letter score, ranging from A (highest score) to D (lowest score) on the comfort dimensions and fuel economy. Furthermore, it contrasts the overall score of the individual driver with the score of his or her base location. Table 3 summarizes the experimental conditions.

At this point, it is important to stress that the treatments condition on the eligibility to receive negative (and positive) peer-comparison feedback but not on the actual exposure. For example, among individuals in treatment group T2 [1n0p], only about 70% of the drivers receive a negative message in a given feedback round because they score lower than half of their peers on at least one of the three comfort dimensions. In case they perform poorly on multiple dimensions, one is selected randomly for peer-comparison feedback. The remaining 30% performs well on all dimensions and is therefore not notified with a message. Hence, the treatment effects that we present show the effect of treatment eligibility. They are conservative estimates of the effect of exposure to peer-comparison feedback as only part of the group actually receives these messages in a given month. For each driving dimension, there is considerable month-to-month variation in the group of drivers in the top-25% and bottom-50% group. While most drivers move in and out, some drivers are never in the top (bottom) part.²²

Table 4 summarizes per experimental condition the data in final analysis sample and reports the outcome of balance tests. The *p*-values show that driver pre-experimental performance in terms of the outcomes fuel economy and ABC events is well-balanced across the experimental groups. A comparison of a rich set of trip-level and bus-type characteristics also reveals no differences across experimental groups, indicating that drivers in

²¹Working with an uninformed control group is not possible due to company policies requiring that every driver should at least receive some feedback. By handing out reports to drivers in the control condition, we embed the experimental variation more naturally and explicitly recognize and control for Hawthorne and general feedback effects.

 $^{^{22}}$ For instance, on acceleration, 19% of the treated drivers is never in the bottom-50% (and 16% always); 42% are never in the top-25% (and 9% always). Outcomes are similar for braking and cornering. Online Appendix D.4 gives a detailed overview per treatment condition of the number of messages send per month and the driving dimensions targeted.

the different treatment groups on average have been exposed to very comparable driving conditions.²³ Drivers are on average 54 years old and work for 20 years at the company. Most drivers are male (89%). The average trip had a length of 31 km and was typically driven in rural areas (84%).

In sum, the detailed data allow for precise identification of good and bad performers in every feedback round. The peer-comparison messages are subsequently intended as a means to assist drivers in offering guidance on where to improve or maintain performance. They are updated every round to inform about progress and to avoid drivers from slacking off. The treatment variation enables us to vary the intensity of the corrective and positive feedback drivers receive.

4.3 In-Person Coaching

In parallel, the company initiated a coaching program. Six experienced drivers (one for each base location) were recruited as coaches based on their track record of driving behavior. All coaches participated in a training on how to approach drivers and how to communicate feedback. Since coaches are bus drivers themselves, there is only limited time available for coaching activities (about one day every two weeks).²⁴ Furthermore, because of the hop-on hop-off approach to on-the-road coaching, a coach's previous session determines the choice set for the next. This makes random allocation of coaching sessions at the driver-trip level impossible. At the same time, it is next to infeasible for coaches to target specific drivers, also because coaches have no access to the individual feedback reports and hence cannot target drivers with poor scores. We will provide empirical support for the view that the assignment of drivers to coaching is the outcome of a quasirandom process.

In a coaching session, a coach rides along with a bus driver for a portion of the driver's shift. This allows the coach to personalize the feedback and to direct attention to the driver-specific issues at hand. A session is not announced to the driver beforehand. The coach writes down examples of what goes well and wrong and identifies obstacles that may

²³For each of the dimensions along which we stratified (base location, gender, years of service), $p \ge 0.99$.

 $^{^{24}}$ Coaches can decide which day they use for coaching. They vary the day of the week such that every driver has a chance of being coached.

hinder driver performance, such as sharp corners. Due to the presence of passengers, there is no or limited interaction between the driver and the coach during the ride. The coach provides feedback once the trip is completed and passengers have left the bus. The trip is reconstructed using the written-down examples. Both personal and general advice are offered that focus on fuel consumption, punctuality and the ABC dimensions.²⁵ Drivers are treated as equals and feedback is delivered in a constructive and positive manner.

Coaches maintain a detailed log of their activities, allowing us to pinpoint when and how often drivers are coached. We use these logs to pin down the coaching date. To check whether the assignment of coaching sessions is quasi-random and not based on preselected criteria, we compare for each outcome variable (fuel economy and ABC) the mean baseline performance of drivers who have received their first coaching and non-coached colleagues with the same base location. Table 5 verifies balancing on multiple baseline outcome performance measures and covariates. We present both the standard *p*-values and the ones adjusted for the problem of multiple hypothesis testing using the Bonferroni and Holm correction. Only for morning and evening rush hours we find statistically significant differences. These differences merely reflect that coaches tend to start their work early in the morning. For none of the other variables, we find differences that are even close to significance, especially once we take into account the problem of multiple hypothesis testing. This supports the view that the implementation of the coaching program exhibits a quasi-random order of phase-in.

4.4 Data Collection and Sample Construction

The EOBRs are installed in all three bus types the company operates. The VDL bus is most commonly used, accounting for about 75% of all trips performed. Intouro buses are mainly used for routes with a long travel distance. Two specific features importantly distinguish the IRIS bus from the other bus types. First, both the VDL and Intouro buses have diesel engines, but the IRIS bus runs on natural gas. This implies that for trips completed with an IRIS bus no records on fuel economy are available. Second,

 $^{^{25}{\}rm These}$ notes are not included in the logs, so unfortunately we do not know exactly what the coached has conferred with a driver.

whereas the VDL and Intouro buses are used by drivers in all base locations, the IRIS bus is only used by drivers in the largest and most urbanized base location. Hence, the treatment effects on the outcomes fuel economy and ABC events are estimated on the sample of trips completed by either a VDL or Intouro bus.

All 409 tenured drivers are included in our research design. Drivers with a temporary contract, 67 in total, are excluded because their behavior is only observed for short and irregular time spans. The trip-level observations in the final sample are matched with driver, trip, and daily weather characteristics.²⁶ We use this sample when we analyze the impact of coaching and peer-comparison feedback on a driver's relative ranking. To keep the analysis succinct, we present full estimation results for fuel economy and acceleration in the main text and relegate some findings for braking and cornering events to the online appendix. We will however highlight any important qualitative differences in treatment effects for acceleration and the outcomes braking and cornering when they arise.²⁷

5 Results

We first present the results of the written feedback program with the peer-comparison messages (5.1), followed by the effects of the in-person coaching program (5.2). Section 5.3 examines the interference between coaching and the written feedback program.

5.1 Feedback Reports

This section reports the effects of the peer-comparison feedback program. To identify this effect, we estimate the following difference-in-differences (DID) regression specification:

$$Y_{its} = \beta \cdot \text{postannounce}_i + \sum_{j=1}^{4} I\{T_i = j\} \cdot (\tau_j \cdot \text{postfeedback}_{it} + \gamma_j \cdot \text{postexperiment}_{it}) + X_{its} \cdot \theta + \mu_i + \kappa_b + \upsilon_t + \zeta_{bt} + \xi_r + \upsilon_{its}.$$
(1)

²⁶Online Appendix A details the steps we have taken to construct the final sample.

²⁷From the ABC dimensions, we selected acceleration because of the higher average number of events in this dimension (Table 2) and the absence of intermediate changes in threshold settings (Table A2).

The dependent variable Y_{its} is the outcome variable of interest (fuel economy or ABC), indexed by driver (i), time in days (t), and the bus trip (s). In addition, the specification includes a vector X_{its} that contains the control variables listed in Table 1. A rich set of dummy variables controlling for driver (μ_i) , bus type (κ_b) , day (v_t) , bus type interacted with day (ζ_{bt}) , and route (ξ_r) fixed effects completes the specification.²⁸ Throughout, we use robust standard errors clustered at the driver level to account for within-driver correlation patterns in the error term (Bertrand, Duflo and Mullainathan 2004). Importantly, because coaching takes place in parallel to feedback, a post-coaching dummy variable is included in the controls. In addition, the dummy variable $postfeedback_{it}$ takes on the value one when the first feedback report has been delivered to driver i and is zero otherwise. This definition makes no selection on the actual reading of the report. From a policy perspective, this is useful because it captures the aggregate performance of the treatments when applied to an eligible population (Allcott 2011).²⁹ The dummy variable $postannounce_{it}$ equals one once a driver is informed about the upcoming EcoManager campaign, and zero otherwise; the dummy $postexperiment_{it}$ equals one once the feedback report with the final notification message has been received, and zero otherwise.

The treatment indicator $T_i = j$ when driver *i* is assigned treatment *j*, j = 1, ..., 4. The τ -coefficients then estimate the treatment-specific effects of receiving tailor-made peer-comparison feedback, while the γ -coefficients measure the impact the withdrawal of peer-comparison messages has on performance (Barankay 2012). The β -coefficient captures the aggregate effect of the launch of the campaign and the switching on of the LED-arrays (which happen at the same date) on driving behavior.

Table 6 presents the results. Our preferred specification is reported in columns (2)-(4) and (6)-(8) and controls for being coached and time-variant driving features, such as weather conditions and the number of passengers. For fuel economy, we find a strong and significant reduction of $\beta=0.41$ liters/100km (0.40 σ_r , p < 0.001) following the start

 $^{^{28}}$ By interacting day- and bus type fixed effects, we relax the common trends assumption between bus types to address potential differences over time in the ease (or difficulty) of avoiding ABC events due to different thresholds per bus type. Of course, regressions with day fixed-effects do not include the post announcement and post feedback dummies.

²⁹The start of the post-feedback period may differ per driver due to absence in the month on which the first report is based. A no-report indicator captures drivers operating after 15 December 2015 (first feedback round) but who have not yet received their first report.

of EcoManager. This is the joint effect of the launch-event and the switching on of the LED-arrays in the buses. The distribution of feedback reports generates an additional reduction of, on average, 0.13 liters/100km ($0.13\sigma_r$, p = 0.105). Column (3) shows that these estimates remain qualitatively unchanged but become more significant once driver fixed effects are added.

How does the experimental variation in the dosage of the number and nature of peercomparison feedback messages affect worker productivity? Reassuringly, Table 6 shows no differences in fuel economy between the different treatment groups *before* the first feedback report is distributed. The estimates for the post-feedback dummy variable interacted with treatment indicators show no significant effect of the peer-comparison messages in the text boxes in addition to the general effect generated by the feedback reports. The point estimates across treatments for fuel economy are small in size, ranging from -0.11 to 0.05 liters/100km and are individually and jointly insignificant.

While fuel economy is an important outcome variable, the peer-comparison feedback messages do not mention fuel economy but dissect a driver's relative performance into his/her performance on the disaggregate comfort dimensions acceleration, braking and cornering. The absence of a treatment effect for fuel economy need not imply that there is no effect at these 'lower' levels of driving behavior that are explicitly targeted by the intervention. Table 6 reveals that the pattern of effects for acceleration resembles the pattern for fuel economy: a large and significant effect following the announcement $(0.52\sigma_r)$, a significant but smaller effect when the feedback reports are received $(0.35\sigma_r)$, but again no indication that the text-box variation in the number and nature of peer-comparison messages matters. For braking and cornering, the estimates of the announcement and reception of feedback are $1.23\sigma_r$, $0.00\sigma_r$, and $0.14\sigma_r$, $0.10\sigma_r$, respectively (Table A5).³⁰

In sum, with the exception of braking, the launch of the feedback program and the distribution has a significantly positive impact on fuel economy and all ABC dimensions. Table A14 shows that results remain significant at the p = 0.05-level when we apply a

 $^{^{30}}$ The larger effect on braking is partly due to a change in the threshold setting for braking-events happening around the same time, see Appendix A.1.

Holm correction for multiple hypothesis testing.³¹

The absence of an effect of peer-comparison feedback on conservation efforts among workers is consistent with findings in Blader et al. (2020). They note however that a focus on aggregate effects may mask temporal effects and improved performance among sub-groups of drivers. In our case, estimates of the effects of peer-comparison feedback for each month separately do not suggest the presence of such temporal effects.³² There is no indication that drivers respond differently to the first peer-comparison messages that they receive than to the ones received in later months, for example because they lose attention. What about the possibility that certain sub-groups of drivers are more responsive to the peer-comparison feedback program than others? Given our design feature that only the sub-set of drivers who actually belong to the top-25% or bottom-50% receive a message, it is indeed possible that we overlook some treatment effects among the subgroups that are treated. The treatment estimates presented so far estimate the overall effect of being assigned a peer-comparison feedback treatment condition. This intention-to-treat (ITT) estimate is a conservative estimate of the average effect of actually receiving positive or negative messages. For example, every month only about 70% of all drivers in treatments T2[1n0p] and T4[3n0p] actually receive messages in their textbox.³³

In an explorative analysis, we group drivers on basis of their performance in month m (being in the top-25% or bottom-50%) and (for each group and ABC outcome dimension separately) regress a driver's ranking in month m + 1 on a dummy variable on receiving relative performance feedback on month m performance. The coefficient estimates (reported in Table A10) for cornering all are insignificant. For acceleration and braking, the coefficients for drivers in the bottom-50% are negative and in some cases significant, suggesting that the feedback messages help them to improve their ranking; for drivers in

³¹At first sight, the fuel economy estimates for 'post-experiment' seem to suggest that the withdrawal of peer-comparison messages in the text box completely reverses the improvement in fuel economy achieved by the introduction of the EcoManager program: $|0.554| \sim |0.411 + 0.130|$. However, caution is needed in drawing this conclusion because the post-experimental period is relatively short and the specifications lack day fixed effects to absorb the unobserved day-to-day fluctuations in driving conditions. Also, the post-experiment coefficients for the ABC outcomes do not reflect a rebound effect.

 $^{^{32}\}mathrm{Appendix}$ G.1 contains the coefficient plots of these estimates.

 $^{^{33}}$ In treatment T3[1n1p], about all drivers (97%) have their text box filled with a message, but with variation in whether the box contains only negative feedback (54%), only positive feedback (25%) or a combination of positive and negative feedback (21%). See Table A9 for detailed information on the composition of messages by treatment.

the top-25%, the coefficients are consistently and significantly positive, indicating that their average ranking deteriorates when having received positive feedback.

5.2 In-Person Coaching

To identify the effect of a single on-the-road coaching session on productivity outcomes in the weeks following coaching, we estimate the following DID regression specification:

$$Y_{its} = \delta_0 I\{t = t_i^c\} + \sum_{\tau=1}^{10} \delta_\tau I\{t - t_i^c \in (7(\tau - 1), 7\tau]\} + \delta_{10}^+ I\{t - t_i^c > 70\}$$
(2)
+
$$\sum_{\tau=1}^{10} \gamma_{-\tau} I\{t - t_i^c \in [-7\tau, -7(\tau - 1))\} + X_{its} \cdot \theta + \mu_i + \kappa_b + \upsilon_t + \zeta_{bt} + \xi_r + \epsilon_{its}.$$

As before, the dependent variable Y_{its} denotes the outcome of interest, the same set of control variables as in equation (2) is included and standard errors are clustered at the driver level. Day t_i^c denotes the specific day at which driver *i* is coached; recall that because of the phase-in design of the coaching program, drivers are coached at different days. The regressors include indicator functions $I(\cdot)$ to estimate the impact of coaching at: *a*) the day of coaching (coefficient δ_0); *b*) the first ten weeks following coaching (postcoaching coefficients $\delta_1, \ldots, \delta_{10}$), and *c*) the ten weeks preceding coaching (pre-coaching coefficients $\gamma_{-1}, \ldots, \gamma_{-10}$). The coefficient δ_{10}^+ absorbs any impact of coaching more than 10 weeks after the day of coaching.³⁴

Figure 2 shows the temporal effects of coaching by plotting the pre- and post-coaching coefficients effects for the fuel economy and ABC outcomes. For fuel economy and acceleration, we observe a strong and immediate effect of coaching: on the day of coaching the fuel need reduces by 0.6 liters/100km ($0.58\sigma_r$) and the number of acceleration events by 1.1 events/10km ($0.50\sigma_r$). These effect sizes are respectively about 1.5 and 1.0 times the impact of the start of EcoManager. These effects persist for about seven to nine weeks. This suggests that, as time progresses, coaching effects decay and drivers seem to fall back into old driving habits.³⁵ We also observe an effect of coaching for braking and cornering,

³⁴Observations more than 10 weeks before coaching are the omitted period, the estimated δ -coefficients in Figure 2 show the average effect relative to this baseline period.

³⁵This fits into the body of evidence showing that in many domains, it is hard to induce persistent

but these effects are much less pronounced and not (braking) or less (cornering) significant because of the lower baseline number of events (see Table 2). For none of the outcomes we observe differences in driving behavior in the 10 weeks prior to coaching, which lends support to our earlier conclusion that the selection for a coaching session is quasi-random and not based on prior performance.

Table 7 reports the main coefficients of regression specifications that take the entire period preceding coaching as the baseline period. Next to the standard p-values, we also report p-values that apply a Bonferroni and a Holm correction for multiple hypothesis testing (MHT). These are conservative methods to adjust for the fact that we consider the impact of coaching on four different outcome variables and three different time periods.³⁶

The regressions reveal that the largest improvements are observed on the day of coaching and with all adjusted *p*-values < 0.02: fuel economy improves by 0.61 liters/100km $(0.55\sigma_r)$, acceleration, braking and cornering by $0.48\sigma_r$, $0.11\sigma_r$ and $0.10\sigma_r$, respectively. For all outcomes except braking, we identify a short-run persistence effect in the first week following coaching. Only for acceleration, an effect is identified for the entire post-coaching period.

5.2.1 Robustness Check: Heterogeneity in Coach Quality

Coaching is provided by a small number of six coaches. One potential worry then is that the observed average treatment effects are not caused by an inherent feature of in-person coaching that is independent of who coaches, but is instead due to one or two coaches with idiosyncratic coaching qualities that are hard to copy. In that case, the data would not allow us to draw the general conclusion that in-person coaching improves worker productivity. We cannot directly compare differences in the way our six coaches provided feedback to drivers because we lack this information. We can however estimate the treat-

changes in habits (Brandon, Ferraro, List, Metcalfe, Price and Rundhammer 2017).

³⁶The Bonferroni multiplicity-adjusted p-values are obtained by multiplying the unadjusted p-values by the number of hypotheses (12); the Holm multiplicity-adjusted p-values are obtained by ranking the unadjusted p-values from largest to smallest and to multiply each unadjusted p-value with its rank. Due to our stratified design, we cannot apply the less conservative MHT correction method developed by List, Shaikh and Xu (2019) that assumes simple random matching. When the joint dependence between the individual test statistics is positive (which is likely in our case given the positive correlations in Table 2) the latter method has a greater ability to detect false null hypotheses than the Bonferroni and Holm method.

ment effect of each individual coach by considering the sub-sample of drivers instructed by that coach. When there is substantial heterogeneity in the quality of instructions given by the coaches, this should result in between-coach differences in treatment effects.

Figure 3 shows these coach-level treatment effects of in-person coaching for the outcome fuel economy.³⁷ Despite the fact that the estimates are less precise due to the smaller sub-samples, the pattern is remarkably consistent across coaches: on the day of coaching, for all coaches the point estimate of fuel savings is in the range [-0.7, -0.4] liters/100km.³⁸ The diminishing and eventually vanishing of this effect in the seven to nine weeks following coaching is common to all coaches. Based on this evidence, we conclude that the observed effect can be attributed to features inherent to in-person coaching.

5.2.2 Treatment Heterogeneity

Next we address whether there is heterogeneity in driver responses to coaching. The literature on peer effects in educational outcomes suggests that the effect of coaching may be heterogeneous, depending on a driver's own past performance. In this section we address the open question whether this result carries over to non-educational contexts. We take the following non-parametric approach. For a driver coached in month m, we compare the driver's relative performance in productivity outcome y the month before (m-1) and the month (m+1) following coaching. We thus ignore a driver's relative performance in the month in which (s)he has been coached. We do this for all four productivity measures. Of course, because of reversion to the mean, there is a tendency for drivers who by chance attain a particularly high (low) ranking in month m-1 to have a lower (higher) ranking in month m+1. To account for this statistical phenomenon, we use the change in ranking non-coached drivers experience from month m-1 to m+1 as a benchmark against we evaluate the change in ranking of drivers coached in month m.

Figure 4 plots for both groups the change in ranking. For non-coached drivers, the shaded area represents the local polynomial estimates of the relation between the ranking

³⁷Figures A6-A8 in the appendix show the coach-level treatment effects for the ABC dimensions.

 $^{^{38}}$ Estimates for coach # 3 are ignored. These estimates are very imprecise because this coach operates in the urban area with IRIS buses for which fuel economy is not recorded.

in months m-1 and m+1, along with a 95% confidence interval.³⁹ We fit separate polynomials for non-coached drivers part of the top-25%/bottom-50%/remaining group in month m-1. Due to the reversion to the mean effect, the slope of each of these polynomials is less than one. The plots show clear evidence of heterogeneity in the effects of coaching: only drivers at the bottom half of the performance distribution benefit from coaching.⁴⁰ This result holds independent of which productivity outcome is considered (fuel economy or either of the comfort dimensions). The direction of our result is in contrast to the empirical literature on peer effects in education, which predominantly finds that high-achieving students benefit most from the presence of high-achieving peers. Possible explanations for this difference are that high-performing workers in our setting have little room left for further improvement or are less open to a colleague's feedback.

5.3 Treatment Interaction

We conclude with an exploratory analysis on the possible complementarity between inperson coaching and peer-comparison feedback. For this, we utilize the fact that a sub-set of drivers received coaching before receiving written feedback while others received one or more written feedback reports before being coached.

We first consider whether having received the general feedback reports makes drivers more or less responsive to coaching. For fuel economy and acceleration, Figure 5 compares the response to coaching by drivers who did not yet receive feedback on paper with those who did. Although the confidence intervals have become wider because of the smaller samples, a comparison of panels (a) with (b) and (c) with (d) shows for both groups a similar pattern in the effect of coaching, both on the day of coaching as well as in the subsequent weeks. Hence, the effect of in-person coaching does not depend on having received prior feedback on one's performance in written form. We also checked whether the impact of coaching is affected by the treatment variation in the number and nature of peer-comparison messages in the tex box. In line with the non-significant effects of the variation in text-box messages discussed in Section 5.1, we find no effect (see Appendix H).

 $^{^{39}}$ In calculating the weighted local estimate, we use the standard Epanechnikov kernel function. 40 See Table A13 for regression estimates.

¹⁰See Table A13 for regression estimates.

What about the opposite case: do drivers who did already receive in-person coaching respond differently to the peer-comparison feedback messages than those who did not yet receive coaching? To answer this question, we compare the response to the feedback reports by drivers who were coached before the arrival date of the first report (December 15, 2015) with the response by drivers who did not receive coaching at all. For both subsamples, we run the same regression specification as in the previous section. Table 8 shows the results. Coached drivers seem more responsive to the general feedback report ('postfeedback'). Of most interest is the difference in response to the peer-comparison text-box messages. The treatment variation in the number of peer-comparison messages does not generate any observable change in productivity among the group of coached drivers, similar to what we found earlier for the entire sample. However, in the group of drivers that has not yet been exposed to coaching, varying the nature and intensity of feedback does seem to have an effect. Drivers in the treatment group exposed to the highest number of negative feedback messages [3n0p] improve significantly in acceleration (p=0.003), braking (p=0.002) and fuel economy (p=0.041) compared to non-coached drivers that do not receive any peer-comparison messages. For fuel economy and braking, we also find positive effects in the group that is exposed to up to one negative message [1n0p] but at lower levels of significance (p=0.016 and p=0.077, respectively). For none of the outcome variables we find a treatment effect for treatment [1n1p] that mixes negative and positive feedback.

In sum, in-person coaching and peer-comparison feedback seem to interfere in an asymmetric manner: coaching is effective independent of prior exposure to peer-comparison messages but prior coaching renders peer-comparison messages non-effective. One possible explanation is that in-person coaching trumps peer-comparison feedback: once drivers have met a coach who gave them detailed feedback on what they do right and wrong on a trip, they become insensitive to subsequent messages about their relative performance. Our evidence shows no need to limit negative feedback or to mix it with positive feedback.

6 Discussion and Conclusions

Given our precise empirical estimates on the impact of the written feedback and the inperson coaching program on worker productivity, we next discuss the possible channels through which these programs change drivers' behavior. Cassar and Meier (2018) present a theoretical framework in which they distinguish four factors that affect work meaning: the need for autonomy, competence and relatedness and the mission of an organization.⁴¹ Different features of the feedback programs may impact these four dimensions of work meaning. The announcement of EcoManager and the provision of feedback may help to align drivers' beliefs with the (social) mission of the firm. Corrective peer-comparison feedback can help to develop competence, but may also make a driver feel less competent. To avoid the latter, it may work to combine corrective feedback with positive feedback. Intensifying feedback may on the other hand also induce feelings of being monitored and a loss in autonomy. Finally, being coached by an experienced colleague may strengthen the social relation with colleagues, thus benefiting relatedness.

The announcement of EcoManager has a strong and positive impact on all four productivity measures. One possible channel is that the campaign makes the social mission of the firm salient, thereby increasing the workers sense of job meaning. Similar effects have been recorded in fundraising contexts by Grant (2008). From a principal-agent perspective, another possibility is that the announcement triggers reputational concerns – despite the firm's assurance that the feedback information will not be used in formal evaluations (List 2003). In line with evidence that checklists improve worker productivity by serving as a "memory aid" (Jackson and Schneider 2015), it is also possible that the switching on of the LED-arrays in the bus, happening around the feedback announcement date, serves as a permanent memory aid to drive carefully.

Additional regressions show that the announcement effect on fuel economy and acceleration for drivers less than fifty years old is about twice the size of that of other drivers and highly significant.⁴² Figure 6 illustrates this for fuel economy. The lines show per

 $^{^{41}}$ The first three are psychological needs that have been identified by self-determination theory as essential for human motivation, see Ryan and Deci (2000) and references therein.

⁴²The outcome variables are regressed on post-announcement, post-feedback and post-experiment dummies, each interacted with four about equally sized age-categories (aged < 50, 50 - 54, 55 - 59 or ≥ 60).

age, years-of-service or gender category, respectively, the week-dummy coefficients over time (the week before the announcement, week 40, is taken as the baseline). Clearly, younger drivers show a sharper response to the EcoManager launch and the gap with the older drivers never closes (panel (a)). Does this reflect cohort differences in learning or reputational concerns? In case of the latter, we might expect a similar gap to occur if we categorize drivers by the number of years that they are already at the company. We do not observe this (panel (b)), suggesting that the increased saliency of the company's objectives especially resonates with younger drivers.

We find a positive effect of receiving written feedback. The feedback may indeed help drivers to become more competent drivers. Of course, drivers may do better on the dimensions measured because they know that these are monitored by the company. There is the possibility that their performance on unmeasured dimensions of job performance such as friendliness will deteriorate. We have no information on this but also did not hear from the company that the number of complaints increased. No treatment effects for the peer-comparisons in the text-messages are identified, except that not-yet-coached drivers show a larger improvement if they receive the full amount of corrective feedback. When workers receive negative feedback on certain dimensions, it does not increase their performance on these dimensions if the corrective feedback is accompanied by positive feedback on other dimensions.

Different explanations are possible for the strong and immediate impact of coaching. Coaching may improve the driver's competences, improve the worker's alignment with the company's mission, and/or deepen the relatedness to colleagues. We cannot distinguish between these three. However, the decay path tells us that neither the improved alignment with firm objectives, nor the improvement to human capital, nor the closer connection to colleagues is permanent. A social pressure explanation does not fit the pattern because the decay is not immediate. It may be that coaching serves as a memory aid for drivers with limited attention. Hanna, Mullainathan and Schwartzstein (2014) find a similar result for farmers. Farmers change behavior "when presented with summaries that highlight previously unattended-to relationships in the data". Their paper cannot tell whether this Full regression estimates reported in Tables A20-A22. effect remains as their final follow-up is two months after farmers receive this information. Our evidence clearly points out that, at least for bus drivers, the effect is short-lived.

Comparing the written feedback and in-person feedback, it seems that in-person feedback is more powerful but that the repetitive character of the monthly written report is necessary to let the impact last. This is in line with Dusch, Evans, Eze-Ajoku and Macis (2017) and also resonates the recommendations of Oreopoulos and Petronijevic (2018) for feedback provision in educational settings.

To conclude, increasing conservation efforts among individuals is generally seen as lowhanging fruit in the battle to reduce energy consumption. Most existing studies on energy conservation however focus on households. Their results may not apply in corporate settings where workers are in a principal-agent relationship and have no financial stake in energy conservation and where institutional constraints often hinder firms in the use of pay-for-performance plans. Our findings contribute to a growing body of literature on nonfinancial interventions aimed at energy conservation in the workplace. Our analyses show how carefully designed non-pecuniary strategies can improve conservation efforts among workers. One robust outcome of the quasi-experimental variation in being coached is that in-person coaching immediately improves a driver's performance. Especially drivers with the lowest prior performance receive a boost. Although this effect is transient, the decay is not immediate. In the weeks following coaching, 17.52 liter of fuel is saved per coached driver, which amounts to \in 19.27, or \in 60 per day of coaching. This is less than the cost of freeing up an experienced driver to coach, but the benefits may outweigh the cost if the company or passengers sufficiently value the improved comfort or environmental gains. Written performance feedback comes at a lower marginal cost. The reduction in fuel consumption following the announcement and distribution of general feedback reports is 5/6th the effect of coaching on the day of coaching. The additional peer-comparison messages do not have any impact and we find no evidence that managers need to restrain themselves from giving negative feedback.

Our research points to several directions for future research. First, the increased adoption of digital monitoring technologies at the work floor creates a myriad of new opportunities for tailoring feedback to motivate workers. This paper has examined the impact of different feedback channels and variation in feedback intensity, but we reckon that designing and evaluating other data-driven incentives could yield fruitful research. Second, we document important interaction effects between written feedback and in-person coaching and believe that more research should be done to investigate interactions between nonfinancial incentives. Finally, and more in general, the question how conservation efforts can be stimulated when someone else pays the bill is in need of more answers.

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Tables

Dependent variable:]	Fuel econom	у	
-	(1)	(2)	(3)	(4)	(5)
VDL 10m	-1.013***	-1.014***	-0.948***	-0.943***	-0.945***
	(0.029)	(0.029)	(0.028)	(0.027)	(0.016)
VDL 14m	8.910***	8.958***	8.904***	8.935***	8.922***
	(0.165)	(0.158)	(0.145)	(0.146)	(0.136)
Intouro	4.785***	4.808***	4.445***	4.487***	4.483***
	(0.239)	(0.239)	(0.234)	(0.216)	(0.161)
Rush hour 7-10am			-0.349***	-0.350***	-0.248***
			(0.031)	(0.030)	(0.015)
Rush hour 4-7pm			0.334***	0.334***	0.246***
			(0.039)	(0.038)	(0.018)
Non-scheduled trip			0.095	0.077	0.096**
			(0.093)	(0.091)	(0.044)
No. of stops per km.			0.721***	0.750***	0.715***
			(0.087)	(0.086)	(0.083)
Urban trip			0.000	0.278	0.673
			(.)	(1.169)	(0.838)
Trip length (in km.)			-0.023***	-0.025***	-0.024***
			(0.001)	(0.001)	(0.001)
Ln(No. of passengers)			1.263***	1.288***	1.275^{***}
			(0.016)	(0.016)	(0.014)
Punctuality			0.013***	0.010**	0.045^{***}
			(0.005)	(0.005)	(0.003)
Constant	23.716^{***}	23.450***	20.531***	21.274***	21.156***
	(0.053)	(0.057)	(0.134)	(0.182)	(0.166)
\mathbb{R}^2	.279	.291	.409	.43	.514
Number of trip-level observations	533171	533171	533171	533171	533171
Weather dummies	No	Yes	Yes	No	No
Driver fixed effects	No	No	No	No	Yes
Day fixed effects	No	No	No	Yes	Yes
Route fixed effects	No	No	Yes	Yes	Yes

Table 1: Determinants of Fuel Economy

Notes: Dependent variable: Fuel economy in liters/100km. Default categories: Scheduled trips in rural areas outside rush hours completed with a VDL 12m bus. Trip punctuality is the difference in minutes between actual and scheduled driving time. Weather data are collected from a weather station located in the regional capital and are maintained by the Royal Netherlands Meteorological Institute (KNMI). Standard errors are clustered by driver.

***(**,*): statistically different from zero at the 1%-level (5%-level, 10%-level). Standard errors in parentheses.

Table 2: Driver Variation in Fuel Economy and ABC Comfort Outcomes

					Resi	dual correl	ation
Driving dimension	μ	σ_r	c_v	$\Delta(p_{90} - p_{10})$	Acc.	Braking	Corn.
Fuel economy	24.91	1.03	0.04	2.46	0.399	0.083	0.166
Acceleration	10.87	2.22	0.20	4.87		0.268	0.271
Braking	1.68	1.02	0.61	0.93			0.154
Cornering	2.27	1.93	0.85	1.71			

Notes: Fuel economy: liters/100km. ABC dimensions: no. of events/10km. σ_r : residual standard deviation; c_v : coefficient of variation. $\Delta(p_{90} - p_{10})$: difference in performance 90th vs. 10th percentile driver.

Conditions	General feedback	Max $\#$ positive message(s)	Max $\#$ negative message(s)
T1 [0n0p]	Yes	0	0
T2 $[1n0p]$	Yes	0	1
T3 $[1n1p]$	Yes	1	1
T4 [3n0p]	Yes	0	3

 Table 3: Experimental Conditions

$ \begin{array}{ c c c c c c c c c c c c c c c c c c c$		(1)	(2)	(3)	(4)	(5)	(6)	(7)	(8)	(9)	(10)	(11)	(12)
$ \begin{array}{ c c c c c c c c c c c c c c c c c c c$												Joint	t test:
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$ \begin{array}{c c c c c c c c c c c c c c c c c c c $		Mean	S.D.	Mean					S.D.	Mean	S.D.	effec	t = 0
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Let the term of term o	<u> </u>		()		· · · ·		· · ·		· /		· /		
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	Cornering	2.88	(4.93)	2.99	(5.11)	2.85	(5.17)	2.62	(4.60)	3.06	(4.89)	0.16	[0.93]
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$						Demo	manhics						
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	Year of birth	1962	(8.28)	1962	(8.83)		· •	1962	(7.62)	1962	(8.12)	0.01	[1.00]
	Year of employment		()		· /						· /		
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	1 0		()		()		(-)		(-)		()	0.26	L J
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$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	0		· /		· · · ·		· · ·		· · ·				
Number of bus stops 37.84 (8.79) 37.38 (9.09) 38.54 (8.40) 37.93 (8.76) 37.51 (8.99) 0.35 [0.79] % share of rides: - <					· /				· · · ·				
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$\begin{array}{c c c c c c c c c c c c c c c c c c c $	Number of bus stops	37.84	(8.79)	37.38	(9.09)	38.54	(8.40)	37.93	(8.76)	37.51	(8.99)	0.35	[0.79]
$\begin{array}{c c c c c c c c c c c c c c c c c c c $	% share of rides.												
$\begin{array}{c c c c c c c c c c c c c c c c c c c $		19.45		19.34		20.53		18.64		10.31		0.46	[0.71]
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Bus type VDL 75.20 73.64 77.71 75.63 73.88 0.33 $[0.81]$ Bus type Intouro 9.65 10.21 9.34 9.30 9.75 0.10 $[0.96]$ Bus type IRIS 15.15 16.15 12.96 15.07 16.37 0.21 $[0.89]$ Base locations (# drivers)Location 1 12 3 3 3 0.00 $[1.00]$ Location 2 61 16 15 15 0.01 $[1.00]$ Location 3 30 7 8 8 7 0.05 $[0.99]$ Location 4 74 19 18 18 19 0.02 $[1.00]$ Location 5 150 37 38 38 37 0.02 $[1.00]$ Location 6 82 21 20 20 21 0.02 $[1.00]$	5011001	0.0		0.1		0.0		0.0		0.1		0.21	[0.00]
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Base locations (# drivers) Location 1 12 3 3 3 0.00 [1.00] Location 2 61 16 15 15 0.01 [1.00] Location 3 30 7 8 8 7 0.05 [0.99] Location 4 74 19 18 18 19 0.02 [1.00] Location 5 150 37 38 38 37 0.02 [1.00] Location 6 82 21 20 20 21 0.02 [1.00]													
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Location 5150373838370.021.00Location 682212020210.021.00	Location 4	74		19		18		18		19			5 5
Location 6 82 21 20 20 21 0.02 [1.00]	Location 5	150		37		38		38		37			
	Location 6	82											L J
Number of drivers 409 103 102 102 102	Number of drivers	409		103		102		102		102			<u> </u>

Table 4: Descriptive Statistics of Experimental Cond	Table 4: I	Descriptive	Statistics	of Ex	perimental	Conditions	3
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Notes: Unit of observation is the driver. Columns (11) and (12) show F-statistics and [p-values] from a balance test of whether the treatment coefficients are jointly equal to zero. Pairwise t-tests with the control group T1 do not reveal any statistically significant differences in means for any of the variables for any of the treatment groups at the p = 0.10 level. Data are from EOBRs in buses and centralized databases with driver and trip characteristics. Fuel economy in liters/100km. Performance on the comfort dimensions (Acceleration, Braking and Cornering) as the number of events/10km. The pre-experimental period is the period before receiving the first feedback report. Punctuality is the difference in minutes between actual and planned driving time. Distance traveled is measured in kilometers. Number of passengers based on check-ins with public transport cards. VDL and Intouro buses have diesel engines, the IRIS bus runs on natural gas. Morning and evening rush hours are from 7:00-10:00 and 16:00-19:00, respectively. Holiday rides take place during, for example, Christmas, New Year's Eve and school holidays. School rides are along routes with schools and universities as final destinations. Stars indicate a statistically significant difference in means with the control group.

	С	NC	$ \Delta(\text{C-NC}) $	stand. <i>p</i> -value	Bonf. corr.	Holm corr.
Baseline performance						
Fuel economy	25.038	25.247	-0.209	0.0865	1.0000	0.2595
Acceleration	13.132	13.349	-0.217	0.5200	1.0000	1.0000
Braking	3.715	3.789	-0.075	0.7744	1.0000	1.0000
Cornering	1.093	1.189	-0.096	0.2065	1.0000	1.0000
Share of experimental conditions						
T1 (0n0p)	0.260	0.247	0.013	0.8118	1.0000	1.0000
T2 (1n0p)	0.200 0.244	0.261	-0.016	0.7602	1.0000	1.0000
T3 (1n1p)	0.235	0.201 0.228	0.010	0.8968	1.0000	1.0000
T4 (3n0p)	0.260	0.220 0.264	-0.003	0.9532	1.0000	1.0000
14 (biop)	0.200	0.204	-0.005	0.5052	1.0000	1.0000
Demographics						
Year of birth	1962.4	1961.8	0.558	0.3372	1.0000	1.0000
Year of employment	1996.2	1996.3	-0.150	0.8706	1.0000	1.0000
Share of FTE>0.9	0.801	0.776	0.025	0.6205	1.0000	1.0000
Share of female drivers	0.094	0.073	0.020	0.554	1.0000	1.0000
Trip-specific variables						
Punctuality	-2.942	-3.018	0.076	0.2251	1.0000	1.0000
Distance traveled (in km.)	30.564	32.025	-1.461	0.0996*	1.0000	0.3984
Number of passengers	15.035	15.283	-0.248	0.5983	1.0000	1.0000
Number of bus stops	37.934	37.864	0.070	0.9268	1.0000	1.0000
Share of rides:				0.0200		
- Morning rush hours	0.298	0.159	0.139	0.0076***	0.1976	0.0076***
- Evening rush hours	0.125	0.253	-0.127	0.0084***	0.2184	0.0168**
- Weekend	0.031	0.031	0.000	1.0000	1.0000	1.0000
- Fill in	0.004	0.025	-0.021	0.1539	1.0000	0.7695
- Holidays	0.119	0.125	-0.006	0.8839	1.0000	1.0000
- Urban area	0.149	0.146	0.003	0.9366	1.0000	1.0000
- School	0.004	0.004	0.000	0.9954	1.0000	1.0000
Share of rides on bus types						
VDL	0.773	0.755	0.017	0.7427	1.0000	1.0000
Intouro	0.078	0.099	-0.021	0.5555	1.0000	1.0000
IRIS	0.149	0.146	0.003	0.9366	1.0000	1.0000

Table 5: Quasi-Random Coaching: Balancing Tests on Baseline Performance and Non-Performance Descriptives

Notes: Unit of observation is the driver. For every coaching date, the mean baseline performance and nonperformance related variables of drivers who receive their first coaching (C) is compared to that of non-yet-coached colleagues (NC). Reported are the mean values over all coaching dates. Standard *p*-values as well as *p*-values that use a Bonferroni and Holm correction for multiple hypothesis testing are reported. Fuel economy in liters/100km; Performance on the ABC dimensions as the number of events/10km. Fewer events mean better driving behavior. Punctuality is the difference in minutes between actual and planned driving time. Number of passengers is based on check-ins with public transport cards. Morning and evening rush hours are from 7:00-10:00 and 16:00-19:00, respectively. Holiday rides take place during, for example, Christmas, New Year's Eve and school holidays. School rides are along routes with schools and universities as final destinations. Fill-ins are non-scheduled trips whereby a driver replaces a colleague from another base location.

***(**,*) : the corresponding *p*-values are less than 1% (5% or 10%).

Danandant variahle	þ	T I I I I I I I I I I I I I I I I I I I	Find Fronomy			Arcol	<u>A ccalaration</u>	
	(4)			(1)	(1)			(0)
	(1)	(2)	(3)	(4)	(Q)	(0)	(f)	(8)
Post-announcement	-0.305^{***}	-0.411^{***}	-0.367^{***}		-2.250^{***}	-1.154^{***}	-1.229^{***}	
	(0.062)	(0.053)	(0.038)		(0.129)	(0.116)	(0.094)	
T2 $(1n/0p)$	-0.258^{*}	-0.201			-0.328	-0.348		
	(0.154)	(0.125)			(0.277)	(0.249)		
T3 $(1n/1p)$	-0.040	-0.079			0.160	0.025		
	(0.172)	(0.152)			(0.362)	(0.305)		
T4 (3n/0p)	-0.081	-0.121			0.243	0.167		
	(0.164)	(0.134)			(0.284)	(0.256)		
Post-feedback	-0.402^{***}	-0.130	-0.173^{***}		-0.656^{***}	-0.824^{***}	-0.693^{***}	
	(770.0)	(0.080)	(0.062)		(0.159)	(0.168)	(0.142)	
Post-feedback \times T2 (1n/0p)	-0.105	-0.090	-0.026	-0.026	0.045	0.100	-0.097	-0.110
	(0.116)	(0.092)	(0.083)	(0.082)	(0.238)	(0.216)	(0.218)	(0.215)
Post-feedback \times T3 (1n/1p)	-0.013	0.047	0.036	0.023	-0.061	0.083	0.027	0.039
	(960.0)	(0.079)	(0.080)	(0.078)	(0.227)	(0.200)	(0.199)	(0.196)
Post-feedback \times T4 (3n/0p)	-0.082	0.017	-0.021	-0.032	-0.237	-0.117	-0.252	-0.236
	(0.103)	(0.075)	(0.074)	(0.072)	(0.231)	(0.204)	(0.208)	(0.207)
Post-experiment	0.574^{***}	0.554^{***}	0.553^{***}		0.367^{**}	0.142	0.187^{*}	
	(0.080)	(0.062)	(0.055)		(0.142)	(0.119)	(0.104)	
Post-experiment \times T2 (1n/0p)	-0.010	0.018	0.033	0.036	0.114	0.016	0.032	0.029
	(0.130)	(0.093)	(0.070)	(0.077)	(0.220)	(0.187)	(0.149)	(0.149)
Post-experiment \times T3 (1n/1p)	0.048	0.070	0.027	0.040	0.081	0.151	0.065	0.055
	(0.114)	(0.081)	(0.070)	(0.069)	(0.188)	(0.158)	(0.137)	(0.138)
Post-experiment \times T4 (3n/0p)	-0.056	0.050	0.033	0.023	0.017	0.157	0.080	0.060
	(0.115)	(0.084)	(0.070)	(0.076)	(0.198)	(0.162)	(0.140)	(0.140)
Constant	24.639^{***}	22.056^{***}	22.546^{***}	23.984^{***}	10.790^{***}	8.594^{***}	11.868^{***}	11.863^{***}
	(0.110)	(0.104)	(0.080)	(0.181)	(0.217)	(0.194)	(0.191)	(0.259)
\mathbb{R}^2	.0148	.417	.499	.515	.0527	.405	.558	.573
Number of trip-level observations	533172	533172	533172	533172	352887	352887	352887	352887
Controls	N_{O}	$\mathbf{Y}_{\mathbf{es}}$	$\mathbf{Y}_{\mathbf{es}}$	$\mathbf{Y}_{\mathbf{es}}$	N_{O}	\mathbf{Yes}	\mathbf{Yes}	$\mathbf{Y}_{\mathbf{es}}$
Weather dummies	No	$\mathbf{Y}_{\mathbf{es}}$	$\mathbf{Y}_{\mathbf{es}}$	No	N_{O}	\mathbf{Yes}	\mathbf{Yes}	No
Driver fixed effects	N_{O}	N_{O}	$\mathbf{Y}_{\mathbf{es}}$	\mathbf{Yes}	N_{O}	N_{O}	$\mathbf{Y}_{\mathbf{es}}$	$\mathbf{Y}_{\mathbf{es}}$
Day fixed effects	N_{O}	N_{O}	No	$\mathbf{Y}_{\mathbf{es}}$	N_{O}	N_{O}	N_{O}	$\mathbf{Y}_{\mathbf{es}}$
Bus type \times day fixed effects	N_{O}	N_{O}	N_{O}	$\mathbf{Y}_{\mathbf{es}}$	No	No	N_{O}	$\mathbf{Y}_{\mathbf{es}}$
<i>Notes:</i> Identification of the written feedback treatment effects on driving performance. The time period under consideration is from 01/01/2015 until 31/01/2017. Treatments vary in the number of positive and negative peer-comparison messages on the comfort driving dimensions (acceleration, braking, cornering). Messages are terreated in the some that they are only provided if a driver performs relatively near (bottom 50%) or mode (no 25%) compared to a reference error of collearnes. The	dback treatmer e and negative	it effects on dri peer-comparison	ving performanc a messages on t	e. The time p he comfort driv tom 50%) or a	eriod under con ing dimensions (add (ton 25%) of	sideration is fro (acceleration, br	ent effects on driving performance. The time period under consideration is from 01/01/2015 until 31/01/2017. e peer-comparison messages on the comfort driving dimensions (acceleration, braking, cornering). Messages are ever performs relatively near (hottom 50%) or mod (ton 25%) compared to a reference even of collocaries. The	ntil 31/01/2017.). Messages are
post-announcement dummy variable is one in the period	in the period fi	rom November 9), 2015, onwards	(kickoff-event),	zero otherwise.	Drivers are cons	from November 9, 2015, onwards (kickoff-event), set otherwise. Drivers are considered to be in the post-feedback	ne post-feedback
period when uney have received at least one report in the past. For most drivers, this was at 15 December 2019 and after. The post-experimental period starts at november 15, 2016, when it was communicated to the treated drivers that they will no longer receive peer-comparison messages. The dependent variable fuel economy is measured in	e report in une l e treated drivers	past. For most d s that they will	no longer receive	t 15 December peer-comparise	and auter. in messages. The	t ne post-expern e dependent vari	nental period sta able fuel econom;	rts at ivovember y is measured in
liters/100km and acceleration as the number of events per 10 kilometers. Standard errors are clustered by driver. Controls include: travel distance, route dummies, number of masseneers and hus store, and dummies for hus true, moming and evening masseneers non-scheduled rides and having been coached. Weather dummies: daily temperature	r of events per	10 kilometers. Standard avening	andard errors ar	e clustered by d	river. Controls in	nclude: travel dis or coeched Weat	tance, route dum امت ماسسامه، ما	unies, number of
passengers and the stops, and dummes tot bus type, monting and evening their nous, non-scheduled trues and having been concred. Weather dummes, of wind and rainfall. A no-report indicator is included to capture drivers operating after December 15, 2015, but who have not yet received their first report.	included to cap	ture drivers ope	rating after Dece	-scheduled flues	but who have no	t yet received th	neir first report.	шу vermperavure,
***(**,*): statistically different from zero at the 1%-level (5%-level, 10%-level). Standard errors in parentheses	at the 1%-level	(5%-level, 10%-l	evel). Standard	errors in parent	leses.			

Table 6: Targeted Peer-Comparison Feedback Effects on Driving Performance

Outcome		Coefficient		p-values	
			Unadj.	Bonf.	Holm
Fuel economy	day of coaching	-0.6086	0.0000***	0.0000***	0.0000***
	day 1-7 after coaching	-0.3124	0.0000^{***}	0.0000^{***}	0.0000^{***}
	post-coaching	-0.1235	0.0311^{**}	0.3732	0.2799
Acceleration	day of coaching	-1.0803	0.000***	0.0000***	0.0000***
	day 1-7 after coaching	-0.6885	0.0000^{***}	0.0000^{***}	0.0000^{***}
	post-coaching	-0.4469	0.0002^{***}	0.0024^{***}	0.0012^{***}
Braking	day of coaching	-0.1094	0.0013^{***}	0.0156^{**}	0.0091***
	day 1-7 after coaching	-0.0244	0.3264	1.0000	1.0000
	post-coaching	-0.0159	0.5294	1.0000	1.0000
Cornering	day of coaching	-0.1901	0.0000***	0.0000***	0.0000***
	day 1-7 after coaching	-0.1043	0.0027^{***}	0.0324^{**}	0.0216^{**}
	post-coaching	-0.0473	0.2118	1.0000	1.0000

Table 7: In-Person Coaching Effects on Driving Performance

Notes: Identification of in-person coaching effects on driving performance. The time period under consideration is the period for which we have complete logs available from all coaches (01/01/2015-30/04/2016). The dependent variable fuel economy is measured in liters/100km; acceleration, braking and cornering as the number of events per 10 kilometers. Reported are the DID effects of coaching on the day of coaching, in the first week following coaching and in the entire post-coaching period following coaching. Standard *p*-values as well as *p*-values that use a Bonferroni and Holm correction for multiple hypothesis testing are reported. Standard errors are clustered by driver. Full regression results are reported in Tables A11 and Table A15 in the appendix. ***(**,*) : the corresponding *p*-values are less than 1% (5% or 10%).

Dependent variable:	Fuel	Economy	Acce	eleration	B	raking	Co	rnering
	Coached	Non-coached	Coached	Non-coached	Coached	Non-coached	Coached	Non-coached
	(1)	(2)	(3)	(4)	(5)	(6)	(7)	(8)
Post-announcement	-0.455^{***}	-0.338***	-1.261***	-1.090***	-1.336***	-1.302***	-0.225***	-0.328***
	(0.072)	(0.068)	(0.168)	(0.175)	(0.048)	(0.050)	(0.051)	(0.059)
Post-feedback	0.171^{*}	-0.023	-0.673***	-0.335	-0.159***	0.199^{***}	-0.157**	-0.098
	(0.100)	(0.105)	(0.249)	(0.202)	(0.051)	(0.057)	(0.066)	(0.107)
Post-feedback \times T2 [1n/0p]	0.117	-0.379**	0.260	-0.409	0.101	-0.130^{*}	0.061	-0.047
	(0.135)	(0.155)	(0.356)	(0.318)	(0.071)	(0.073)	(0.111)	(0.116)
Post-feedback \times T3 [1n/1p]	0.082	-0.117	0.183	-0.512	0.056	-0.088	0.075	0.081
	(0.107)	(0.181)	(0.284)	(0.417)	(0.068)	(0.106)	(0.090)	(0.119)
Post-feedback \times T4 [3n/0p]	0.064	-0.304**	0.242	-1.012^{***}	0.095	-0.282***	0.139^{*}	-0.226
	(0.101)	(0.147)	(0.246)	(0.326)	(0.076)	(0.090)	(0.075)	(0.137)
Post-experiment	0.537^{***}	0.476^{***}	0.220	0.161	0.066	-0.003	-0.026	-0.092^{*}
	(0.082)	(0.086)	(0.163)	(0.188)	(0.045)	(0.042)	(0.035)	(0.051)
\mathbb{R}^2	0.498	0.502	0.561	0.519	0.233	0.219	0.379	0.407
# trip-level observations	232597	136482	164593	94667	164593	94667	167632	95938

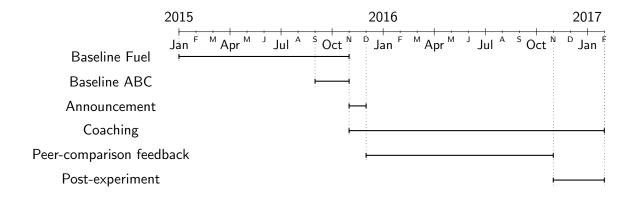
Table 8: Impact of Peer-Comparison Feedback, Conditional on Coaching

Notes: The estimated regression specification includes the same controls, weather dummies and driver fixed effects as the specification estimated in columns

(3) and (7) of Table 6. Full regression estimates reported in Tables A16-A19. ****(**,*): statistically different from zero at the 1%-level (5%-level, 10%-level). Standard errors in parentheses.

Figures

Figure 1: Timeline Study



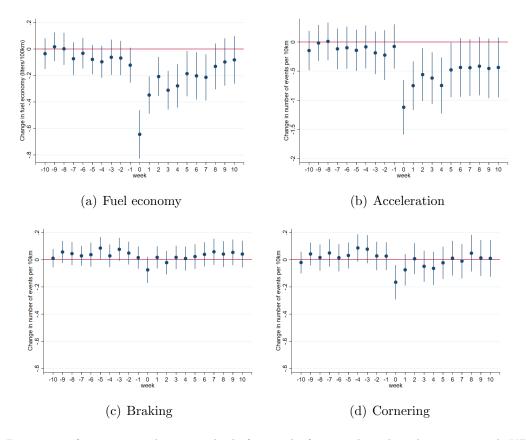


Figure 2: Temporal Effects In-Person Coaching

Notes: Driving performance in the 10 weeks before and after coaching based on trips with VDL and Intouro buses. The day of coaching itself is point 0 on the x-axis. The vertical spikes indicate 95% confidence intervals. The dependent variable fuel economy is measured in liters/100km and acceleration, braking and cornering as the number of events per 10 kilometers. Standard errors are clustered by driver. Controls include: travel distance, number of passengers and bus stops, dummies for non-scheduled rides, additional coaching sessions, bus types, morning and evening rush hours, and the interaction of bus type and day fixed effects. Coaches themselves are excluded from the sample.

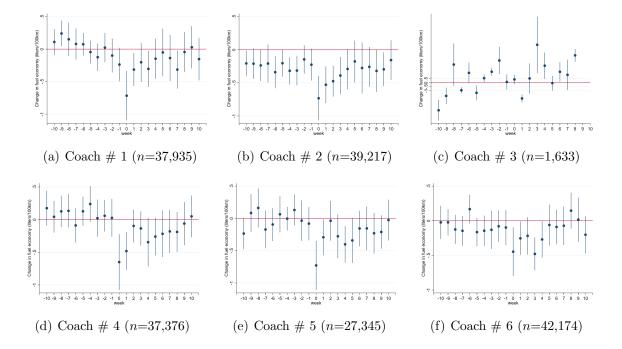


Figure 3: Temporal Effects In-Person Coaching at Coach Level: Fuel Economy

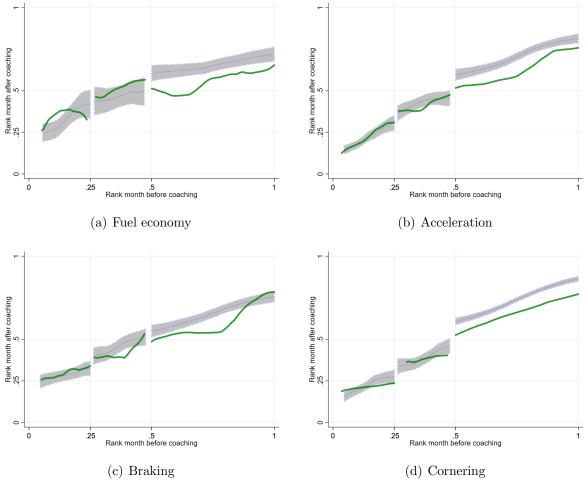
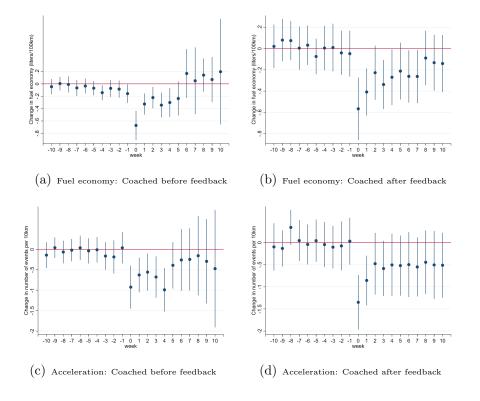


Figure 4: Differential Treatment Effects of Coaching

Note: Green (blue) : Average ranking of drivers (not) coached in month m in month m-1 (x-axis) and month m+1 (y-axis). The lines plot the non-parametric piece-wise local polynomial fit using an Epanechnikov kernel function. For non-coached drivers, the 95% confidence interval (shaded area) is shown as well.

Figure 5: Impact In-Person Coaching With and Without Having First Received Written Feedback Reports



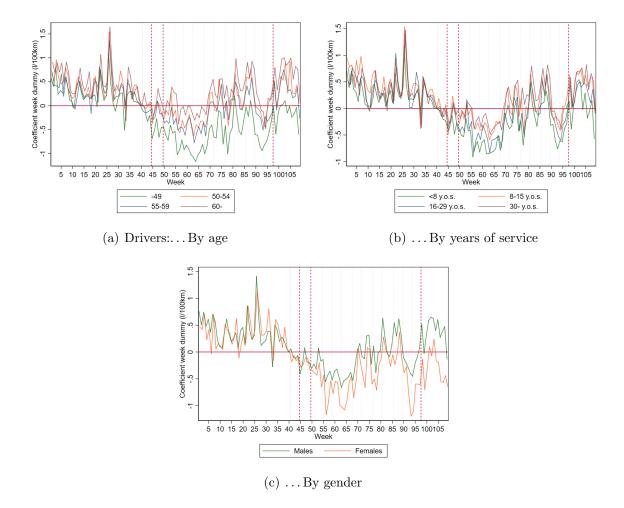


Figure 6: Response in Fuel Economy to Written Feedback per Sub-Group of Drivers

Notes: Coefficients week dummies on trips with VDL buses. The time period is from 01/01/2015 to 31/01/2017. The dashed lines indicate the launch date of the EcoManager program [09/11/2015], the distribution of the first feedback report [15/12/2015] and the distribution of the report with the final notification message [15/11/2016]. The dotted lines indicate the distribution of the intermediate monthly feedback reports. The first dotted line indicates the moment EcoManager promotion materials are send to the locations [05/10/2015]. Controls include: weather conditions, travel distance, route dummies, number of passengers and bus stops, having received coaching, and dummies for bus type, morning and evening rush hours and fill-in rides. A no-report indicator is included to capture drivers operating after 15/12/2015 (first feedback round) but who have not yet received their first report.

Online Appendix: Not for Publication

Improving Worker Productivity Through Tailored Performance Feedback: Field Experimental Evidence from Bus Drivers

Gert-Jan Romensen and Adriaan R. Soetevent

A Construction Final Sample

The initial sample consists of 1,278,913 trip-level observations. Table A1 summarizes the steps taken to arrive at the final sample that is used in our analysis. The absence of a bus identifier has been the most important reason to discard observations (22.7% of the initial sample). Without such an identifier, it is not possible to link the trip to the outcome data of interest (fuel economy and ABC dimensions). Observations are also dropped when there are technical mismatches between the bus type and EOBR data (about 5%) or when there are between-trip inconsistencies at the driver level (3%). We also exclude extreme outcomes regarding punctuality or outcomes that suggest a temporary technical recording problem in the EOBR (< 0.5 percent). These comprise observations of fuel economy being less than one or more than eight (1,259 obs; 0.10%), a difference of more than one hour between actual and planned driving time (156 obs; 0.01%) and outcomes that are more than five standard deviations above the means of the ABC dimensions (4,003 obs; 0.31%).

		% share of full sample
Full sample	$1,\!278,\!913$	
Reason for dropping observation:		
Duplicate observation (in terms of all variables)	(6,762)	0.50
No bus identifier	(290,737)	22.73
Bus type not eligible for EOBR	(34, 870)	2.73
Error message from EOBR	(31, 118)	2.46
Within-driver obs. with the same departure date/time	(37, 575)	2.94
Very short rides (less than 1 kilometer)	(29,588)	2.31
Punctuality: more than 1 hour	(156)	0.01
Unreasonable outcomes of dependent variables:		
- Fuel eeconomy: less than 12.5 or more than 100	(1,259)	0.10
- ABC dimensions: more than 5 SDs above the mean	(4,003)	0.31
	842,845	

Table A1: Cleaning Steps for Sample Construction

Notes: Fuel economy is measured in liters/100km. The ABC comfort dimensions are the number of events per 10 kilometers (fewer events mean better driving behavior). Trip punctuality is the difference between actual and planned driving time.

The company uses different bus types. For the trips in the final sample, Table A2 shows which bus type is used. The table reveals that the vast majority of trips (> 63%) is

completed with a VDL bus. More specifically, over half of the trips are completed with the VDL 12 meter bus. The IRIS bus is used in about 30% of all trips. Most of these IRIS buses run on natural gas, which implies that no fuel economy score is recorded for these trips. These gas buses are almost exclusively used in the province's capital because of the lower CO_2 emissions of natural gas compared to diesel. A small minority (<10%) of trips is completed with a third bus type, the Mercedes Intouro.

Bus type	length (m)	fuel type	No. trips	% share of full sample
VDL AMBASSADOR ALE 106	10.6	diesel	76,815	9.11
VDL CITEA LLE 120	12.0	diesel	452,375	53.67
VDL CITEA XLE 145	14.5	diesel	5,830	0.69
IRISBUS CITELIS 10,5 M	10.5	diesel	22,882	2.71
IRISBUS CITELIS 10,5 M CNG	10.5	natural gas	70,341	8.35
IRISBUS CITELIS 12 M	12.0	diesel	41,048	4.87
IRISBUS CITELIS 12 M CNG	12.0	natural gas	113,731	13.49
MERCEDES BENZ INTOURO	13.0	diesel	59,823	7.10
Analysis set			$842,\!845$	
VDL			535,020	63.5
IRISBUS			248,002	29.4
INTOURO			59,823	7.1

Table A2: Fleet Information

Table A3 shows per bus type when the start of the recording of data. Data on fuel economy are available for a somewhat longer time period than the outcomes on the ABC-comfort dimensions.

		01	01
	VDL	Intouro	IRIS
Fuel consumption	1 Jan. 2015	1 Jan. 2015	n.a.
Acceleration	1 Sep. 2015	9 Nov. 2015	1 Sep. 2015
Braking	1 Sep. 2015	9 Nov. 2015	1 Sep. 2015
Cornering	1 Sep. 2015	1 Sep. 2015	9 Nov. 2015
No. of trips	535,020	59,823	248,002

Table A3: Start Date of Data Recording per Bus Type

Notes: The number of trips for which the ABC events are recorded is lower than the total number of trips mentioned in the table, because recording of ABC events commenced only in Sept. 2015. This explains the difference between the number of observations mentioned in this table and those in the regression tables of Section 5.

A.1 Intermediate Changes in ABC settings

During the period of data collection, the company changed some of the threshold settings for the ABC dimensions. An increase (decrease) in the threshold has the effect of reducing (increasing) the number of recorded events. The company has provided a detailed list of when which threshold has been changed on which bus type(s). This list is presented in Table A4.

We note that the VDL buses did not have any changes in settings throughout the period of data collection, except for the braking threshold, which was increased on Oct. 16, 2015 and subsequently slightly decreased on Nov. 5. Especially the Oct. 16 change seems to result in a drop of the number of recorded events, as can be seen in Figure A1b, which shows by bus type the development of the scores in ABC dimensions and fuel economy (weekly averages).

As Figure A1a-c (right axis) show, the IRIS buses record an importantly larger number of events in all three dimensions than the other two bus types. This is due to the fact that this is the bus type of choice in the province's capital, where the routes are characterized by many road bends and stops. Unfortunately, both the acceleration and cornering thresholds for the IRIS buses were increased at Dec. 11, just around the time the drivers received their first report. We therefore cannot identify whether the drop we observe in Figures A1b and c for the number of braking and cornering events is due to the report or the change in settings. For cornering, no data are available for the period prior to the kickoff event. Due to these issues, we exclude the IRIS bus from the analysis in the main text.

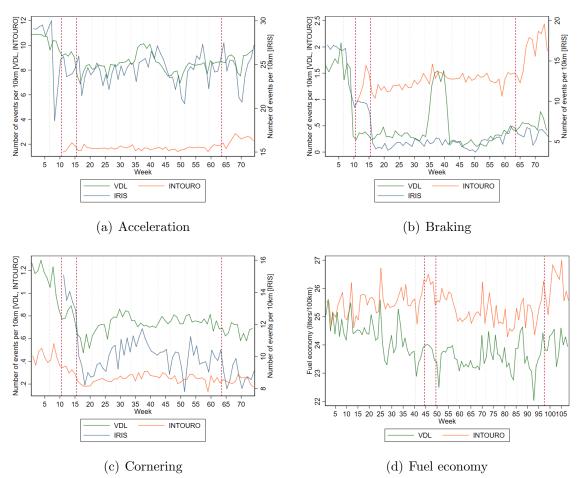
The Intouro buses experienced a number of recalibrations, but all before the date the first feedback report was received by the drivers and mostly comprised only two to four buses out of a total of 29 Intouro buses. Because calibration for these buses was late, we have no records for acceleration and braking for the period prior to the kickoff event, as Figures A1a and b clearly show.

Other than the ABC dimensions, the fuel economy records of both the VDL and Intouro buses cover the entire period from January 2015 till January 2017 and have not been subject to any change in measurement. For completeness, Figures A1d shows the weekly average fuel economy for both the VDL and Intouro buses.

Table A4:	Change	in	Threshold	Settings
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Bus type	date of change	dimension affected	nature of threshold change
IRISBUS 12 M	Dec. 11, 2015	А	decrease
IRISBUS 12 M CNG	Dec. 11, 2015	А	decrease
IRISBUS 10,5 M	Dec. 11, 2015	\mathbf{C}	increase
IRISBUS 10,5 M CNG	Dec. 11, 2015	\mathbf{C}	increase
VDL AMBASSADOR ALE 106	Oct. 16, 2015	В	increase
	Nov. 5, 2015	В	decrease
VDL CITEA LLE 120	Oct. 16, 2015	В	increase
MERCEDES BENZ INTOURO			
bus no. 7503, 7504	Sept. 16, 2015	ABC	recalibration
bus no. 7503, 7504	Oct. 02, 2015	ABC	recalibration
bus no. 7501, 7502, 7503	Nov. 25, 2015	ABC	recalibration
all	Dec. 03, 2015	AB	recalibration

Figure A1: Development Over Time in ABC Dimensions (No. Events) and Fuel Economy (liters/100km) – Weekly Averages by Bus Type



Note: Averages are calculated based on all trips in the analysis set. The red dashed lines indicate the launch date of the EcoManager program [09/11/2015], the distribution of the first feedback report [15/12/2015] and the distribution of the report with the final notification message [15/11/2016]. The dotted lines indicate the distribution of the intermediate monthly feedback reports. The first dotted line indicates the moment EcoManager promotion materials are send to the locations [05/10/2015].

B Sample Feedback Report

Figure A2 reproduces a specimen of the feedback report drivers received once a month between December 2015 - November 2016.



Figure A2: Sample Feedback Report

Bustype	Traject type	Afstand	Liters	Verbruik km/l	Score
	Streek	3.590	927	3,9	C
	Streek	1.207	297	4,1	C
Verbruik chauffeur		4.797	1.223	3,9	C

Beste collega,

Op het onderdeel bochten nemen behoort u tot de beste 25 procent van de buschauffeurs binnen uw vestiging.

Hier doet u het uitstekend!

Op het onderdeel remmen behoort u tot de onderste 50 procent van de buschauffeurs binnen uw vestiging.

Hier kunt u zich verbeteren!

Note: Confidential information (related to the driver) has been removed.

C Results on Braking and Cornering

(1)		DIA	Braking			Corn	Cornering	
(+)		(2)	(3)	(4)	(5)	(9)	(2)	(8)
Post-announcement -1.267**	***2	-1.268***	-1.292***		-0.334***	-0.272***	-0.317***	
T2 (1n/0p) -0.081	81	(0.024)	(170.0)		-0.075 -0.075	(een.n) 080-	(070.0)	
_	(6)	(0.058)			(0.117)	(0.116)		
T3 $(1n/1p)$ -0.083	S3	-0.082			-0.152	-0.158		
	i3)	(0.063)			(0.121)	(0.117)		
T4 (3n/0p) -0.029	29	-0.030			0.012	0.007		
	55) 	(0.063)	0		(0.121)	(0.120)		
Post-feedback 0.070**	**(0.020	0.000		-0.145^{***}	-0.160^{***}	-0.193***	
$\begin{array}{llllllllllllllllllllllllllllllllllll$		(0.035)	(0.036)	0.047	(0.052)	(0.058)	(0.051)	0.059
)	(0)	(0.049)	(0.051)	(0.049)	(0.070)	(0.070)	(0.068)	(0.068)
Post-feedback \times T3 (1n/1p) 0.003	3	0.015	0.009	0.015	0.114^{*}	0.118^{*}	0.110^{*}	0.108^{*}
(0.054)	(4)	(0.052)	(0.053)	(0.051)	(0.069)	(0.067)	(0.065)	(0.064)
Post-feedback \times T4 (3n/0p) -0.017	17	0.001	-0.020	-0.014	0.035	0.040	0.063	0.062
<u> </u>	<u>(3</u>)	(0.052)	(0.051)	(0.050)	(0.068)	(0.068)	(0.063)	(0.062)
Post-experiment 0.033	<u></u>	-0.003	-0.011		-0.100***	-0.106^{***}	-0.051**	
		(0.UZ <i>l</i>)	(0.UZ <i>1</i>)		(0.034) 0.037	(0.030) 0.021	(070.0)	000
Post-experiment × 1.2 (1n/Up) U.005	0 0	-0.004	0.009 (0.036)	(0.036)	0.007	0.004 (0.049)	0.004	600.0 (990.0)
$\frac{10.040}{\text{Post-evneriment}} \propto T_3 (1n/1n) \qquad 0.000^{**}$	() **((0.000) 0 107***		0.000)	0.034	0.042	(0.00) -0.096	(000.0) 0000-
	(69)	(0.035)	(0.035)	(0.034)	(0.042)	(0.040)	(0.032)	(0.031)
Post-experiment \times T4 (3n/0p) 0.080*)**	0.059	0.058	0.041	0.068	0.076	-0.007	-0.004
	(6)	(0.039)	(0.039)	(0.038)	(0.052)	(0.050)	(0.040)	(0.040)
Constant 1.751***	***	1.367^{***}	2.313^{***}	2.157^{***}	1.142^{***}	1.302^{***}	1.637^{***}	1.735^{***}
(0.050)	(0)	(0.055)	(0.059)	(0.085)	(0.090)	(0.096)	(0.056)	(0.078)
	F	.2	.224	.28	.0264	.0912	.388	.397
of trip-level observations 35	87	352887	352887	352887	359066	359066	359066	359066
Controls No		$\mathbf{Y}_{\mathbf{es}}$	\mathbf{Yes}	$\mathbf{Y}_{\mathbf{es}}$	N_{O}	$\mathbf{Y}_{\mathbf{es}}$	$\mathbf{Y}_{\mathbf{es}}$	\mathbf{Yes}
Weather dummies No		$\mathbf{Y}_{\mathbf{es}}$	\mathbf{Yes}	N_{O}	N_{O}	$\mathbf{Y}_{\mathbf{es}}$	$\mathbf{Y}_{\mathbf{es}}$	No
Driver fixed effects No		No	\mathbf{Yes}	$\mathbf{Y}_{\mathbf{es}}$	N_{O}	N_{O}	$\mathbf{Y}_{\mathbf{es}}$	\mathbf{Yes}
Day fixed effects No		No	No	$\mathbf{Y}_{\mathbf{es}}$	No	No	No	$\mathbf{Y}_{\mathbf{es}}$
Bus type \times day fixed effects No		N_{O}	No	$\mathbf{Y}_{\mathbf{es}}$	No	No	N_{O}	$\gamma_{\rm es}$

hours, fill-in rides and having been coached. Weather dummies: daily temperature, wind and rainfall. A no-report indicator is included to capture drivers operating after 15/12/2015 (first feedback round) but who have not yet received their first report.

D Additional Tables and Figures

D.1 Model of the estimation of the residual standard deviation

Let the outcome variable of interest, Y_{it} (fuel economy or ABC), indexed by driver (i) and trip (t), be given by:

$$Y_{it} = X_{it} \cdot \beta + \mu_i + f(s_{it}) + g(z_{it}) + \epsilon_{it}.$$
(3)

In this specification, X_{it} includes all observable determinants of driver performance, day, driver and route fixed effect. The μ_i parameters denote driver fixed effects that absorb all time-invariant unobservables at the driver level and the functions f() and g() reflect the potential impact of having been exposed to the peer-comparison treatment (s_{it}) and coaching (z_{it}) , respectively. Especially for the ABC-dimensions our baseline period before treatment is too small for a reliable estimation of the residual variation. Hence, similar to Chetty, Friedman and Rockoff (2014), we use the entire sample to compute driver's residual outcomes. The residual r_{it} in outcomes after accounting for the observable determinants of driver performance, day, driver and route fixed effect is constructed as follows:

$$r_{it} = Y_{it} - X_{it} \cdot \beta = \mu_i + f(s_{it}) + g(z_{it}) + \epsilon_{it}.$$

$$\tag{4}$$

The standard deviation of the residual variation is computed as:

$$\sigma_r = \sqrt{\frac{1}{n-1} \sum_{i=1}^{n} (r_i - \bar{r})^2},$$

with $r_i = \frac{1}{n_i} \sum_{t=1}^{n_i} r_{it}$ driver *i*'s mean residual over n_t trips and $\bar{r} = \frac{1}{n} \sum_{t=1}^{n} r_i$ the mean residual across drivers. In case the impact of treatment (written feedback or in-person coaching) is correlated with unobservables at the driver level, σ_r will over- or understate the residual variation across drivers. When for example coaches tend to select on average worse drivers (for which we do not find evidence) or when worse drivers benefit more from coaching (for which we do find some evidence), σ_r will be a conservative, downward biased estimate of the actual across driver variation in μ_i 's.

D.2 Determinants of ABC Outcomes	\mathbf{S}
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Table A	.6: Determ	mants of A	Acceleration	1	
Dependent variable:			Acceleration	1	
-	(1)	(2)	(3)	(4)	(5)
VDL 10m	0.953***	0.969***	1.090***	1.139***	1.086***
	(0.073)	(0.073)	(0.071)	(0.072)	(0.048)
VDL 14m	-0.080	-0.127	-0.189	-0.301	-0.172
	(0.149)	(0.146)	(0.157)	(0.191)	(0.198)
Intouro	-1.454***	-1.414***	-1.756***	-1.472***	-1.235***
	(0.210)	(0.213)	(0.205)	(0.214)	(0.224)
Rush hour 7-10am	× /	× ,	-0.896***	-0.909***	-0.844***
			(0.144)	(0.146)	(0.127)
Rush hour 4-7pm			1.182***	1.199***	1.146***
-			(0.157)	(0.156)	(0.111)
Non-scheduled trip			0.353^{*}	0.461**	0.624***
			(0.202)	(0.208)	(0.165)
No. of stops per km.			2.274***	2.376***	2.361***
			(0.194)	(0.188)	(0.169)
Urban trip			0.000	0.000	0.000
			(.)	(.)	(.)
Trip length (in km.)			-0.025***	-0.021***	-0.021***
			(0.002)	(0.002)	(0.002)
Ln(No. of passengers)			1.858^{***}	1.728^{***}	1.648^{***}
			(0.081)	(0.080)	(0.072)
Punctuality			-0.039***	-0.031**	0.049***
			(0.015)	(0.015)	(0.007)
Constant	13.267^{***}	14.002***	6.341***	4.694***	4.718***
	(0.188)	(0.199)	(0.457)	(0.429)	(0.357)
\mathbb{R}^2	.514	.516	.537	.543	.602
Number of trip-level observations	513866	513866	513866	513866	513866
Weather dummies	No	Yes	Yes	No	No
Driver fixed effects	No	No	No	No	Yes
Day fixed effects	No	No	No	Yes	Yes
Route fixed effects	No	No	Yes	Yes	Yes

Table A6: Determinants of Acceleration

Notes: Dependent variable: Number of acceleration events per 10 km. Default categories: Scheduled trips in rural areas outside rush hours completed with a VDL 12m bus. Standard errors are clustered by driver.

***(**,*): statistically different from zero at the 1%-level (5%-level, 10%-level). Standard errors in parentheses.

Dependent variable:			Braking		
-	(1)	(2)	(3)	(4)	(5)
VDL 10m	0.959***	0.969***	0.984***	1.037***	1.017***
	(0.032)	(0.032)	(0.032)	(0.032)	(0.031)
VDL 14m	0.232***	0.195***	0.178***	0.145***	0.197***
	(0.029)	(0.033)	(0.037)	(0.055)	(0.071)
Intouro	3.758***	3.776***	3.632***	3.741***	3.771***
	(0.240)	(0.240)	(0.239)	(0.236)	(0.227)
Rush hour 7-10am	· · · ·	· · · · ·	0.005	-0.008	-0.024
			(0.054)	(0.054)	(0.033)
Rush hour 4-7pm			0.207***	0.221***	0.252***
-			(0.077)	(0.076)	(0.046)
Non-scheduled trip			-0.061	-0.053	-0.078
-			(0.080)	(0.077)	(0.085)
No. of stops per km.			0.275**	0.324***	0.321***
			(0.118)	(0.113)	(0.089)
Urban trip			0.000	0.000	0.000
-			(.)	(.)	(.)
Trip length (in km.)			-0.005***	-0.002***	-0.002***
			(0.001)	(0.001)	(0.000)
Ln(No. of passengers)			0.384***	0.287***	0.280***
			(0.037)	(0.034)	(0.031)
Punctuality			-0.030***	-0.025***	-0.000
			(0.006)	(0.006)	(0.002)
Constant	0.956^{***}	1.303***	-0.001	0.121	0.115
	(0.066)	(0.076)	(0.253)	(0.220)	(0.185)
\mathbb{R}^2	.463	.467	.473	.492	.575
Number of trip-level observations	513866	513866	513866	513866	513866
Weather dummies	No	Yes	Yes	No	No
Driver fixed effects	No	No	No	No	Yes
Day fixed effects	No	No	No	Yes	Yes
Route fixed effects	No	No	Yes	Yes	Yes

Table A7: Determinants of Braking

 $\overline{Notes:}$ Dependent variable: Number of braking events per 10 km. Default categories: Scheduled trips in rural areas outside rush hours completed with a VDL 12m bus. Standard errors are clustered by driver. ***(**,*) : statistically different from zero at the 1%-level (5%-level, 10%-level). Standard errors in parentheses.

Dependent variable:			Cornering		
	(1)	(2)	(3)	(4)	(5)
VDL 10m	-0.085***	-0.079***	-0.110***	-0.078***	-0.064***
	(0.018)	(0.018)	(0.018)	(0.019)	(0.013)
VDL 14m	-0.164***	-0.132***	-0.109**	-0.125	-0.103
	(0.039)	(0.043)	(0.051)	(0.077)	(0.117)
Intouro	-0.343***	-0.320***	-0.463***	-0.371***	-0.279***
	(0.043)	(0.044)	(0.059)	(0.065)	(0.055)
Rush hour 7-10am			-0.130	-0.139	-0.172***
			(0.101)	(0.099)	(0.049)
Rush hour 4-7pm			0.164	0.171	0.177***
			(0.116)	(0.115)	(0.045)
Non-scheduled trip			-0.116	-0.108	-0.327**
			(0.119)	(0.117)	(0.159)
No. of stops per km.			-0.509***	-0.570***	-0.518***
			(0.134)	(0.134)	(0.095)
Urban trip			0.000	0.000	0.000
			(.)	(.)	(.)
Trip length (in km.)			-0.004***	-0.002***	-0.003***
			(0.001)	(0.001)	(0.000)
Ln(No. of passengers)			0.151***	0.098***	0.094***
			(0.031)	(0.032)	(0.023)
Punctuality			-0.121***	-0.119***	-0.055***
			(0.014)	(0.014)	(0.006)
Constant	3.096^{***}	3.386***	3.797***	1.610***	1.467***
	(0.163)	(0.179)	(0.318)	(0.244)	(0.177)
\mathbb{R}^2	.5	.502	.506	.513	.676
Number of trip-level observations	513866	513866	513866	513866	513866
Weather dummies	No	Yes	Yes	No	No
Driver fixed effects	No	No	No	No	Yes
Day fixed effects	No	No	No	Yes	Yes
Route fixed effects	No	No	Yes	Yes	Yes

Table A8: Determinants of Cornering

 $\overline{Notes:}$ Dependent variable: Number of cornering events per 10 km. Default categories: Scheduled trips in rural areas outside rush hours completed with a VDL 12m bus. Standard errors are clustered by driver. ***(**,*) : statistically different from zero at the 1%-level (5%-level, 10%-level). Standard errors in parentheses.

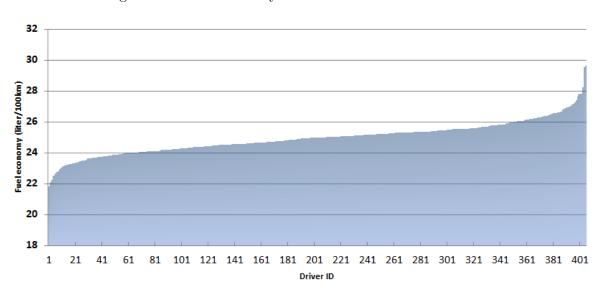


Figure A3: Fuel economy: Estimates Driver Fixed Effects

 $\it Note:$ Estimates based on trips completed with VDL and Intouro buses.

D.3 Timing of Coaching Sessions

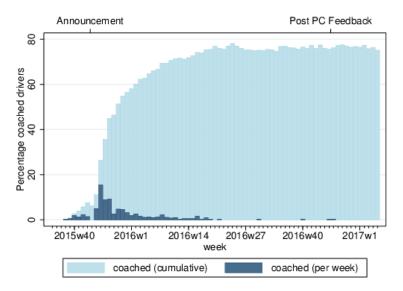


Figure A4: Time of First Coaching

Notes: Moment of first coaching for drivers. Dark blue bars indicate the drivers who received their first coaching during a specific week as a share of the total number of drivers operating during that week. The light blue bars depict the cumulative share of coached drivers operating during a week. Feedback was announced Nov. 9, 2015 and first distributed as a monthly report after Dec. 15, 2015. Peer-comparison messages were removed from the reports from Nov. 2016 onwards.

Two things in Figure A4 related to the coaching program deserve some further explanation. First, the cumulative share of coached drivers operating during a week is more or less flat after April 2016. We have complete coach logs for the period till 30 April, 2016. Some coaches indicated that they no longer provided or kept track of coaching after April 2016. In our evaluation of the coaching program, we therefore restrict attention to the period until 30 April 2016. Second, 30 drivers (10% of all coached drivers) received coaching prior to the feedback announcement.

D.4 Driver Exposure to Targeted Feedback

The tailored nature of the messages is illustrated in Table A9. Panel A reports the percentage share of drivers receiving one of the possible message combinations in each treatment and feedback round (conditional on receiving a feedback report).⁴³ It highlights

⁴³No report is created when drivers were absent in the previous month (on which the report is based).

the flexible design of the treatments. Each treated driver is assigned an individualized message combination which points to behaviors that require attention. In treatment 1 (1n/0p), for example, about 70% of the drivers receive a negative message in a given feedback round, meaning that they perform poorly compared to peers on one of the three comfort dimensions. The remaining 30% performs well on all dimensions and is therefore not notified with a message. Panel B details the composition of the message combinations and shows that all ABC dimensions are well-represented.

How often a treated driver is in the top-25% or bottom-50% on a given driving dimension is shown in Figure A5. The figure plots the number of feedback rounds a driver is in the bottom or top part of the reference group divided by the total number of feedback rounds in which the driver received a feedback report. This gives an indication how often a driver is eligible for targeted messages. For many drivers it varies per round whether they were in the target groups. On each dimension, we observe that there are drivers who were always or never in the bottom (top) part. On acceleration, 19% (16%) of the treated drivers were never (always) in the bottom 50%. For the top 25%, the corresponding figures are 42% (9%). Outcomes are similar for braking and cornering.

	T1 (]	(1n/0p)		T2	(1n/1p)			T3	(3n/0p)	
Feedback round	0n/0p	1n/0p	0n/0p	$1\mathrm{n}/0\mathrm{p}$	0n/1p	1n/1p	0n/0p	$1\mathrm{n}/0\mathrm{p}$	2n/0p	3n/0p
					Panel A: in	Panel A: incidence of messages	ssages			
December 2015	31%	60%	3%	53%	24%	20%	29%	26%	22%	23%
January 2016	27%	73%	7%	49%	22%	22%	29%	24%	17%	29%
February 2016	31%	%69%	2%	49%	21%	28%	27%	27%	22%	24%
March 2016	30%	%02	3%	52%	23%	22%	32%	16%	24%	28%
April 2016	30%	20%	1%	53%	27%	19%	31%	18%	28%	23%
May 2016	29%	71%	2%	55%	27%	16%	28%	18%	34%	20%
June 2016	30%	20%	5%	51%	23%	22%	29%	19%	30%	22%
July 2016	26%	74%	3%	54%	24%	19%	25%	23%	26%	25%
August 2016	27%	73%	4%	47%	23%	25%	27%	24%	24%	24%
September 2016	32%	68%	2%	56%	26%	16%	28%	19%	34%	18%
October 2016	30%	20%	3%	52%	22%	23%	29%	22%	24%	25%
				Panel E	3: compositio	Panel B: composition of messages	(A%;B%;C%)	(%)		
December 2015		(31;46;23)		(40;23;38)	(33;39;28)	(80; 33; 87)		(30; 35; 35)	(65;59;76)	(100;100;100)
January 2016		(33; 33; 33)		(26;30;45)	(38; 33; 29)	(76;29;95)		(30;30;39)	(69;69;63)	(100;100;100)
February 2016		(20;41;39)		(34;43;23)	(55;15;30)	(67;59;74)		(44;20;36)	(52; 81; 67)	(100;100;100)
March 2016		(32;43;25)		(34; 32; 34)	(32;23;45)	(90;52;57)		(27; 33; 40)	(65;70;65)	(100;100;100)
April 2016		(33;38;30)		(27; 37; 35)	(42;23;35)	(56;72;72)		(35;24;41)	(63;74;63)	(100;100;100)
May 2016		(38; 29; 32)		(34;38;28)	(31;27;42)	(100;56;44)		(29;29;41)	(64;73;64)	(100;100;100)
June 2016		(40;35;25)		(31; 37; 33)	(45;27;27)	(67;62;71)		(28;28;44)	(68; 71; 61)	(100;100;100)
July 2016		(34;31;34)		(33;24;43)	(57;22;22)	(61;78;61)		(32;27;41)	(64;76;60)	(100;100;100)
August 2016		(38;30;33)		(29;36;36)	(32; 32; 36)	(88;58;54)		(43;30;26)	(61;61;78)	(100;100;100)
September 2016		(41;29;31)		(28; 33; 39)	(32;36;32)	(73;80;47)		(28;44;28)	(69;56;75)	(100;100;100)
October 2016		(47; 25; 27)		(39;27;35)	(38;24;38)	(50;86;64)		(50;25;25)	(55;68;77)	(100;100;100)
<i>Notes</i> : Panel A reports the percentage share of drivers receiving one of the possible message combinations in each treatment (condition receiving a feedback report). Drivers do not receive a report when they were absent in the previous month (on which the report is based). B shows the composition of these combinations in terms of the ABC comfort dimensions. Negative (positive) messages are provided if a belongs to the bottom 50% (top 25%) of a reference group of peers on one of the comfort dimensions. The reference group consists of driver	ports the p t report). E sition of th m 50% (to)	bercentage sh Drivers do not lese combinat p 25%) of a r	are of drive t receive a r ions in tern eference gro	rs receiving eport when as of the Ai up of peers	c one of the they were al BC comfort on one of th	e of the possible mess were absent in the pr comfort dimensions. N one of the comfort dim	sage combine previous mon Negative (pc mensions. Th	ations in eac nth (on whic) sitive) mess te reference a	h treatment a the report ages are pro group consist	of drivers receiving one of the possible message combinations in each treatment (conditional on zeive a report when they were absent in the previous month (on which the report is based). Panel in terms of the ABC comfort dimensions. Negative (positive) messages are provided if a driver ence group of peers on one of the comfort dimensions. The reference group consists of drivers who
share the same base location and treatment status. A printed version of the feedba 15th day of each feedback round and delivered via the team manager or pigeonhole.	e location a dback roun	nd treatment id and deliver	status. A _F ed via the t	orinted versi eam manag	ion of the fee er or pigeonl	dback report 10le.	(with the m	lessages inte	grated) is cre	A printed version of the feedback report (with the messages integrated) is created around the he team manager or pigeonhole.

Dep. var			Rank month	(m+1)	
			Acceler	ation	
	Message	0.001	-0.007	-0.086**	0.054**
		(0.02)	(0.016)	(0.036)	(0.022)
	Rank month m	0.725^{***}	0.644^{***}	0.851^{***}	1.105^{**}
		(0.079)	(0.053)	(0.075)	(0.22)
	obs.	464	521	487	197
	R^2	0.2503	0.2195	0.2884	0.214
Sample	Rank month m :	bottom- 50%	bottom- 50%	bottom- 50%	top-25%
	Treatment:	T2[0p1n]	T3[1p1n]	T4[0p3n]	T3[1p1r
			Braki	ng	
	Message	-0.043*	-0.044**	-0.063	0.113**
		(0.022)	(0.019)	(0.048)	(0.036)
	Rank month m	0.704^{***}	0.723^{***}	0.712^{***}	0.581**
		(0.096)	(0.062)	(0.113)	(0.253)
	obs.	468	516	492	204
	R^2	0.1928	0.216	0.1635	0.1248
Sample	Rank month m :	bottom- 50%	bottom- 50%	bottom- 50%	top-25%
	Treatment:	T2[0p1n]	T3[1p1n]	T4[0p3n]	T3[1p1r
			Corne	ring	
	Message	-0.003	-0.008	-0.014	0.012
		(0.012)	(0.012)	(0.031)	(0.019)
	Rank month m	0.911***	0.911***	0.808***	0.907**
		(0.043)	(0.049)	(0.062)	(0.148)
	obs.	470	508	500	196
	R^2	0.5877	0.524	0.4244	0.2048
Sample	Rank month m :	bottom- 50%	bottom- 50%	bottom- 50%	top-25%
	Treatment:	T2[0p1n]	T3[1p1n]	T4[0p3n]	T3[1p1r

Table A10: Change in ranking month (m + 1) vs. m following relative performance feedback on performance indicator in month m.

Notes: All regressions include a constant. Standard errors clustered by driver.

 $^{***}(^{**},^{*})$: statistically different from zero at the 1%-level (5%-level, 10%-level). Standard errors in parentheses.

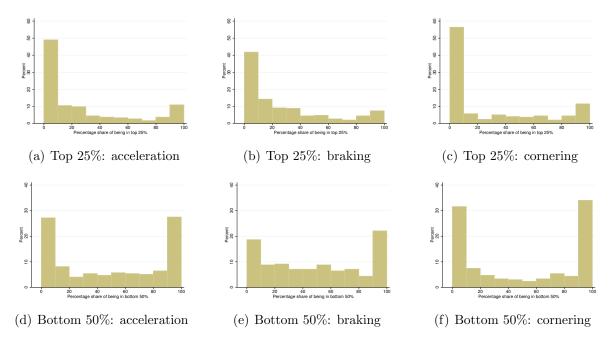


Figure A5: Share of Feedback Rounds in Top 25% or Bottom 50% for Treated Drivers

Notes: The figures show for each ABC driving dimension the distribution of feedback round shares in which treated drivers were in the top 25% or bottom 50% of the peer reference group. The shares are calculated as the number of feedback rounds a driver was in the bottom or top part of the reference group divided by the total number of feedback rounds in which a feedback report was constructed for the driver. It indicates how often a driver was eligible for a targeted peer-comparison message on a given driving dimension (the received message combination depends on the treatment condition). The reference group consists of drivers who share the same base location and treatment status.

E Further Results: In-Person Coaching

Dependent variable:	ш	Fuel Economy	~		Acceleration	
1	(1)	(2)	(3)	(4)	(5)	(9)
Post-coaching	-0.168***	-0.124^{**}		-0.468***	-0.447^{***}	
)	(0.064)	(0.057)		(0.134)	(0.120)	
Day of first coaching			-0.609***			-1.080^{***}
			(0.085)			(0.165)
1 - 7 days after			-0.312^{***}			-0.689***
			(0.058)			(0.120)
8 –14 days after			-0.174^{***}			-0.467^{***}
			(0.064)			(0.137)
15-21 days after			-0.278^{***}			-0.513^{***}
			(0.063)			(0.133)
22 - 28 days after			-0.246^{***}			-0.654^{***}
			(0.073)			(0.149)
29 - 35 days after			-0.154^{**}			-0.371^{***}
			(0.077)			(0.138)
36 - 42 days after			-0.171^{**}			-0.335^{**}
			(0.081)			(0.156)
43 - 49 days after			-0.182^{**}			-0.349^{**}
			(0.079)			(0.159)
50-56 days after			-0.099			-0.364^{**}
			(0.077)			(0.172)
57 - 63 days after			-0.066			-0.406^{**}
			(0.081)			(0.166)
64 - 70 days after			-0.050			-0.336^{*}
			(0.083)			(0.185)
2.20 < 100			0.048			-0.134
			(0.076)			(0.180)
Number of trip-level observations	352253	352253	352253	187127	187127	187127
Controls	N_{O}	\mathbf{Yes}	\mathbf{Yes}	N_{O}	\mathbf{Yes}	${ m Yes}$
Driver fixed effects	N_{O}	\mathbf{Yes}	\mathbf{Yes}	N_{O}	\mathbf{Yes}	${ m Yes}$
Day fixed effects	\mathbf{Yes}	\mathbf{Yes}	$\mathbf{Y}_{\mathbf{es}}$	$\mathbf{Y}_{\mathbf{es}}$	$\mathbf{Y}_{\mathbf{es}}$	\mathbf{Yes}
Bus type \times day fixed effects	N_{O}	\mathbf{Yes}	${ m Yes}$	N_{O}	$\mathbf{Y}_{\mathbf{es}}$	\mathbf{Yes}

Table A11: In-Person Coaching Effects on Driving Performance: Fuel Economy and Acceleration

period thereafter for each coached driver. The dependent variable fuel economy is measured in liters/100km and acceleration as the number of events per 10 kilometers. Standard errors are clustered by driver. Controls include: travel distance, route dummies, number of passengers and bus stops, and dummies for bus type, morning and evening rush hours, non-scheduled rides and having been coached. ***(**,*) : statistically different from zero at the 1%-level (5%-level). Standard errors in parenthese.

					Cornering	
	(1)	(2)	(3)	(4)	(5)	(9)
Post-coaching	-0.009	-0.016		-0.047	-0.047	
)	(0.026)	(0.025)		(0.038)	(0.038)	
Day of first coaching			-0.109^{***}			-0.190^{***}
			(0.034)			(0.039)
1-7 days after			-0.024			-0.104^{***}
			(0.025)			(0.035)
8 - 14 days after			-0.063^{**}			-0.027
			(0.027)			(0.035)
15 - 21 days after			-0.016			-0.079**
			(0.025)			(0.037)
22 - 28 days after			-0.031			-0.098**
			(0.026)			(0.040)
29 - 35 days after			-0.018			-0.054
			(0.028)			(0.038)
36 - 42 days after			-0.004			-0.020
			(0.029)			(0.045)
43 - 49 days after			0.017			-0.039
			(0.031)			(0.047)
50-56 days after			-0.007			0.012
			(0.031)			(0.051)
57 - 63 days after			0.009			-0.030
			(0.030)			(0.051)
64 - 70 days after			-0.005			-0.015
			(0.032)			(0.052)
> 70			0.020			0.018
			(0.037)			(0.055)
Number of trip-level observations	187127	187127	187127	187127	187127	187127
Controls	N_{O}	${ m Yes}$	\mathbf{Yes}	N_{O}	${ m Yes}$	${ m Yes}$
Driver fixed effects	N_{O}	$\mathbf{Y}_{\mathbf{es}}$	$\mathbf{Y}_{\mathbf{es}}$	N_{O}	$\mathbf{Y}_{\mathbf{es}}$	${ m Yes}$
Day fixed effects	$\mathbf{Y}_{\mathbf{es}}$	\mathbf{Yes}	\mathbf{Yes}	\mathbf{Yes}	\mathbf{Yes}	$\mathbf{Y}_{\mathbf{es}}$
Bus type \times day fixed effects	N_{O}	Yes	Y_{es}	N_{O}	Yes	$\mathbf{Y}_{\mathbf{es}}$

Table A12: In-Person Coaching Effects on Driving Performance: Braking and Cornering

uncreated for each concrete driver. The dependent variables praking and cornering are measured as the number of events per 10 kilometers. Standard errors are clustered by driver. Controls include: travel distance, route dummies, number of passengers and bus stops, and dummies for bus type, morning and evening rush hours, fill-in rides and having been coached. Weather dummies: daily temperature, wind and rainfall. ***(**,*) : statistically different from zero at the 1%-level (5%-level, 10%-level). Standard errors in parentheses.

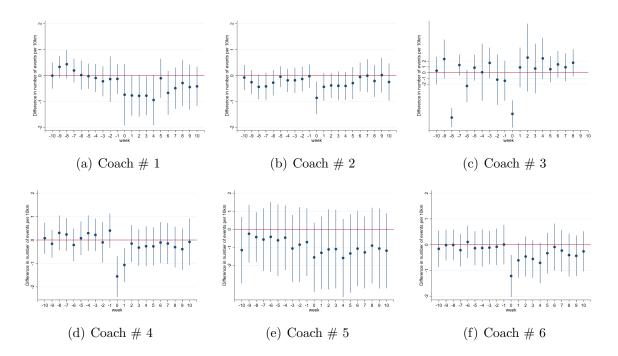


Figure A6: Temporal Effects In-Person Coaching at Coach Level: Acceleration

Dep. var	Ran	k month (r	(n + 1)		
			Accelerat	ion	
	Coached month m	-0.006 (0.031)	-0.012 (0.035)	-0.074^{**} (0.029)	
	Rank month $(m-1)$	$\begin{array}{c} 1.195^{***} \\ (0.11) \end{array}$	$\begin{array}{c} 0.697^{***} \\ (0.122) \end{array}$	$\begin{array}{c} 0.653^{***} \\ (0.043) \end{array}$	
	obs. R^2	$754 \\ 0.1765$	$736 \\ 0.0495$	$1744 \\ 0.2018$	
Sample	Rank month $(m-1)$:	top-25%	25-50%	bottom-50%	
			Brakin	g	
	Coached month m Rank month $(m-1)$	$\begin{array}{r} 0.004 \\ (0.049) \\ 0.694^{***} \end{array}$	-0.009 (0.039) 0.527^{***}	-0.068^{**} (0.029) 0.64^{***}	
		(0.141)	(0.136)	(0.047)	
	obs. R^2	$751 \\ 0.0392$	$731 \\ 0.0229$	$1752 \\ 0.1576$	
Sample	Rank month (m-1):	top- 25%	25 - 50%	bottom-50%	
		Cornering			
	Coached month m	-0.004 (0.021)	-0.024 (0.042)	-0.078^{***} (0.021)	
	Rank month $(m-1)$	$\begin{array}{c} 0.845^{***} \\ (0.091) \end{array}$	$\begin{array}{c} 0.758^{***} \\ (0.094) \end{array}$	$\begin{array}{c} 0.843^{***} \\ (0.031) \end{array}$	
	obs. R^2	$740 \\ 0.1478$	739 0.0797	$1759 \\ 0.4318$	
Sample	Rank month $(m-1)$:	top- 25%	25 - 50%	bottom-50%	
]	Fuel econo	omy	
	Coached month m	0.007 (0.088)	$0.074 \\ (0.055)$	-0.087^{*} (0.046)	
	Rank month $(m-1)$	0.931^{***} (0.196)	0.451^{**} (0.197)	0.565^{***} (0.062)	
	obs. R^2	$351 \\ 0.0607$	$343 \\ 0.0184$	$833 \\ 0.1304$	
Sample	Rank month $(m-1)$:	top-25%	25-50%	bottom-50%	

Table A13: Change in ranking month (m + 1) vs. (m - 1) following coaching in month m.

Notes: All regressions include a constant. Standard errors clustered by driver. ***(**,*) : statistically different from zero at the 1%-level (5%-level, 10%-level). Standard errors in parentheses.

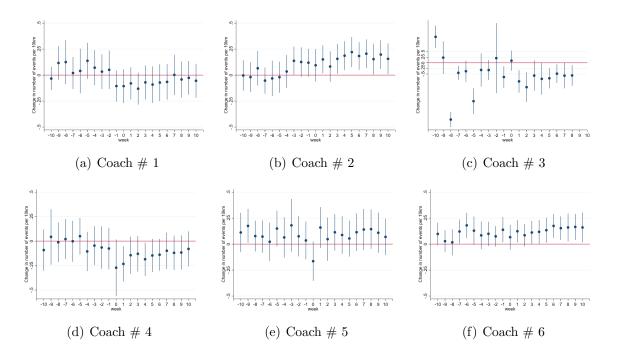
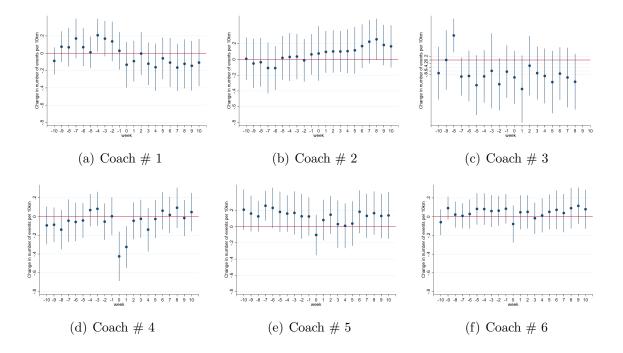


Figure A7: Temporal Effects In-Person Coaching at Coach Level: Braking

Figure A8: Temporal Effects In-Person Coaching at Coach Level: Cornering



F Regression Estimates Temporal Effects of Coaching on Braking and Cornering

Table A14: Written Feedback on Driving Performance, Multiple Hypotheses Testing Correction

Outcome		Δ		p-values	
			Unadj.	Bonf.	Holm
Fuel Economy	Post-announcement	-0.3674	0.0000***	0.0000***	0.0000***
	Post-feedback	-0.1726	0.0053^{***}	0.0635^{*}	0.0423^{**}
	Post-experiment	0.5529	0.0000***	0.0000^{***}	0.0000^{***}
Acceleration	Post-announcement	-1.2294	0.0000***	0.0000***	0.0000***
	Post-feedback	-0.6928	0.0000^{***}	0.0000^{***}	0.0000^{***}
	Post-experiment	0.1866	0.0732	0.879	0.6592
Braking	Post-announcement	-1.2917	0.0000***	0.0000***	0.0000***
	Post-feedback	0.0005	0.9898	1.0000	1.0000
	Post-experiment	-0.0111	0.6855	1.0000	1.0000
Cornering	Post-announcement	-0.3168	0.0000***	0.0000***	0.0000***
	Post-feedback	-0.1931	0.0001^{***}	0.0017^{***}	0.001^{***}
	Post-experiment	0.0629	0.3588	1.0000	1.0000

Notes: Identification of written feedback on driving performance. The dependent variable fuel economy is measured in liters/100km; acceleration, braking and cornering as the number of events per 10 kilometers. The time period under consideration is from 01/01/2015 until 31/01/2017. Standard *p*-values as well as *p*-values that use a Bonferroni and Holm correction for multiple hypothesis testing are reported. Standard errors are clustered by driver. Full regression results are reported in Tables 6 and Table A5.

***(**,*): the corresponding *p*-values are less than 1% (5% or 10%).

Treatments vary in the number of positive and negative peer-comparison messages on the comfort driving dimensions (acceleration, braking, cornering). Messages are targeted in the sense that they are only provided if a driver performs relatively poor (bottom 50%) or good (top 25%) compared to a reference group of colleagues. The post-announcement dummy variable is one in the period from November 9, 2015, onwards (kickoff-event), zero otherwise. Drivers are considered to be in the post-feedback period when they have received at least one report in the past. For most drivers, this was at 15 December 2015 and after. The post-experimental period starts at November 15, 2016, when it was communicated to the treated drivers that they will no longer receive peer-comparison messages. The dependent variable fuel economy is measured in liters/100km and acceleration as the number of events per 10 kilometers. Standard errors are clustered by driver. Controls include: travel distance, route dummies, number of passengers and bus stops, and dummies for bus type, morning and evening rush hours, non-scheduled rides and having been coached. Weather dummies: daily temperature, wind and rainfall. A no-report indicator is included to capture drivers operating after December 15, 2015, but who have not yet received their first report.

Dependent variable:		$\operatorname{Braking}$			Cornering	
	(1)	(2)	(3)	(4)	(2)	(9)
Post-coaching	-0.009	-0.016		-0.047	-0.047	
	(0.026)	(0.025)		(0.038)	(0.038)	
Day of first coaching			-0.109^{***}			-0.190^{***}
			(0.034)			(0.039)
1 - 7 days after			-0.024			-0.104^{***}
			(0.025)			(0.035)
8 - 14 days after			-0.063^{**}			-0.027
			(0.027)			(0.035)
15-21 days after			-0.016			-0.079**
			(0.025)			(0.037)
22 - 28 days after			-0.031			-0.098**
			(0.026)			(0.040)
29 - 35 days after			-0.018			-0.054
			(0.028)			(0.038)
36 - 42 days after			-0.004			-0.020
			(0.029)			(0.045)
43 - 49 days after			0.017			-0.039
			(0.031)			(0.047)
50-56 days after			-0.007			0.012
			(0.031)			(0.051)
57 - 63 days after			0.009			-0.030
			(0.030)			(0.051)
64 - 70 days after			-0.005			-0.015
			(0.032)			(0.052)
> 20			0.020			0.018
			(0.037)			(0.055)
Number of trip-level observations	187127	187127	187127	187127	187127	187127
Controls	N_{O}	\mathbf{Yes}	${\rm Yes}$	No	$\mathbf{Y}_{\mathbf{es}}$	\mathbf{Yes}
Driver fixed effects	N_{O}	\mathbf{Yes}	\mathbf{Yes}	No	\mathbf{Yes}	\mathbf{Yes}
Day fixed effects	\mathbf{Yes}	\mathbf{Yes}	\mathbf{Yes}	$\mathbf{Y}_{\mathbf{es}}$	$\mathbf{Y}_{\mathbf{es}}$	\mathbf{Yes}
Bus type \times day fixed effects	N_{O}	\mathbf{Yes}	\mathbf{Yes}	N_{O}	$\mathbf{Y}_{\mathbf{es}}$	\mathbf{Yes}

Table A15: In-Person Coaching Effects on Driving Performance: Braking and Cornering

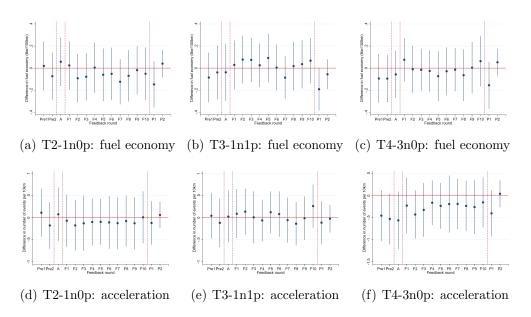
thereafter for each coached driver. The dependent variables braking and cornering are measured as the number of events per 10 kilometers. Standard errors are clustered by driver. Controls include: travel distance, route dummies, number of passengers and bus stops, and dummies for bus type, morning and evening rush hours, fill-in rides and having been coached. Weather dummies: daily temperature, wind and rainfall. ***(**,*) : statistically different from zero at the 1%-level (5%-level). Standard errors in parentheses.

G Further Results: Targeted Peer-Comparison Feedback

G.1 Intertemporal Treatment Differences

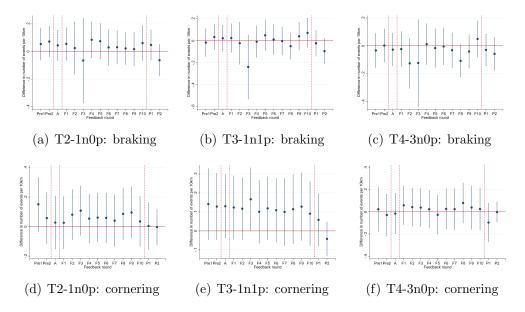
Figure A9 examines temporal effects by plotting the treatment effects per feedback round. The first round starts around 15 December 2015, with a new report being distributed in each subsequent month. The feedback report in November 2016 contains a text message notifying all treated drivers that they will no longer receive peer-comparison messages. The general pattern is that there are no intertemporal effects of the peer-comparison messages on driving behavior.

Figure A9: Intertemporal Treatment Differences Targeted peer-comparison Feedback [Fuel Economy and Acceleration]



Notes: Treatment effects per feedback round based on trips with VDL and Intouro buses. The time period is from 01/09/2015-31/01/2017. **Pre:** 01/09/2015-08/11/2015 [pre-announcement period]; **A**: 09/11/2015-14/12/2015 [announcement period]; **F***i*: 15/12/2015-14/11/2016 [feedback period]; **P***i*: 15/11/2016-31/01/2017 [post-experiment period]. The dependent variable fuel economy is measured in liters/100km and acceleration as the number of events per 10 kilometers. Standard errors are clustered by driver. Controls include: travel distance, route dummies, number of passengers and bus stops, and dummies for bus type, morning and evening rush hours and fill-in rides. Weather dummies: daily temperature, wind and rainfall. A no-report indicator is included to capture drivers operating after 15/12/2015 (first feedback round) but who have not yet received their first report.

Figure A10: Intertemporal Treatment Differences Targeted Peer-Comparison Feedback [Braking and Cornering]

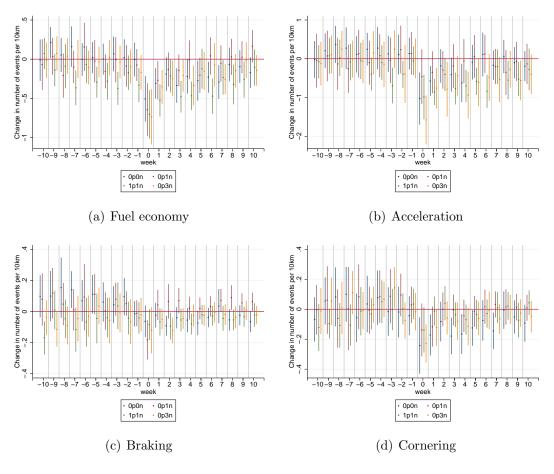


Notes: Treatment effects per feedback round based on trips with VDL and Intouro buses. The time period is from 01/09/2015-31/01/2017. **Pre:** 01/09/2015-08/11/2015 [pre-announcement period]; **A**: 09/11/2015-14/12/2015 [announcement period]; **F***i*: 15/12/2015-14/11/2016 [feedback period]; **P***i*: 15/11/2016-31/01/2017 [post-experiment period]. The dependent variables braking and cornering are measured as the number of events per 10 kilometers. Standard errors are clustered by driver. Controls include: travel distance, route dummies, number of passengers and bus stops, and dummies for bus type, morning and evening rush hours and fill-in rides. Weather dummies: daily temperature, wind and rainfall. A no-report indicator is included to capture drivers operating after 15/12/2015 (first feedback round) but who have not yet received their first report.

H Further Results on Treatment Complementarity

H.1 Effects In-Person Coaching, Conditional on Peer-Comparison Treatment

Figure A11: Treatment Level Effects In-Person Coaching: Fuel Economy and ABC



Notes: Driving performance in the 10 weeks before and after coaching based on trips with VDL and Intouro buses. The day of coaching itself is point 0 on the x-axis. The vertical spikes indicate 95% confidence intervals. The dependent variables braking and cornering are measured as the number of events per 10 kilometers. Standard errors are clustered by driver. Controls include: travel distance, route dummies, number of passengers and bus stops, and dummies for bus type, morning and evening rush hours and fill-in rides the interaction of bus type and date fixed effects. Coaches are excluded.

H.2 Effects Peer-Comparison Feedback, Conditional on Being Coached

Driver NOT COACHED Receiving First	
: Effects on Driving Performance -	
Targeted peer-comparison Feedback	
Table A16: T	Feedback

		Fuel E	Fuel Economy			Accele	Acceleration	
1	(1)	(6)	(3)	(7)	(2)	(9)	(2)	(8)
Post-announcement	-0.172	-0.409^{***}	-0.338***	(1)	-1.693***	-0.974***	-1.090***	(0)
TP3 /1/0)	(0.121)	(0.097)	(0.068)		(0.231)	(0.200)	(0.175)	
	(0.232)	(0.220)			(0.420)	(0.426)		
T3 (1n/1p)	0.350	0.357			0.470	0.442		
T4 (3n/0p)	$(0.349) \\ 0.277$	$(0.339) \\ 0.225$			$(0.636) \\ 0.541$	(0.596) 0.565		
Post-feedback	(0.329) - 0.371^{***}	(0.297) -0.036	-0.023		(0.524) -0.611**	(0.530) -0.539**	-0.335	
$\mathrm{D}_{\mathrm{out}}$ foodbools $\sim \mathrm{Tr}_{0}$ (15 /05)	(0.141)	(0.127)	(0.105)	**100 U	(0.289)	(0.252)	(0.202)	0 AEE
Γ USU-TEEUDACK × 1.2 (111/UD)	(0.204)	(0.182)	(0.155)	(0.149)	-0.209 (0.386)	(0.339)	(0.318)	(0.315)
Post-feedback \times T3 (1n/1p)	0.001	-0.015	-0.117	-0.106	-0.370	-0.334	-0.512	-0.536
	(0.180)	(0.171)	(0.181)	(0.180)	(0.488)	(0.426)	(0.417)	(0.415)
Post-reedback \times 1.4 (3n/0p)	-0.354 (0.163)	-0.210 (0 140)	-0.304*** (0.147)	-0.284*** (0.141)	-0.889 (0.405)	-0.945 (0.317)	-1.012	-1.024 (0.334)
Post-experiment	0.517^{***}	0.519^{***}	0.476^{***}	(+ + + + + + + + + + + + + + + + + + +	0.371	0.166	0.161	(+00.0)
4	(0.145)	(0.091)	(0.086)		(0.284)	(0.205)	(0.188)	
Post-experiment \times T2 (1n/0p)	-0.048	0.046	0.122	0.110	-0.026	-0.009	0.024	0.019
	(0.207)	(0.127)	(0.130)	(0.115)	(0.341)	(0.274)	(0.235)	(0.243)
Post-experiment \times T3 (1n/1p)	0.144	0.131	0.084	0.091	0.158	0.193	0.056	0.030
2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	(0.197)	(0.146)	(0.131)	(0.119)	(0.404)	(0.297)	(0.266)	(0.264)
Post-experiment \times 14 (3n/0p)	-0.156	0.033	0.058	0.052	0.049	0.189 (0.216)	0.236	0.239
Constant	94 196***	0.149) 21 809***	22.307***	0.120) 24 NG7***	10.283^{***}	8.538***	11 257***	10 921***
	(0.181)	(0.207)	(0.161)	(0.386)	(0.357)	(0.361)	(0.376)	(0.418)
\mathbb{R}^2	.0175	.409	.502	.526	.0451	.374	.519	.541
Number of trip-level observations	144305	136482	136482	136482	99562	94667	94667	94667
Controls	N_{O}	$\mathbf{Y}_{\mathbf{es}}$	\mathbf{Yes}	Yes	No	\mathbf{Yes}	\mathbf{Yes}	Yes
Weather dummies	N_{O}	$\mathbf{Y}_{\mathbf{es}}$	\mathbf{Yes}	No	N_{O}	\mathbf{Yes}	\mathbf{Yes}	No
Driver fixed effects	N_{O}	N_{O}	\mathbf{Yes}	$\mathbf{Y}_{\mathbf{es}}$	N_{O}	N_{O}	\mathbf{Yes}	\mathbf{Yes}
Day fixed effects	N_{O}	N_{O}	N_{O}	\mathbf{Yes}	N_{O}	N_{O}	N_{O}	\mathbf{Yes}
Bus type \times day fixed effects	N_{O}	No	N_{O}	Yes	N_{O}	N_{O}	N_{O}	Yes
<i>Notes:</i> Identification of the treatment effects on driving performance. The time period under consideration is from 01/01/2015 until 31/01/2017. Treatments vary in the number of positive and negative peer-comparison messages on the confort driving dimensions (acceleration, braking, cornering). Messages are targeted in the sense that they are only provided if a driver performs relatively poor (bottom 50%) or good (top 25%) compared to a reference group of colleagues. The post-announcement dummy variable is one in the period from 09/11/2015 onwards (feedback announcement), zero otherwise. Drivers are considered to be in the post-feedback period when they have received at least one report in the past. For most drivers, this was at 15/12/2015 and after. The post-experimental period starts at 15/11/2016 when it was communicated to the treated drivers that they will no longer receive peer-comparison messages. The dopendent variable fuel economy is measured in liters/100m and acceleration as the number of events period after travel distance, route dummics, number of passengers and bus stops, and dummics for bus type, morning and evening rush hours and fill-in rides. Weather dummies: daily temperature, wind and rainfall. A no-report indicator is included to capture drivers.	ects on driving urison messages vely poor (bottu vels (feedback a river peer-compa urive peer-compa is and fill-in ri ound) but who out the 1%-level	1. performance. 7 on the comfort om 50%) or goo announcement), s at 15/12/2015 rrison messages. by divier. Con des. Weather di- des. Weather di- have not yet re (5%-level. 10%-1	The time period driving dimensio d (top 25%) com zero otherwise.] and after. The The dependent trols include: tri trols include: tri trols include: tri trols include: tri trols badly te ceived their first	under considerat ins (acceleration, pared to a refere Drivers are consi post-experiment, variable fuel eco avel distance, ro mperature, wind report.	ion is from 01/0 braking, corneri nce group of coll dered to be in tl al period starts a nomy is measured the dummies, nu and rainfall. A	1/2015 until 31/ ng). Messages a eagues. The pos a post-feedback at 15/11/2016 w 1 in liters/100km mber of passeng no-report indica	s on driving performance. The time period under consideration is from 01/01/2015 until 31/01/2017. Treatments vary in the on messages on the comfort driving dimensions (acceleration, braking, cornering). Messages are targeted in the sense that they r poor (bottom 50%) or good (top 25%) compared to a reference group of colleagues. The post-announcement dummy variable (feedback announcement), zero otherwise. Drivers are considered to be in the post-feedback period when they have received ars, this was at 15/12/2015 and after. The post-experimental period starts at 15/11/2016 when it was communicated to the peet-comparison messages. The dependent variable fuel economy is measured in liters/100km and acceleration as the number re clustered by driver. Controls include: travel distance, route dummies, number of passengers and bus stops, and dummies and fill-in rides. Weather dummies: daily temperature, wind and rainfall. A no-report indicator is included to capture drivers and but who have not get received their first report.	tents vary in the sense that they dummy variable sy have received nunicated to the n as the number s, and dummies o capture drivers

Dependent variable: Fuel Economy Acceleration		Fuel E	Economy	0		Accele	Acceleration	
	(1)	(2)	(3)	(4)	(5)	(9)	(2)	(8)
Post-announcement	-0.452^{***}	-0.392***	-0.455^{***}	~	-2.617^{***}	-1.069***	-1.261^{***}	~
Tray (1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1	(0.091) 0 553**	(0.105)	(0.072)		(0.180)	(0.194)	(0.168)	
12 (111/0 <i>D</i>)	-0.356)	-0.018 (0.194)			-0.1010 (0.497)	-0.230 (0.404)		
T3 $(1n/1p)$	-0.332	-0.313			0.023	-0.046		
	(0.255)	(0.207)			(0.582)	(0.463)		
14 (3n/0p)	-0.320 (0.254)	-0.478 (0.184)			-0.332 (0 479)	-0.1397) (7.020)		
Post-feedback	-0.477***	0.007	-0.171^{*}		-0.436^{*}	-0.400	-0.673^{***}	
	(0.123)	(0.158)	(0.100)	00	(0.242)	(0.291)	(0.249)	
Post-feedback \times 1.2 (1n/0p)	0.090	0.071	0.117	0.120	0.404	0.349	0.260	0.238
Post-feedback \times T3 (1n/1p)	(0.212) 0.165	(0.154) 0.134	(0.135) 0.082	(0.135)	(0.411) 0.004	(0.354) 0.185	(0.350) 0.183	(0.301)
· · ·	(0.152)	(0.110)	(0.107)	(0.106)	(0.342)	(0.288)	(0.284)	(0.282)
Post-feedback \times T4 (3n/0p)	0.173	0.126	0.064	0.035	0.059	0.286	0.242	0.254
	(0.174)	(0.109)	(0.101)	(0.097)	(0.321)	(0.262)	(0.246)	(0.246)
Post-experiment	0.547^{***}	0.486^{***}	0.537^{***}		0.308	0.117	0.220	
	(0.144)	(0.093)	(0.082)		(0.235)	(0.196)	(0.163)	
Post-experiment \times T2 (1n/0p)	0.235	0.238	0.179	0.186	0.516	0.465	0.316	0.307
	(0.216)	(0.169)	(0.149)	(0.140)	(0.352)	(0.321)	(0.273)	(0.266)
Post-experiment \times T3 (1n/1p)	0.134	0.166	0.089	0.107	0.431	0.427^{*}	0.256	0.274
	(0.185)	(0.127)	(0.105)	(0.107)	(0.296)	(0.249)	(0.216)	(0.216)
Post-experiment \times T4 (3n/0p)	0.014	0.156	0.056	0.056	0.156	0.253	0.075	0.087
	(0.171)	(0.114)	(0.104)	(0.105)	(0.313)	(0.251)	(0.193)	(0.192)
Constant	24.949^{***}	22.243^{***}	22.581^{***}	23.768^{***}	10.914^{***}	8.389^{***}	11.638^{***}	11.793^{***}
	(0.181)	(0.142)	(0.125)	(0.289)	(0.387)	(0.315)	(0.268)	(0.377)
${ m R}^2$.0183	.424	.498	.517	.0458	.414	.561	.578
Number of trip-level observations	243265	232597	232597	232597	171092	164593	164593	164593
Controls	N_{O}	Yes	Yes	Yes	No	Yes	Yes	Yes
Weather dummies	N_{O}	Yes	Yes	No	No	Yes	Yes	No
Driver fixed effects	N_{O}	N_{O}	Yes	$\mathbf{Y}^{\mathbf{es}}$	N_{O}	N_{O}	\mathbf{Yes}	\mathbf{Yes}
Day fixed effects	N_{O}	No	N_{O}	$\mathbf{Y}_{\mathbf{es}}$	N_{O}	N_{O}	N_{O}	\mathbf{Yes}
Bus type \times day fixed effects	N_{O}	No	N_{O}	$\mathbf{Y}^{\mathbf{es}}$	No	N_{O}	No	Yes
<i>Notes:</i> Identification of the treatment effects on driving performance. The time period under consideration is from 01/01/2015 until 31/01/2017. Treatments vary in the number of positive and negative peer-comparison messages on the comfort driving dimensions (acceleration, braking, cornering). Messages are targeted in the sense that they are only provided if a driver performs relatively poor (bottom 50%) or good (top 25%) compared to a reference group of colleagues. The post-announcement dummy variable is one in the period from 09/11/2015 onwards (feedback announcement), zero otherwise. Drivers are considered to be in the post-feedback period when they have received at least one report in the past. For most drivers, this was at 15/12/2015 and after. The post-emontal period starts at 15/11/2016 when it was communicated to the treated drivers that they will no longer receive peer-comparison messages. The dependent variable fule economy is measured in liters/100km and acceleration as the number of events period from on provided errors are clustered by driver. Controls include: travel distance, route dummies, number of passengers and bus stops, and dummies for bus type, morning and evening rush hours, fill-in rides and having been coeffed. Weather dummies, number of passengers and bus stops, and dummies for bus type, during rush hours, fill-in rides and having been coeffed. Weather dummies, number of passengers and bus stops, and dummies for bus type, morning after 15/12/2016 first feedback round) but who have not yet received their first report.	ffects on driving parison messages tively poor (bott ards (feedback a drivers, this was erive peer-compa ar are clustered 1 i, fill-in rides and i, fill-in rides and at the 1%-level	s on driving performance. The time period under consideration is from m messages on the comfort driving dimensions (acceleration, braking, poor (bottom 50%) or good (top 25%) compared to a reference group (feedback announcement), zero otherwise. Drivers are considered to 1 ars, this was at 15/12/2015 and after. The post-experimental period peer-comparison messages. The dependent variable fuel economy is m elestreed by driver. Controls include: travel distance, route dummies in rides and having been coached. Weather dummies: daily temperatu first feedback round) but who have not yet received their first report. in 1%-level (5%-level) 10%-level). Standard errors in parentheses.	he time period thriving dimensio 1 (top 25%) com sero otherwise. and after. The ard after. The dependent ols include: trawn ached. Weather ached. Weather evel). Standard	under considerat ins (acceleration, pared to a refere Drivers are cons post-experiment variable fuel eco, el distance, rout dummies: daily received their fin errors in parentl	ion is from 01/0 braking, corneri mee group of coll idered to be in t al period starts, a puriod starts, a ouny is measure a dummies, numl temperature, wii reses.	1/2015 until 31/ ng). Messages a eagues. The pos he post-feedback at 15/11/2016 w 1 in liters/100kr or of passengers and and rainfall.	s on driving performance. The time period under consideration is from 01/01/2015 until 31/01/2017. Treatments vary in the on messages on the comfort driving dimensions (acceleration, braking, cornering). Messages are targeted in the sense that they poor (bottom 50%) or good (top 25%) compared to a reference group of colleagues. The post-announcement dummy variable (feedback announcement), zero otherwise. Drivers are considered to be in the post-feedback period when they have received are, this was at 15/12/2015 and after. The post-experimental period starts at 15/11/2016 when it was communicated to the peet-comparison messages. The dependent variable fuel economy is measured in liters/100km and acceleration as the number in rides and having been coached. Weather threed dummies, number of passengers and bus stops, and dummies for in rides and having been coached. Weather dummies: daily temperature, wind and rainfall. A no-report indicator is included first feedback round) but who have not yt received their first report.	ents vary in the ents vary in the sense that they dummy variable sy have received nunicated to the a st he number and dummies for :ator is included
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Table A17: Targeted Peer-Comparison Feedback Effects on Driving Performance - Drivers COACHED Before First Feedback

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Table A18: Targete	back
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Dependent variable:		Bra	Braking			Corn	Cornering	
	(1)	(2)	(3)	(4)	(5)	(9)	(2)	(8)
Post-announcement	-1.264***	-1.294***	-1.302***		-0.249***	-0.255^{***}	-0.328***	
	(0.047)	(0.052)	(0.050)		(0.072)	(0.067)	(0.059)	
12 (1n/up)	0.040	000.0			0.197	0.195		
T3 (1n/1n)	(0.106) -0.016	(0.104) -0.004			(0.235) - 0.022	(0.235) -0.038		
	(0.125)	(0.122)			(0.245)	(0.234)		
T4 (3n/0p)	0.203	0.222^{*}			0.392	0.391		
	(0.124)	(0.122)			(0.262)	(0.258)		
Post-feedback	0.182^{***}	0.199***	0.199***		-0.115	-0.094	-0.098	
$\mathrm{D}_{\mathrm{out}}$ foodbook $\sim \mathrm{T}_{2}$ (15./0.)	(160.0)	(0.053)	(0.057) 0 130*	*771 U	0.120)	(0.115) 0.070	(70170) (70172)	0.061
$1 \text{ Opt-regularity } 1 \neq (111/0h)$	(0.063)	(0.068)	(0.073)	(0.078)	(0.120)	(0.118)	(0.116)	(0.118)
Post-feedback \times T3 (1n/1p)	-0.085	-0.097	-0.088	-0.091	0.067	0.077	0.081	0.074
· · ·	(0.102)	(0.099)	(0.106)	(0.103)	(0.131)	(0.121)	(0.119)	(0.120)
Post-feedback \times T4 (3n/0p)	-0.280***	-0.291^{***}	-0.282***	-0.279***	-0.318^{**}	-0.324^{**}	-0.226	-0.230
	(0.090)	(0.091)	(0.090)	(0.092)	(0.150)	(0.148)	(0.137)	(0.139)
Post-experiment	0.006	-0.021	-0.003		-0.217^{***}	-0.221^{***}	-0.092*	
	(0.056)	(0.048)	(0.042)		(0.072)	(0.074)	(0.051)	
Post-experiment \times T2 (1n/0p)	0.066	0.034	0.026	0.040	0.191^{**}	0.172^{*}	0.059	0.046
	(0.063)	(0.061)	(0.053)	(0.055)	(0.092)	(0.089)	(0.064)	(0.061)
Post-experiment \times T3 (1n/1p)	0.104	0.132^{*}	0.099	0.113	0.117	0.113	0.002	-0.009
	(0.084)	(0.073)	(0.071)	(0.069)	(0.089)	(0.091)	(0.069)	(0.068)
Post-experiment \times T4 (3n/0p)	0.086	0.078	0.057	0.060	0.193^{*}	0.181	0.078	0.079
	(0.068)	(0.061)	(0.060)	(0.057)	(0.111)	(0.112)	(0.095)	(0.093)
Constant	1.641^{***}	1.362^{***}	2.261^{***}	1.991^{***}	1.039^{***}	1.162^{***}	1.668^{***}	1.615^{***}
	(0.091)	(0.103)	(0.112)	(0.174)	(0.188)	(0.202)	(0.107)	(0.133)
${ m R}^2$.0833	.196	.219	.29	.0306	.0973	.407	.421
Number of trip-level observations	99562	94667	94667	94667	100837	95938	95938	95938
Controls	N_{O}	\mathbf{Yes}	Yes	Yes	No	\mathbf{Yes}	\mathbf{Yes}	Yes
Weather dummies	N_{O}	$\mathbf{Y}_{\mathbf{es}}$	Yes	N_{O}	No	$\mathbf{Y}_{\mathbf{es}}$	Yes	N_{O}
Driver fixed effects	N_{O}	N_{O}	Yes	\mathbf{Yes}	N_{O}	N_{O}	Yes	Yes
Day fixed effects	N_{O}	N_{O}	N_{O}	$\mathbf{Y}_{\mathbf{es}}$	N_{O}	N_{O}	N_{O}	Yes
Bus type \times day fixed effects	N_{O}	N_{O}	No	Yes	N_{O}	No	N_{O}	Yes
Notes: Identification of the treatment effects on driving performance. The time period under consideration is from 01/01/2015 until 31/01/2017. Treatments vary in the	ects on driving	g performance. 7	The time period 1	under considerat	ion is from $01/0$	1/2015 until $31/$	01/2017. Treatm	tents vary in the
number of positive and negative peer-comparison messages on the comfort driving dimensions (acceleration, braking, cornering). Messages are targeted in the sense that they are only provided if a driver performs relatively poor (bottom 50%) or good (top 25%) compared to a reference group of colleagues. The post-announcement dummy variable	arison messages vely poor (bott	s on the comfort om 50%) or goo	driving dimensio d (top 25%) com	ns (acceleration pared to a refere	, braking, corner ence group of col	ing). Messages a leagues. The pos	re targeted in the st-announcement	e sense that they dummy variable
is one in the period from $09/11/2015$ onwards	rds (feedback a	announcement),	zero otherwise. I	Drivers are cons	idered to be in t	he post-feedback	(feedback announcement), zero otherwise. Drivers are considered to be in the post-feedback period when they have received	ey have received
at least one report in the past. For most drivers, this was at 15/12/2015 and after. The post-experimental period starts at 15/11/2016 when it was communicated to the	lrivers, this wa	s at 15/12/2015	and atter. The June 1	post-experiment	al period starts	at 15/11/2016 w	then it was comn	nunicated to the
treated drivers that they will no longer receive peer-comparison messages. The dependent variable tuel economy is measured in liters/JU0km and acceleration as the number of providence and his stress and dimension and the stress and dimension acceleration as the number of providence and his stress and dimension acceleration as the number of providence and his stress and dimension acceleration as the number of providence and his stress and dimension acceleration as the number of providence and his stress and dimension acceleration as the number of providence and his stress and dimension acceleration acceleration acceleration acceleration acceleration acceleration acceleration acceleration acceleration acce	aive peer-compa	arison messages.	The dependent	variable fuel eco	nomy is measure	d in liters/ luukn	n and acceleratio	n as the number
of events per 10 kinneters. Standard errors are clustered by driver. Controls include: travel distance, route dummes, number of passengers and ours stops, and dummes for the traveler standard errors are clustered by driver. Journols include: travel distance i number of passengers and nummes	rs are clustered	l by ariver. Cou	trols include: tra	ivel distance, ro	ute aummies, m	under of passeng	Sers and Dus stop	s, and dummies

for bus type, morning and evening rush hours and fill-in rides. Weather dummies: daily temperature, wind and rainfall. A no-report indicator is included to capture drivers operating after 15/12/2015 (first feedback round) but who have not yet received their first report. ***(**,*): statistically different from zero at the 1%-level (5%-level). Standard errors in parentheses.

Dependent variable:		Bra	Braking			Corr	Cornering	
	(1)	(2)	(3)	(4)	(5)	(9)	(2)	(8)
Post-announcement	-1.248***	-1.321^{***}	-1.336^{***}		-0.316^{***}	-0.120^{*}	-0.225^{***}	
	(0.043)	(0.049)	(0.048)		(0.038)	(0.069)	(0.051)	
T2 (1n/0p)	-0.124	-0.111			-0.196	-0.172		
	(0.091)	(0.086)			(0.191)	(0.176)		
T3 (1n/1p)	-0.145	-0.138			-0.228	-0.235		
	(0.092)	(0.089)			(0.175)	(0.159)		
T4 (3n/0p)	-0.167	-0.168^{*}			-0.167	-0.125		
	(0.106)	(0.097)			(0.169)	(0.166)		
Post-feedback	0.017	-0.156^{***}	-0.159^{***}		-0.122^{**}	-0.056	-0.157^{**}	
	(0.048)	(0.051)	(0.051)		(0.052)	(0.086)	(0.066)	
Post-feedback \times T2 (1n/0p)	0.135^{*}	0.112	0.101	0.087	0.029	0.026	0.061	0.054
	(0.076)	(0.071)	(0.071)	(0.067)	(0.115)	(0.109)	(0.111)	(0.110)
Post-feedback \times T3 (1n/1p)	0.069	0.055	0.056	0.055	0.052	0.065	0.075	0.070
	(0.073)	(0.068)	(0.068)	(0.066)	(0.090)	(0.085)	(0.090)	(0.088)
Post-feedback \times T4 (3n/0p)	0.113	0.122	0.095	0.097	0.149^{**}	0.148^{**}	0.139^{*}	0.130^{*}
	(0.082)	(0.079)	(0.076)	(0.074)	(0.074)	(0.073)	(0.075)	(0.074)
Post-experiment	0.134^{**}	0.060	0.066		-0.066	-0.092	-0.026	
	(0.053)	(0.044)	(0.045)		(0.064)	(0.056)	(0.035)	
Post-experiment \times T2 (1n/0p)	0.007	-0.011	-0.008	-0.017	0.047	0.067	-0.021	-0.024
	(0.071)	(0.063)	(0.062)	(0.061)	(0.081)	(0.071)	(0.054)	(0.054)
Post-experiment \times T3 (1n/1p)	0.036	0.055	0.039	0.029	0.014	0.032	-0.033	-0.035
	(0.071)	(0.053)	(0.053)	(0.054)	(0.071)	(0.058)	(0.042)	(0.042)
Post-experiment \times T4 (3n/0p)	0.030	0.068	0.055	0.042	0.052	0.067	-0.039	-0.040
	(0.065)	(0.064)	(0.062)	(0.059)	(0.081)	(0.069)	(0.051)	(0.050)
Constant	1.786^{***}	1.392^{***}	2.264^{***}	2.113^{***}	1.178^{***}	1.304^{***}	1.492^{***}	1.643^{***}
	(0.079)	(0.083)	(0.093)	(0.119)	(0.131)	(0.134)	(0.075)	(0.117)
\mathbb{R}^2	.0767	.206	.233	.291	.0235	.101	.379	.391
Number of trip-level observations	171092	164593	164593	164593	174143	167632	167632	167632
Controls	N_{O}	Y_{es}	Yes	Yes	No	$\mathbf{Y}_{\mathbf{es}}$	Y_{es}	\mathbf{Yes}
Weather dummies	N_{O}	$\mathbf{Y}_{\mathbf{es}}$	Yes	No	No	$\mathbf{Y}_{\mathbf{es}}$	$\mathbf{Y}_{\mathbf{es}}$	No
Driver fixed effects	N_{O}	No	\mathbf{Yes}	\mathbf{Yes}	N_{O}	N_{O}	\mathbf{Yes}	Yes
Day fixed effects	N_{O}	N_{O}	N_{O}	\mathbf{Yes}	N_{O}	N_{O}	N_{O}	\mathbf{Yes}
Bus type \times day fixed effects	N_{O}	N_{O}	N_{O}	\mathbf{Yes}	N_{O}	N_{O}	N_{O}	\mathbf{Yes}
<i>Notes:</i> Identification of the treatment effects on driving performance. The time period under consideration is from 01/01/2015 until 31/01/2017. Treatments vary in the number of positive and negative peer-comparison messages on the confort driving dimensions (acceleration, braking, cornering). Messages are targeted in the sense that they are only provided if a driver performs relatively poor (bottom 50%) or good (top 25%) compared to a reference group of colleagues. The post-announcement dummy variable is one in the period from 09/11/2015 onwards (feedback announcement), zero otherwise. Drivers are considered to be in the post-feedback period when they have received at least one report in the past. For most drivers, this was at 15/12/2015 and after. The post-experimental period starts at 15/11/2016 when it was communicated to the treated drivers that they will no longer receive peer-comparison messages. The dependent variable fue (coronny is measured in liters/100km and acceleration as the number of events period and events period starts at 15/11/2016 when it was communicated to the treated drivers that they will no longer receive peer-comparison messages. The dependent variable fue (coronny is measured in liters/100km and acceleration as the number of events period at and evening rush hours, fill-in rides and having been coefied. Weather dumnies, number of passengers and bus stops, and dumnies for bus type, morning and evening rush hours, fill-in rides and having been coefied. Weather dumnies: daily temperature, wind and rainfall. A no-report indicator is included to capture drivers operation after 10%-level, 10%-level). Standard errors in parentheses.	Fects on driving arison messages ively poor (bott ards (feedback a drivers, this was eive peer-comps is are clustered fill-in rides and fill-in rides and the 1%-level at the 1%-level	c) performance. T i on the comfort om 50%) or good unnouncement), i s at 15/12/2015 by driver. Contr having been co dk round) but w (5%-level, 10%-1	s on driving performance. The time period under consideration is from an messages on the comfort driving dimensions (acceleration, braking, poor (bottom 50%) or good (top 25%) compared to a reference group (feedback announcement), zero otherwise. Drivers are considered to 1s; this was at 15/12/2015 and after. The post-experimental period peer-comparison messages. The dependent variable fuel economy is m clustered by driver. Controls include: travel distance, route dummies in rides and having been coached. Weather dummies: daily temperatu first feedback round) but who have not yet received their first report. In 2%-level (5%-level). Standard errors in parentheses.	inder considerat ins (acceleration. pared to a refere Drivers are cons post-experiment variable fuel econ al distance, routd dummes: daily dummes: daily received their fin errors in parentl	ion is from 01/0 braking, corneri- mee group of col- idered to be in t al period starts - nony is measure a dumnies, numl temperature, wii st report.	1/2015 until 31/ ng). Messages a leagues. The pos he post-feedbach at 15/11/2016 w d in liters/100kr ber of passengers nd and rainfall.	(01/2017. Treatm re targeted in thus st-announcement c period when th chen it was comm n and acceleratio s and bus stops, A no-report indi	tents vary in the e sense that they dummy variable ey have received municated to the n as the number and dummies for cator is included
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Table A19: Targeted Peer-Comparison Feedback Effects on Driving Performance - Drivers COACHED Before First Feedback

84

Dependent variable:	Fuel economy	Acceleration	Braking	Cornering
	(1)	(2)	(3)	(4)
Post-announcement=1	-0.371***	-0.911***	-1.214***	-0.287***
	(0.065)	(0.185)	(0.049)	(0.054)
Post-announcement= $1 \times agegroup=1$	-0.310***	-0.800***	-0.093	-0.082
	(0.114)	(0.280)	(0.069)	(0.087)
Post-announcement= $1 \times agegroup=2$	0.016	0.191	-0.135*	-0.063
	(0.105)	(0.251)	(0.081)	(0.075)
Post-announcement= $1 \times agegroup=4$	0.047	-0.011	-0.023	-0.074
	(0.092)	(0.230)	(0.071)	(0.075)
Post-feedback=1	-0.132**	-0.972***	0.008	-0.210***
	(0.065)	(0.172)	(0.028)	(0.044)
Post-feedback= $1 \times \text{agegroup}=1$	-0.095	0.113	-0.026	0.062
	(0.112)	(0.270)	(0.040)	(0.057)
Post-feedback= $1 \times \text{agegroup}=2$	-0.073	0.049	-0.027	0.043
	(0.125)	(0.300)	(0.046)	(0.083)
Post-feedback= $1 \times \text{agegroup}=4$	0.069	0.391^{*}	0.030	0.167***
	(0.103)	(0.213)	(0.044)	(0.054)
Post-experiment=1	0.599***	0.436***	0.070***	-0.024
-	(0.043)	(0.106)	(0.024)	(0.026)
Post-experiment= $1 \times \text{agegroup}=1$	-0.046	-0.244	-0.077**	-0.026
	(0.076)	(0.164)	(0.035)	(0.035)
Post-experiment= $1 \times \text{agegroup}=2$	-0.033	-0.137	-0.010	-0.071
	(0.078)	(0.183)	(0.037)	(0.053)
Post-experiment= $1 \times \text{agegroup}=4$	0.014	-0.103	0.003	-0.067*
	(0.067)	(0.174)	(0.034)	(0.035)
Constant	22.555***	11.357***	2.314***	1.642***
	(0.078)	(0.188)	(0.059)	(0.052)
\mathbb{R}^2	.531	.45	.198	.396
# trip-level observations	484918	349879	349879	349879
Controls	Yes	Yes	Yes	Yes
Weather dummies	Yes	Yes	Yes	Yes
Driver fixed effects	Yes	Yes	Yes	Yes
Day fixed effects	No	No	No	No
Bus type \times day fixed effects	No	No	No	No

Table A20: Targeted Peer-Comparison Feedback Effects on Driving Performance [Groups: Age]

Notes: Identification of the treatment effects on driving performance. The time period under consideration is from 01/01/2015 until 31/01/2017. The post-announcement dummy variable is one in the period from 09/11/2015 onwards (feedback announcement), zero otherwise. Drivers are considered to be in the post-feedback period when they have received at least one report in the past. For most drivers, this was at 15/12/2015 and after. The post-experimental period starts at 15/11/2016 when it was communicated to the treated drivers that they will no longer receive peer-comparison messages. The dependent variable fuel economy is measured in liters/100km and acceleration as the number of events per 10 kilometers. Standard errors are clustered by driver. Controls include: travel distance, route dummies, number of passengers and bus stops, and dummies for bus type, morning and evening rush hours, fill-in rides and having been coached. Weather dummies: daily temperature, wind and rainfall. A no-report indicator is included to capture drivers operating after 15/12/2015 (first feedback round) but who have not yet received their first report. Default agegroup=3 (55-59 years); agegroup=1: < 50 years; agegroup=2: 50 - 54 years; agegroup=4: ≥ 60 years.

***(**,*): statistically different from zero at the 1%-level (5%-level, 10%-level). Standard errors in parentheses.

Dependent variable:	Fuel economy	Acceleration	Braking	Cornering
	(1)	(2)	(3)	(4)
Post-announcement=1	-0.490***	-1.193***	-1.254^{***}	-0.342***
	(0.075)	(0.182)	(0.042)	(0.056)
Post-announcement= $1 \times \text{dienstgroup}=1$	0.017	0.082	-0.016	0.014
	(0.101)	(0.245)	(0.070)	(0.076)
Post-announcement= $1 \times \text{dienstgroup}=2$	0.016	0.073	-0.099	-0.008
	(0.120)	(0.280)	(0.070)	(0.092)
Post-announcement= $1 \times \text{dienstgroup}=4$	0.180^{*}	0.304	0.051	0.016
	(0.106)	(0.257)	(0.068)	(0.076)
Post-feedback=1	-0.155*	-0.938***	-0.008	-0.130***
	(0.090)	(0.193)	(0.029)	(0.043)
Post-feedback= $1 \times \text{dienstgroup}=1$	-0.082	0.041	0.056	-0.006
	(0.117)	(0.273)	(0.042)	(0.064)
Post-feedback= $1 \times \text{dienstgroup}=2$	0.006	0.227	-0.026	-0.066
	(0.129)	(0.247)	(0.046)	(0.062)
Post-feedback= $1 \times \text{dienstgroup}=4$	0.129	0.242	0.016	0.012
	(0.110)	(0.248)	(0.045)	(0.058)
Post-experiment=1	0.637***	0.412***	0.049^{*}	-0.026
	(0.054)	(0.128)	(0.025)	(0.033)
Post-experiment= $1 \times \text{dienstgroup}=1$	-0.055	-0.068	-0.008	-0.042
	(0.078)	(0.178)	(0.035)	(0.042)
Post-experiment= $1 \times \text{dienstgroup}=2$	-0.073	-0.158	-0.022	-0.059
	(0.084)	(0.190)	(0.039)	(0.044)
Post-experiment= $1 \times \text{dienstgroup}=4$	-0.084	-0.178	0.019	-0.043
	(0.070)	(0.179)	(0.038)	(0.043)
Constant	22.562***	11.359***	2.318***	1.636***
	(0.080)	(0.190)	(0.058)	(0.053)
\mathbb{R}^2	.531	.449	.198	.396
# trip-level observations	484918	349879	349879	349879
Controls	Yes	Yes	Yes	Yes
Weather dummies	Yes	Yes	Yes	Yes
Driver fixed effects	Yes	Yes	Yes	Yes
Day fixed effects	No	No	No	No
Bus type \times day fixed effects	No	No	No	No

Table A21: Targeted Peer-Comparison Feedback Effects on Driving Performance [Groups: Years of Service]

Notes: Identification of the treatment effects on driving performance. The time period under consideration is from 01/01/2015 until 31/01/2017. The post-announcement dummy variable is one in the period from 09/11/2015 onwards (feedback announcement), zero otherwise. Drivers are considered to be in the post-feedback period when they have received at least one report in the past. For most drivers, this was at 15/12/2015 and after. The post-experimental period starts at 15/11/2016 when it was communicated to the treated drivers that they will no longer receive peer-comparison messages. The dependent variable fuel economy is measured in liters/100km and acceleration as the number of events per 10 kilometers. Standard errors are clustered by driver. Controls include: travel distance, route dummies, number of passengers and bus stops, and dummies for bus type, morning and evening rush hours, fill-in rides and having been coached. Weather dummies: daily temperature, wind and rainfall. A no-report indicator is included to capture drivers operating after 15/12/2015 (first feedback round) but who have not yet received their first report. Default tenuregroup=3 (16-29 years); tenuregroup=1: < 8 years; tenuregroup=2: 8 - 15 years; tenuregroup=4: ≥ 30 years.

***(**,*): statistically different from zero at the 1%-level (5%-level, 10%-level). Standard errors in parentheses.

Table A22: Targeted Peer-Comparison Feedback Effects on Driving Performance [Grou	ips:
Gender]	

Dependent variable:	Fuel economy	Acceleration	Braking	Cornering
	(1)	(2)	(3)	(4)
Post-announcement=1	-0.429***	-1.100***	-1.269^{***}	-0.341***
	(0.044)	(0.104)	(0.028)	(0.032)
Post-announcement= $1 \times \text{gendergroup}=1$	-0.063	0.155	0.032	0.038
	(0.090)	(0.266)	(0.098)	(0.086)
Post-feedback=1	-0.123**	-0.750***	0.008	-0.134***
	(0.049)	(0.103)	(0.018)	(0.028)
Post-feedback= $1 \times \text{gendergroup}=1$	-0.199	-0.625	-0.044	-0.058
	(0.154)	(0.397)	(0.045)	(0.068)
Post-experiment=1	0.612***	0.369***	0.055***	-0.059***
	(0.028)	(0.066)	(0.013)	(0.015)
Post-experiment= $1 \times \text{gendergroup}=1$	-0.298**	-0.580**	-0.094*	-0.032
	(0.119)	(0.229)	(0.049)	(0.044)
Constant	22.554***	11.368***	2.317***	1.637***
	(0.079)	(0.193)	(0.059)	(0.054)
\mathbb{R}^2	.529	.448	.197	.393
Number of trip-level observations	484918	349879	349879	349879
Controls	Yes	Yes	Yes	Yes
Weather dummies	Yes	Yes	Yes	Yes
Driver fixed effects	Yes	Yes	Yes	Yes
Day fixed effects	No	No	No	No
Bus type \times day fixed effects	No	No	No	No

Notes: Identification of the treatment effects on driving performance. The time period under consideration is from 01/01/2015 until 31/01/2017. The post-announcement dummy variable is one in the period from 09/11/2015 onwards (feedback announcement), zero otherwise. Drivers are considered to be in the post-feedback period when they have received at least one report in the past. For most drivers, this was at 15/12/2015 and after. The post-experimental period starts at 15/11/2016 when it was communicated to the treated drivers that they will no longer receive peer-comparison messages. The dependent variable fuel economy is measured in liters/100km and acceleration as the number of events per 10 kilometers. Standard errors are clustered by driver. Controls include: travel distance, route dummies, number of passengers and bus stops, and dummies for bus type, morning and evening rush hours, fill-in rides and having been coached. Weather dummies: daily temperature, wind and rainfall. A no-report indicator is included to capture drivers operating after 15/12/2015 (first feedback round) but who have not yet received their first report. Default gendergroup=0 (males).

***(**,*): statistically different from zero at the 1%-level (5%-level, 10%-level). Standard errors in parentheses.

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